

## Review Problems for Final Math 461 Exam

(1). (*Determinants, minors, etc.*) Let

$$A = (\mathbf{v}_1 | \mathbf{v}_2 | \mathbf{v}_3) = \begin{pmatrix} 1 & 0 & 2 \\ -1 & 1 & 2 \\ 1 & 2 & -1 \end{pmatrix}$$

(a) Find the volume for the solid geometric body (tetrahedron)  $\{x_1\mathbf{v}_1 + x_2\mathbf{v}_2 + x_3\mathbf{v}_3 : 0 \leq x_1, x_2, x_3 \leq 1\}$  with vertices  $\mathbf{0}, \mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3$ .

(b) Find  $A^{-1}$  via Cramer's rule.

(c) Find  $A^{-1}(1, 2, 3)^T$  via row-reduction.

(2). (*MATLAB, Invertibility*) Suppose  $B = (\mathbf{w}_1 | \mathbf{w}_2 | \cdots | \mathbf{w}_6)$  is a  $6 \times 6$  matrix.

(a) Give 4 different MATLAB commands involving  $B$ , each producing an output from which you can read off *by inspection* whether the columns of  $B$  are linearly independent. Explain what each output is and why it gives enough information to distinguish linear independence.

(b) Now assume  $B$  is invertible. Give a MATLAB command (or short sequence of commands) to produce an orthonormal basis of  $W = \text{span}(\mathbf{w}_1, \mathbf{w}_2, \mathbf{w}_3)$  and an orthonormal basis of  $W^\perp$ .

(c) Explain in symbols what the elements of the  $6 \times 6$  matrix

$$\gg \text{diag}(\text{diag}(B'*B).^(-1/2)) * B'*B * \text{diag}(\text{diag}(B'*B).^(-1/2))$$

are. Can you interpret these elements?

(3). (*ODE's, complex eigenvalues*) Solve the differential equation for all  $t > 0$ :

$$\dot{\mathbf{x}}(t) = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & -1 \\ 0 & 1 & 1 \end{pmatrix} \mathbf{x}(t) \quad , \quad \mathbf{x}(0) = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix}$$

*Hint: solve for  $(x_2(t), x_3(t))$  first, using first principles or formulas from the book. Then (harder part) solve the equation as an inhomogeneous equation for  $x_1$ , plugging in the functions already found for  $x_2(t), x_3(t)$ .*

(4). (*Null & Col Spaces*) By hand, find bases for  $Nul(A)$ ,  $col(A)$ , and  $(row(A))^\perp$ , where

$$A = \begin{pmatrix} 1 & 0 & 1 & 0 \\ 1 & 2 & -1 & 1 \\ 1 & 2 & -1 & -1 \\ 1 & 0 & 1 & 0 \end{pmatrix}$$

(5). (*Symmetric matrices*) Suppose that

$$B = \begin{pmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$

Find the values of

$$\max_{\mathbf{x}: \|\mathbf{x}\|=1} \mathbf{x}^T B \mathbf{x} \quad , \quad \min_{\mathbf{y}: \|\mathbf{y}\|=1} \mathbf{y}^T B \mathbf{y}$$

and give the vectors  $\mathbf{x}$ ,  $\mathbf{y}$  for which the *max* and *min* are achieved.

(6). (*Least-squares*) A vector of observations  $\mathbf{y} = (y_1, \dots, y_{50})^T$  is to be expressed as accurately as possible in mean-squared error sense according to the model  $y_i \approx a + bx_i + cx_i^2$ . Suppose that

$$\begin{aligned} \sum_{i=1}^{50} x_i &= 10, \quad \sum_{i=1}^{50} x_i^2 = 20, \quad \sum_{i=1}^{50} x_i^3 = 40, \quad \sum_{i=1}^{50} x_i^4 = 90 \\ \sum_{i=1}^{50} y_i &= 20, \quad \sum_{i=1}^{50} x_i y_i = 40, \quad \sum_{i=1}^{50} x_i^2 y_i = 60 \end{aligned}$$

Find the least-squares values of  $a$ ,  $b$ ,  $c$ .

(7). The  $3 \times 3$  matrix  $A$  is given in the form  $A = P D P^{-1}$ , where

$$P = \begin{pmatrix} 1 & 0 & 0 \\ -2 & 1 & 3 \\ 1 & 2 & 1 \end{pmatrix} \quad , \quad D = \begin{pmatrix} -2 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 3 \end{pmatrix}$$

Find the approximate values of  $\|A^k \mathbf{w}\|^{1/k}$  and  $A^k \mathbf{w} / \|A^k \mathbf{w}\|$  when  $k$  is large, where  $\mathbf{w} = (1, 1, 3)^T$ .

(8). (*Change of Basis*) Suppose that

$$C = (\mathbf{c}_1 | \mathbf{c}_2 | \mathbf{c}_3) = \begin{pmatrix} 1 & 2 & 0 \\ 3 & -1 & 4 \\ -1 & 0 & 1 \end{pmatrix}, \quad B = (\mathbf{b}_1 | \mathbf{b}_2 | \mathbf{b}_3) = \begin{pmatrix} 1 & 0 & 1 \\ 1 & 1 & 2 \\ 0 & 1 & 3 \end{pmatrix}$$

(a) Find the  $3 \times 3$  matrix  $A$  whose  $j$ 'th column is the coordinate vector of  $\mathbf{c}_j$  with respect to the basis  $\mathcal{B} = \{\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3\}$ .

(b) What is the relationship between the eigenvectors and eigenvalues of the matrices  $A$  (defined in part (a)) and  $C$  ?

(9). (*Orthogonal polynomials*) Let  $\mathcal{P}_2$  denote the vector space of polynomials  $a_0 + a_1t + a_2t^2$  of degree 2 or less, and define an inner product on such polynomials by  $\langle p(t), q(t) \rangle = p(-1)q(-1) + p(0)q(0) + p(1)q(1)$ .

(a) Find an orthonormal basis for  $\mathcal{P}_2$  with respect to this inner product.

(b) Explain why this inner-product *cannot* also define an inner product on the vector space  $\mathcal{C}[-1, 1]$  of continuous functions on the interval  $[-1, 1]$ .

(10). (*Transformations*) For each of the following transformations from  $\mathbf{R}^3$  to  $\mathbf{R}^3$ , explain why the transformation is linear, give the standard matrix representation, the null-space and range space, and the eigenvalues:

(a)  $S$  which multiplies the  $z$  coordinate by  $-3$  and rotates points in the  $(x, y)$  plane through 90 degrees (counterclockwise);

(b)  $T$  which maps  $\mathbf{x}$  to  $2((1, 0, -1)^T \mathbf{x}) (1, 0, -1)^T + 3((1, 1, 1)^T \mathbf{x}) (1, 1, 1)^T$ .