

Math 241 Section 12.4: Curves and Associated Definitions

Dr. Justin O. Wyss-Gallifent

1. A space curve (a curve) is the range of a VVF. Really it's just the curve we draw. A curve can be discussed without explicitly giving an $\mathbf{r}(t)$. A choice of $\mathbf{r}(t)$ is defined as a parametrization of the curve and one curve can have many parametrizations.

Example: A line.

Example: A circle.

2. Associated Definitions

(a) Closed:

- A *closed parametrization* is a parametrization with the property that $\mathbf{r}(a) = \mathbf{r}(b)$ (it starts where it ends) but otherwise does not cross itself infinitely many times.

Example: $\mathbf{r}(t) = \cos t \mathbf{i} + \sin t \mathbf{j}$ for $0 \leq t \leq 2\pi$.

Example: If t goes any further like twice around then the curve crosses itself infinitely many times and that's a no-no.

- A curve is *closed* if it has a closed parametrizations.

Example: The circle again. There are lots of parametrizations of the circle but since there is one that's closed then the curve is closed.

(b) Smooth:

- A *smooth parametrization* has $\mathbf{r}'(t) \neq \mathbf{0}$ except it is permitted to be $\mathbf{0}$ at the endpoints, if it has endpoints. A good analogy is an ideal commute where your velocity is (probably) $\mathbf{0}$ at the start and end but you never need to stop on the way.

- A curve is *smooth* if it has a smooth parametrization.

(c) Piecewise Smooth:

- A *piecewise smooth* parametrization is a parametrization in which you can break the t -range into pieces on which the parametrization is smooth. Your commute is probably more like this.

- A curve is *piecewise smooth* if it has a piecewise smooth parametrization.

Example: $\mathbf{r}(t) = (2t + 1) \mathbf{i} + (3 - t) \mathbf{j} + t \mathbf{k}$ for all t . Here $\mathbf{r}'(t) = 2 \mathbf{i} - 1 \mathbf{j} + 1 \mathbf{k}$ which is never $\mathbf{0}$ hence smooth.

Example: $\mathbf{r}(t) = t^2 \mathbf{i} + t^3 \mathbf{j} + 2 \mathbf{k}$ on $[0, 5]$. Here $\mathbf{r}'(t) = 2t \mathbf{i} + 3t^2 \mathbf{j} + 0 \mathbf{k}$ which is $\mathbf{0}$ at $t = 0$ but that's an endpoint so it's okay.

Example: $\mathbf{r}(t)$ same as above but on $[-5, 5]$. Here $t = 0$ is no longer an endpoint so it's not smooth. It is, however, piecewise smooth.

Example: $\mathbf{r}(t) = t^{1/3} \mathbf{i}$ on $[-1, 1]$. Here $\mathbf{r}'(t) = \frac{1}{3t^{2/3}} \mathbf{i}$ which is undefined at $t = 0$ hence neither smooth nor piecewise smooth.

(d) Length: If C is piecewise smooth on $[a, b]$ then:

$$\text{Length of } C = \int_a^b \|\mathbf{r}'(t)\| dt$$

Example: An easy one.

Note: Examples like 22,25 in the text are good because they require a sneaky factorization inside the square root before integration.