

Averaging principle for quasi-linear parabolic PDE's and related diffusion processes

M. Freidlin*, L. Korolov†

Abstract

Quasi-linear perturbations of a two-dimensional flow with a first integral and the corresponding parabolic PDE's with a small parameter at the second order derivatives are considered in this paper.

2000 Mathematics Subject Classification Numbers: 35K55

Keywords: averaging, quasi-linear parabolic equations, perturbations of dynamical systems.

1 Introduction

Let v be a C^2 -smooth incompressible vector field on \mathbb{R}^2 with the stream function H . Let a domain $D \subset \mathbb{R}^2$ be topologically equivalent to an annulus bounded by the curves γ_1 and γ_2 , such that $H(x) = h_1$ for $x \in \gamma_1$, and $H(x) = h_2$ for $x \in \gamma_2$ with $h_1 < h_2$. We also assume at first that H does not have critical points in \overline{D} .

Let g be a C^2 function defined in a neighborhood of $[h_1, h_2]$ and $c_1 = g(h_1)$, $c_2 = g(h_2)$. Let $a_{ij} = a_{ji} \in C^2(\mathbb{R}^3)$, $1 \leq i, j \leq 2$, and $b_i \in C^2(\mathbb{R}^3)$, $1 \leq i \leq 2$. We assume that there is a positive constant k such that $k|\xi|^2 \leq \sum_{i,j=1}^2 a_{ij}(x, u)\xi_i\xi_j$, $x \in D, u \in \mathbb{R}, \xi \in \mathbb{R}^2$.

In this paper we study the asymptotic behavior, as $\varepsilon \downarrow 0$, of solutions to the quasi-linear parabolic equation

$$\frac{\partial u^\varepsilon(t, x)}{\partial t} = \frac{1}{2} \sum_{i,j=1}^2 a_{ij}(x, u^\varepsilon) \frac{\partial^2 u^\varepsilon(t, x)}{\partial x_i \partial x_j} + \left(\frac{1}{\varepsilon} v(x) + b(x, u^\varepsilon) \right) \cdot \nabla_x u^\varepsilon(t, x), \quad x \in D, \quad t > 0, \quad (1)$$

$$u^\varepsilon(0, x) = g(H(x)), \quad x \in D; \quad u^\varepsilon(t, x) = c_1, \quad t \geq 0, \quad x \in \gamma_1, \quad u^\varepsilon(t, x) = c_2, \quad t \geq 0, \quad x \in \gamma_2 \quad (2)$$

and the diffusion processes related to (1)-(2). Under the above assumptions, the solution u^ε exists and is unique in the class of functions that are continuous on $[0, \infty) \times \overline{D}$, and

*Dept of Mathematics, University of Maryland, College Park, MD 20742, mif@math.umd.edu

†Dept of Mathematics, University of Maryland, College Park, MD 20742, korolov@math.umd.edu

have partial derivative in t and partial derivatives up to the second order in x which are bounded and continuous in $(0, \infty) \times D$ (see Theorem 5, Chapter 6.2 of [5]). Later, we also briefly discuss the case of general boundary and initial conditions.

We will show that the u^ε converges to the solution of the averaged quasi-linear equation. Namely, let

$$T(h) = \int_{\gamma(h)} \frac{1}{|\nabla H|} dl, \quad (3)$$

$$\bar{a}(h, u) = \frac{1}{T(h)} \int_{\gamma(h)} \frac{\langle a(x, u) \nabla H, \nabla H \rangle}{|\nabla H|} dl, \quad \text{and} \quad (4)$$

$$\bar{v}(h, u) = \frac{1}{2T(h)} \int_{\gamma(h)} \frac{a(x, u) \cdot H'' + 2\langle b(x, u), \nabla H \rangle}{|\nabla H|} dl, \quad (5)$$

where $a \cdot H''(x) = \sum_{1 \leq i, j \leq 2} a_{ij}(x) \partial^2 H(x) / \partial x_i \partial x_j$, $\gamma(h) = \{x \in \bar{D} : H(x) = h\}$, and u is a real parameter. Let \bar{u} solve

$$\frac{\partial \bar{u}(t, h)}{\partial t} = \frac{1}{2} \bar{a}(h, \bar{u}) \bar{u}''_{hh}(t, h) + \bar{v}(h, \bar{u}) \bar{u}'_h(t, h), \quad h \in [h_1, h_2], \quad t > 0, \quad (6)$$

$$\bar{u}(0, h) = g(h), \quad h \in [h_1, h_2]; \quad \bar{u}(t, h_1) = c_1, \quad t \geq 0, \quad \bar{u}(t, h_2) = c_2, \quad t \geq 0.$$

The solution exists and is unique in the same class of functions as above with D replaced by (h_1, h_2) . The main result of this paper is the following.

Theorem 1.1. *For each $x \in \bar{D}$ and $t > 0$ we have*

$$\lim_{\varepsilon \downarrow 0} u^\varepsilon(t, x) = \bar{u}(t, H(x)). \quad (7)$$

The convergence is uniform on $[0, t_0] \times \bar{D}$ for each $t_0 > 0$.

Before we proceed with the proof of the theorem, let us briefly discuss the situation in the linear case ($b(x, u) = b(x)$ and $a(x, u) = a(x)$), where the result is well-known. Namely, consider the process $X_t^{x, \varepsilon}$ that starts at x and solves

$$dX_t^{x, \varepsilon} = \frac{1}{\varepsilon} v(X_t^{x, \varepsilon}) dt + b(X_t^{x, \varepsilon}) dt + \sigma(X_t^{x, \varepsilon}) dW_t, \quad t \leq \tau^\varepsilon, \quad (8)$$

$$\tau^\varepsilon = \min\{t : X_t^{x, \varepsilon} \in \partial D\}, \quad X_t^{x, \varepsilon} = X_{\tau^\varepsilon}^{x, \varepsilon}, \quad \tau^\varepsilon \leq t.$$

Here W_t is a Wiener process in \mathbb{R}^2 , and $\sigma(x) = a^{1/2}(x)$. The motion in (8) consists of the fast (due to the presence of $1/\varepsilon$ factor in front of v) advection along the flow lines of v perturbed by the slower advection and diffusion. The limiting behavior (as $\varepsilon \downarrow 0$) of the slow component of $X_t^{x, \varepsilon}$ can be described in terms of the diffusion process on the graph corresponding to the structure of the level sets of H (the general result can be found in [3], Chapter 8). Here, we restrict ourselves to the case when $H(x)$ has no critical points

in \overline{D} , and so the corresponding graph is just the segment $[h_1, h_2]$. The general case is briefly considered in Section 4.

We introduce the process Y_t^h on $[h_1, h_2]$ that will serve as the limit of $H(X_t^{x,\varepsilon})$. Let $\overline{a}(h)$ and $\overline{v}(h)$ be defined by (4) and (5), respectively, where the right hand sides now don't depend on u . Let $\overline{\sigma}(h) = \sqrt{\overline{a}(h)}$. Let Y_t^h be the process that starts at h and solves

$$dY_t^h = \overline{v}(Y_t^h)dt + \overline{\sigma}(Y_t^h)d\overline{W}_t, \quad t \leq \overline{\tau},$$

$$\overline{\tau} = \min\{t : Y_t^h \in \{h_1, h_2\}\}, \quad Y_{\overline{\tau}}^h = Y_{\overline{\tau}}^h, \quad \overline{\tau} \leq t,$$

where \overline{W}_t is a one-dimensional Wiener process. The following theorem can be found in [3], Chapter 8.

Theorem 1.2. *Let $x \in D$. Under the above assumptions, the measures on the space $C([0, \infty), [h_1, h_2])$ induced by the processes $H(X_t^{x,\varepsilon})$ converge weakly, as $\varepsilon \downarrow 0$, to the measure induced by the process $Y_t^{H(x)}$.*

Remark 1.3. *The coefficients b and σ , and consequently \overline{v} and $\overline{\sigma}$, may be allowed to depend on t . Moreover, the weak convergence claimed in Theorem 1.2 can be proved to be uniform in certain parameters. For example, for each $t_0, C > 0$, and continuous function F on $[h_1, h_2]$, the following limit*

$$\lim_{\varepsilon \downarrow 0} \mathbb{E} \left(F(H(X_t^{x,\varepsilon})) - F(Y_t^{H(x)}) \right) = 0$$

is uniform in $t \in [0, t_0]$, $x \in D$ and $b, \sigma \in \mathcal{S}_C$, where \mathcal{S}_C is the space of all functions of t and x that are bounded by C , in absolute value, together with the first order partial derivatives.

This theorem together with the representation of the solution of the PDE as the expectation of the functional of the process

$$u^\varepsilon(t, x) = \mathbb{E}g(H(X_t^{x,\varepsilon})), \tag{9}$$

easily imply Theorem 1.1 in the case when a does not depend on u . (Note that in (9) we used the fact that $c_1 = g(h_1)$ and $c_2 = g(h_2)$.)

The difficulty in the non-linear case is due to the fact that now the family of diffusion processes corresponding to the operator in the right hand side of (1) depends on the unknown function u^ε because of the dependence of the coefficients a and b on u^ε . Namely, for $t > 0$ and $x \in \overline{D}$, we can define $X_s^{t,x,\varepsilon}$, $s \in [0, t]$, as the process which starts at x and solves

$$dX_s^{t,x,\varepsilon} = \frac{1}{\varepsilon}v(X_s^{t,x,\varepsilon})ds + b(X_s^{t,x,\varepsilon}, u^\varepsilon(t-s, X_s^{t,x,\varepsilon}))ds + \sigma(X_s^{t,x,\varepsilon}, u^\varepsilon(t-s, X_s^{t,x,\varepsilon}))dW_s, \quad s \leq \tau^\varepsilon \wedge t, \tag{10}$$

$$\tau^\varepsilon = \min\{s : X_s^{t,x,\varepsilon} \in \partial D\}, \quad X_s^{t,x,\varepsilon} = X_{\tau^\varepsilon}^{t,x,\varepsilon}, \quad \tau^\varepsilon \leq s \leq t, \tag{11}$$

where $\sigma = a^{1/2}$. As in the linear case, we have the following relation between u^ε and the process $X_s^{t,x,\varepsilon}$:

$$u^\varepsilon(t, x) = \text{Eg}(H(X_t^{t,x,\varepsilon})). \quad (12)$$

In fact, (10)-(12) can be viewed as a system of equations for the unknown function u^ε and the family of processes $X_s^{t,x,\varepsilon}$ that is equivalent to (1)-(2) (see [2], Chapter 5).

In the next section we use the relationship between the processes $X_s^{t,x,\varepsilon}$ and the solution u^ε in order to prove Theorem 1.1. A lemma that is used in the proof is, in turn, proved in Section 3. In Section 4 we discuss several generalizations. One concerns the systems with several degrees of freedom. The other concerns more general initial and boundary value functions. We also discuss the case when the domain D contains critical points of H .

2 Proof of the main theorem

First, let us prove the uniform convergence for $(t, x) \in [0, t_0] \times \overline{D}$ if t_0 is sufficiently small. The value of t_0 will be specified later. If the convergence does not hold, then there are $\varkappa > 0$ and sequences $\varepsilon^k \downarrow 0$, $s_0^k \in [0, t_0]$, $x^k \in D$ such that

$$|u^{\varepsilon^k}(s_0^k, x^k) - \bar{u}(s_0^k, H(x^k))| \geq \varkappa. \quad (13)$$

Due to the continuity of u^ε and \bar{u} , we can pick a smaller (if necessary) value of s_0^k such that (13) still holds and

$$\sup_{(s,x) \in [0, s_0^k] \times D} |u^{\varepsilon^k}(s, x) - \bar{u}(s, H(x))| \leq \varkappa, \quad (14)$$

and consequently the inequality in (13) becomes an equality. We will drop the superscript k from the notation, simply keeping in mind that an arbitrarily small ε can be taken.

For $t > 0$, $h \in [h_1, h_2]$, let $Y_s^{t,h}$, $s \in [0, t]$, be the process which starts at h and solves

$$dY_s^{t,h} = \bar{v}(Y_s^{t,h})ds + \bar{\sigma}(Y_s^{t,h}, \bar{u}(t-s, Y_s^{t,h}))d\overline{W}_s, \quad s \leq \bar{\tau} \wedge t,$$

$$\bar{\tau} = \min\{s : Y_s^{t,h} \in \{h_1, h_2\}\}, \quad Y_s^{t,h} = Y_{\bar{\tau}}^{t,h}, \quad \bar{\tau} \leq s \leq t,$$

where $\bar{\sigma} = \sqrt{\bar{a}}$. For $t > 0$ and $x \in \overline{D}$, we also introduce $Z_s^{t,x,\varepsilon}$, $s \in [0, t]$, as the process which starts at x and solves

$$dZ_s^{t,x,\varepsilon} = \frac{1}{\varepsilon}v(Z_s^{t,x,\varepsilon})ds + b(Z_s^{t,x,\varepsilon}, \bar{u}(t-s, H(Z_s^{t,x,\varepsilon})))ds +$$

$$\sigma(Z_s^{t,x,\varepsilon}, \bar{u}(t-s, H(Z_s^{t,x,\varepsilon})))dW_s, \quad s \leq \tilde{\tau}^\varepsilon \wedge t,$$

$$\tilde{\tau}^\varepsilon = \min\{s : Z_s^{t,x,\varepsilon} \in \partial D\}, \quad Z_s^{t,x,\varepsilon} = Z_{\tilde{\tau}^\varepsilon}^{t,x,\varepsilon}, \quad \tilde{\tau}^\varepsilon \leq s \leq t.$$

Then

$$\begin{aligned} |u^\varepsilon(s_0, x) - \bar{u}(s_0, H(x))| &= |\text{Eg}(H(X_{s_0}^{s_0,x,\varepsilon})) - \text{Eg}(Y_{s_0}^{s_0,H(x)})| \leq \\ &|\text{Eg}(H(X_{s_0}^{s_0,x,\varepsilon})) - \text{Eg}(H(Z_{s_0}^{s_0,x,\varepsilon}))| + |\text{Eg}(H(Z_{s_0}^{s_0,x,\varepsilon})) - \text{Eg}(Y_{s_0}^{s_0,H(x)})|. \end{aligned}$$

By taking $\tilde{b}(s, x) = b(x, \bar{u}(s_0 - s, H(x)))$, $\tilde{\sigma}(s, x) = \sigma(x, \bar{u}(s_0 - s, H(x)))$ and $F = g$, we see from Remark 1.3 that the second term on the right hand side here can be made smaller than $\varkappa/2$ for all $(s_0, x) \in [0, t_0] \times \bar{D}$ and all sufficiently small ε . In order to deal with the first term we need the following lemma that will be proved in the next section.

Lemma 2.1. *Consider two processes $Z_t^{1,\varepsilon}$ and $Z_t^{2,\varepsilon}$ which solve*

$$dZ_t^{i,\varepsilon} = \frac{1}{\varepsilon}v(Z_t^{i,\varepsilon})dt + b_i(t, Z_t^{i,\varepsilon})dt + \sigma_i(t, Z_t^{i,\varepsilon})dW_t, \quad t \leq \tau^{i,\varepsilon}, \quad Z_0^{i,\varepsilon} = x \in D,$$

$$\tau^{i,\varepsilon} = \min\{t : Z_t^{i,\varepsilon} \in \partial D\}, \quad Z_t^{i,\varepsilon} = Z_{\tau^{i,\varepsilon}}^{i,\varepsilon}, \quad \tau^{i,\varepsilon} \leq t.$$

We assume that $|b_1|, |b_2|, |\sigma_1|, |\sigma_2| \leq M$ for some positive constant M , σ_1 and σ_2 are uniformly elliptic with a constant $m > 0$, b_1 and σ_1 are Lipschitz continuous on $[0, \infty) \times \bar{D}$ with the constant M , b_2 and σ_2 are Lipschitz continuous and

$$\sup_{(t,x) \in (0,\infty) \times D} |b_1(t, x) - b_2(t, x)| \leq \eta. \quad (15)$$

$$\sup_{(t,x) \in (0,\infty) \times D} |\sigma_1(t, x) - \sigma_2(t, x)| \leq \eta. \quad (16)$$

Let $f \in C^2((h_1, h_2), \mathbb{R}) \cap C([h_1, h_2], \mathbb{R})$ be a function whose C^2 -norm is bounded by M . For each choice of m, M and $S > 0$ there exists a positive constant K such that

$$|\mathbb{E}f(H(Z_t^{1,\varepsilon})) - \mathbb{E}f(H(Z_t^{2,\varepsilon}))| \leq K\eta\sqrt{t} \quad (17)$$

whenever $x \in D$, $\eta > 0$, $\varepsilon \leq 1$, $t \leq S$, and b_2, σ_2 satisfy (15)-(16).

By (14), the drift and diffusion coefficients of the process $X_s^{s_0, x, \varepsilon}$ differ from the respective coefficients of the process $Z_s^{s_0, x, \varepsilon}$ by no more than $\eta = L\varkappa$, where L is the Lipschitz constant of the functions $b(x, u)$ and $\sigma(x, u)$. We can thus apply Lemma 2.1 (with $f = g$ and M determined by b, σ, \bar{u} and g) to the processes $Z_s^{1,\varepsilon} = Z_s^{s_0, x, \varepsilon}$ and $Z_s^{2,\varepsilon} = X_s^{s_0, x, \varepsilon}$ to obtain that

$$|\mathbb{E}g(H(X_{s_0}^{s_0, x, \varepsilon})) - \mathbb{E}g(H(Z_{s_0}^{s_0, x, \varepsilon}))| \leq KL\varkappa\sqrt{s_0}.$$

If we take t_0 such that $KL\sqrt{t_0}/2 < 1$, then the right hand side is bounded from above by $\varkappa/2$, which leads to a contradiction with (13), thus proving uniform convergence for $(t, x) \in [0, t_0] \times \bar{D}$.

Now let us show the uniform convergence for $(t, x) \in [t_0, T_0] \times \bar{D}$, where $T_0 > t_0$ is arbitrary. Again, if the convergence does not hold, then there are $\varkappa > 0$ and sequences $\varepsilon^k \downarrow 0$, $s_0^k \in [t_0, T_0]$, $x^k \in D$ such that (13) holds. Let us choose positive constants α, β and $r < t_0$ such that

$$\alpha \exp(\beta T_0) < \varkappa, \quad (18)$$

$$\beta r < 1, \quad (19)$$

$$\beta\sqrt{r} \geq \tilde{K}, \quad (20)$$

where the value of \tilde{K} will be specified later. Due to (18) and the continuity of u^ε and \bar{u} , by choosing if necessary a smaller value of s_0^k we can assume, without loss of generality, that instead of (13) we have for some x

$$|u^{\varepsilon^k}(s_0^k, x) - \bar{u}(s_0^k, H(x))| = \alpha \exp(\beta s_0^k), \quad (21)$$

while

$$\sup_{x \in D} |u^{\varepsilon^k}(s, x) - \bar{u}(s, H(x))| \leq \alpha \exp(\beta s) \quad (22)$$

for each $s \leq s_0^k$. Note that $s_0^k > t_0$ for all sufficiently small ε^k , since otherwise (21) would contradict the uniform convergence on $[0, t_0] \times \bar{D}$ established above. Let us drop the superscript k again. By (21) and (22), we have

$$\begin{aligned} \alpha \exp(\beta s_0) &= |u^\varepsilon(s_0, x) - \bar{u}(s_0, H(x))| = \\ &|\mathbb{E}(u^\varepsilon(s_0 - r, X_r^{s_0, x, \varepsilon}) - \bar{u}(s_0 - r, Y_r^{s_0, H(x)}))| \leq \\ &|\mathbb{E}(u^\varepsilon(s_0 - r, X_r^{s_0, x, \varepsilon}) - \bar{u}(s_0 - r, H(X_r^{s_0, x, \varepsilon})))| + \\ &|\mathbb{E}(\bar{u}(s_0 - r, H(X_r^{s_0, x, \varepsilon})) - \bar{u}(s_0 - r, Y_r^{s_0, H(x)}))| \leq \\ &\alpha \exp(\beta(s_0 - r)) + |\mathbb{E}(\bar{u}(s_0 - r, H(X_r^{s_0, x, \varepsilon})) - \bar{u}(s_0 - r, Y_r^{s_0, H(x)}))|. \end{aligned}$$

Therefore, due to (19),

$$|\mathbb{E}(\bar{u}(s_0 - r, H(X_r^{s_0, x, \varepsilon})) - \bar{u}(s_0 - r, Y_r^{s_0, H(x)}))| \geq \alpha \beta r \exp(\beta s_0)/2.$$

As before, we have

$$\begin{aligned} &|\mathbb{E}(\bar{u}(s_0 - r, H(X_r^{s_0, x, \varepsilon})) - \bar{u}(s_0 - r, Y_r^{s_0, H(x)}))| \leq \\ &|\mathbb{E}(\bar{u}(s_0 - r, H(X_r^{s_0, x, \varepsilon})) - \bar{u}(s_0 - r, H(Z_r^{s_0, x, \varepsilon})))| + \\ &|\mathbb{E}(\bar{u}(s_0 - r, H(Z_r^{s_0, x, \varepsilon})) - \bar{u}(s_0 - r, Y_r^{s_0, H(x)}))|. \end{aligned}$$

The second term on the right hand side is smaller than $\alpha \beta r \exp(\beta s_0)/4$ for all sufficiently small ε by Remark 1.3. The first term is estimated from above, using Lemma 2.1, by $KL\alpha \exp(\beta s_0)\sqrt{r}$. We obtain a contradiction with (20) if we take $\tilde{K} = 4KL$, thus proving the theorem.

3 Lemma on closeness of the processes

In this section we prove Lemma 2.1. Let us consider the processes $(A_t^{i, \varepsilon}, T_t^{i, \varepsilon})$, $i = 1, 2$, which are defined by

$$dA_t^{i, \varepsilon} = T(H(A_t^{i, \varepsilon})) \left(\frac{1}{\varepsilon} v(A_t^{i, \varepsilon}) + b_i(T_t^{i, \varepsilon}, A_t^{i, \varepsilon}) \right) dt + T^{\frac{1}{2}}(H(A_t^{i, \varepsilon})) \sigma_i(T_t^{i, \varepsilon}, A_t^{i, \varepsilon}) dW_t, \quad t \leq \beta^{i, \varepsilon},$$

$$\begin{aligned}
A_0^{i,\varepsilon} &= x \in D, \\
\beta^{i,\varepsilon} &= \min\{t : A_t^{i,\varepsilon} \in \partial D\}, \quad A_t^{i,\varepsilon} = A_{\beta^{i,\varepsilon}}^{i,\varepsilon}, \quad \beta^{i,\varepsilon} \leq t. \\
dT_t^{i,\varepsilon} &= T(H(A_t^{i,\varepsilon}))dt, \quad T_0^{i,\varepsilon} = 0,
\end{aligned}$$

where the function T was defined in (3). Thus $A_t^{i,\varepsilon}$ can be obtained from $Z_t^{i,\varepsilon}$, $i = 1, 2$, via a random change of time. Let Γ be a smooth curve connecting γ_1 and γ_2 and transversal to the vector field v . For $h \in [h_1, h_2]$, let $p(h)$ be the point on Γ such that $H(p(h)) = h$. For $h \in [h_1, h_2]$, let $y_h(\varphi)$ solve

$$\frac{dy_h(\varphi)}{d\varphi} = T(H(y_h(\varphi)))v(y_h(\varphi)), \quad y_h(0) = p(h).$$

Thus $y_h(\varphi)$ represents deterministic periodic (with period one) motion along the level sets of H . Let us make the change of variables (action-angle coordinates after time change) $\Psi : \overline{D} \rightarrow \overline{U} := [h_1, h_2] \times S$, where S is a circle of length one. Namely,

$$\Psi(x) = (h(x), \varphi(x)) := (H(x), y_{H(x)}^{-1}(x)).$$

We denote the process $A_t^{i,\varepsilon}$ in the new variables by $B_t^{i,\varepsilon} = (H_t^{i,\varepsilon}, \varphi_t^{i,\varepsilon})$. Then

$$\begin{aligned}
dH_t^{i,\varepsilon} &= \tilde{b}_i(T_t^{i,\varepsilon}, B_t^{i,\varepsilon})dt + \tilde{\sigma}_i(T_t^{i,\varepsilon}, B_t^{i,\varepsilon})dW_t, \quad t \leq \beta^{i,\varepsilon}, \quad H_0^{i,\varepsilon} = H(x), \\
d\varphi_t^{i,\varepsilon} &= \frac{1}{\varepsilon}dt + \hat{b}_i(T_t^{i,\varepsilon}, B_t^{i,\varepsilon})dt + \hat{\sigma}_i(T_t^{i,\varepsilon}, B_t^{i,\varepsilon})dW_t, \quad t \leq \beta^{i,\varepsilon}, \quad \varphi_0^{i,\varepsilon} = \varphi(x), \\
\beta^{i,\varepsilon} &= \min\{t : H_t^{i,\varepsilon} \in \{h_1, h_2\}\}, \quad H_t^{i,\varepsilon} = H_{\beta^{i,\varepsilon}}^{i,\varepsilon}, \quad \varphi_t^{i,\varepsilon} = \varphi_{\beta^{i,\varepsilon}}^{i,\varepsilon}, \quad \beta^{i,\varepsilon} \leq t. \\
dT_t^{i,\varepsilon} &= T(H_t^{i,\varepsilon})dt, \quad T_0^{i,\varepsilon} = 0,
\end{aligned}$$

where the scalar functions $\tilde{b}_i, \hat{b}_i, i = 1, 2$, and the vector valued functions $\tilde{\sigma}_i, \hat{\sigma}_i, i = 1, 2$, have the following properties: $\tilde{b}_1, \hat{b}_1, \tilde{\sigma}_1$ and $\hat{\sigma}_1$ are bounded by M' and are Lipschitz continuous with the same constant M' ; $\tilde{b}_2, \hat{b}_2, \tilde{\sigma}_2$ and $\hat{\sigma}_2$ are Lipschitz continuous, $|\tilde{\sigma}_1|$ and $|\hat{\sigma}_2|$ are bounded from below by a positive constant, and there is a constant \overline{m} such that

$$\sup_{(t,y) \in [0,\infty) \times \overline{U}} \left(|\tilde{b}_1(t,y) - \tilde{b}_2(t,y)| + |\hat{b}_1(t,y) - \hat{b}_2(t,y)| \right) \leq \overline{m}\eta, \quad (23)$$

$$\sup_{(t,y) \in [0,\infty) \times \overline{U}} (|\tilde{\sigma}_1(t,y) - \tilde{\sigma}_2(t,y)| + |\hat{\sigma}_1(t,y) - \hat{\sigma}_2(t,y)|) \leq \overline{m}\eta. \quad (24)$$

These properties immediately follow from the corresponding properties for the vectors b_1 and b_2 and the matrices σ_1 and σ_2 if one takes into account that the change of time and the change of variables were smooth.

In what follows, C will stand for a generic constant that does not depend on η , but may vary from line to line. Let $\tau \leq \beta^{1,\varepsilon} \wedge \beta^{2,\varepsilon}$ be a stopping time for the process W_t . Using the Ito formula, (23) and (24), we obtain

$$\mathbb{E}|H_{t \wedge \tau}^{1,\varepsilon} - H_{t \wedge \tau}^{2,\varepsilon}|^2 = 2\mathbb{E} \int_0^{t \wedge \tau} (H_s^{1,\varepsilon} - H_s^{2,\varepsilon})(\tilde{b}_1(T_s^{1,\varepsilon}, B_s^{1,\varepsilon}) - \tilde{b}_2(T_s^{2,\varepsilon}, B_s^{2,\varepsilon}))ds +$$

$$\begin{aligned}
& \mathbb{E} \int_0^{t \wedge \tau} |\tilde{\sigma}_1(T_s^{1,\varepsilon}, B_s^{1,\varepsilon}) - \tilde{\sigma}_2(T_s^{2,\varepsilon}, B_s^{2,\varepsilon})|^2 ds \leq \\
& \mathbb{E} \int_0^{t \wedge \tau} |H_{s \wedge \tau}^{1,\varepsilon} - H_{s \wedge \tau}^{2,\varepsilon}|^2 ds + \mathbb{E} \int_0^{t \wedge \tau} |\tilde{b}_1(T_s^{1,\varepsilon}, B_s^{1,\varepsilon}) - \tilde{b}_2(T_s^{2,\varepsilon}, B_s^{2,\varepsilon})|^2 ds + \\
& \mathbb{E} \int_0^{t \wedge \tau} |\tilde{\sigma}_1(T_s^{1,\varepsilon}, B_s^{1,\varepsilon}) - \tilde{\sigma}_2(T_s^{2,\varepsilon}, B_s^{2,\varepsilon})|^2 ds \leq \\
& \mathbb{E} \int_0^{t \wedge \tau} |H_{s \wedge \tau}^{1,\varepsilon} - H_{s \wedge \tau}^{2,\varepsilon}|^2 ds + \\
& \mathbb{E} \int_0^{t \wedge \tau} |(\tilde{b}_1(T_{s \wedge \tau}^{1,\varepsilon}, B_{s \wedge \tau}^{1,\varepsilon}) - \tilde{b}_1(T_{s \wedge \tau}^{2,\varepsilon}, B_{s \wedge \tau}^{2,\varepsilon})) + (\tilde{b}_1(T_{s \wedge \tau}^{2,\varepsilon}, B_{s \wedge \tau}^{2,\varepsilon}) - \tilde{b}_2(T_{s \wedge \tau}^{2,\varepsilon}, B_{s \wedge \tau}^{2,\varepsilon}))|^2 ds + \\
& \mathbb{E} \int_0^{t \wedge \tau} |(\tilde{\sigma}_1(T_{s \wedge \tau}^{1,\varepsilon}, B_{s \wedge \tau}^{1,\varepsilon}) - \tilde{\sigma}_1(T_{s \wedge \tau}^{2,\varepsilon}, B_{s \wedge \tau}^{2,\varepsilon})) + (\tilde{\sigma}_1(T_{s \wedge \tau}^{2,\varepsilon}, B_{s \wedge \tau}^{2,\varepsilon}) - \tilde{\sigma}_2(T_{s \wedge \tau}^{2,\varepsilon}, B_{s \wedge \tau}^{2,\varepsilon}))|^2 ds \leq \\
& C \left(t\eta^2 + \int_0^t \mathbb{E}(|T_{s \wedge \tau}^{1,\varepsilon} - T_{s \wedge \tau}^{2,\varepsilon}|^2 + |B_{s \wedge \tau}^{1,\varepsilon} - B_{s \wedge \tau}^{2,\varepsilon}|^2) ds \right).
\end{aligned}$$

In the same way we obtain

$$\mathbb{E}|\varphi_{t \wedge \tau}^{1,\varepsilon} - \varphi_{t \wedge \tau}^{2,\varepsilon}|^2 \leq C \left(t\eta^2 + \int_0^t \mathbb{E}(|T_{s \wedge \tau}^{1,\varepsilon} - T_{s \wedge \tau}^{2,\varepsilon}|^2 + |B_{s \wedge \tau}^{1,\varepsilon} - B_{s \wedge \tau}^{2,\varepsilon}|^2) ds \right)$$

and

$$\mathbb{E}|T_{t \wedge \tau}^{1,\varepsilon} - T_{t \wedge \tau}^{2,\varepsilon}|^2 \leq C \int_0^t \mathbb{E}|B_{s \wedge \tau}^{1,\varepsilon} - B_{s \wedge \tau}^{2,\varepsilon}|^2 ds.$$

Combining these three inequalities we see that

$$\begin{aligned}
& \mathbb{E} \left(|T_{t \wedge \tau}^{1,\varepsilon} - T_{t \wedge \tau}^{2,\varepsilon}|^2 + |B_{t \wedge \tau}^{1,\varepsilon} - B_{t \wedge \tau}^{2,\varepsilon}|^2 \right) \leq \\
& C \left(t\eta^2 + \int_0^t \mathbb{E}(|T_{s \wedge \tau}^{1,\varepsilon} - T_{s \wedge \tau}^{2,\varepsilon}|^2 + |B_{s \wedge \tau}^{1,\varepsilon} - B_{s \wedge \tau}^{2,\varepsilon}|^2) ds \right).
\end{aligned}$$

The Gronwall inequality then implies that

$$\mathbb{E} \left(|T_{t \wedge \tau}^{1,\varepsilon} - T_{t \wedge \tau}^{2,\varepsilon}|^2 + |B_{t \wedge \tau}^{1,\varepsilon} - B_{t \wedge \tau}^{2,\varepsilon}|^2 \right) \leq \eta^2 (\exp(Ct) - 1).$$

In particular, if $t \leq S$ and τ is bounded by t , then

$$\mathbb{E} \left(|T_\tau^{1,\varepsilon} - T_\tau^{2,\varepsilon}|^2 + |B_\tau^{1,\varepsilon} - B_\tau^{2,\varepsilon}|^2 \right) \leq C\eta^2 t, \quad (25)$$

where C now depends on S .

Let $\alpha^{i,\varepsilon}(t)$, $i = 1, 2$, be the stopping times defined by

$$\int_0^{\alpha^{i,\varepsilon}(t)} T(H_s^{i,\varepsilon}) ds = t. \quad (26)$$

Note that $f(H(Z_t^{i,\varepsilon}))$ has the same distribution as $f(H_{\alpha^{i,\varepsilon}(t)\wedge\beta^{i,\varepsilon}}^{i,\varepsilon})$. We need therefore to estimate the difference $\mathbb{E}f(H_{\alpha^{1,\varepsilon}(t)\wedge\beta^{1,\varepsilon}}^{1,\varepsilon}) - \mathbb{E}f(H_{\alpha^{2,\varepsilon}(t)\wedge\beta^{2,\varepsilon}}^{2,\varepsilon})$. Since we are interested in $t \leq S$ and T is bounded from below, the stopping times $\alpha^{i,\varepsilon}(t)$, $i = 1, 2$, are bounded by $t / \inf_{h \in [h_1, h_2]} T(h) \leq S / \inf_{h \in [h_1, h_2]} T(h) =: t_0$.

Let $\alpha^\varepsilon(t) = \alpha^{1,\varepsilon}(t) \wedge \alpha^{2,\varepsilon}(t)$ and $\mu^\varepsilon(t) = \alpha^{1,\varepsilon}(t) \wedge \beta^{1,\varepsilon} \wedge \alpha^{2,\varepsilon}(t) \wedge \beta^{2,\varepsilon}$. Since T is a Lipschitz continuous function and $\mu^\varepsilon(t)$ is bounded by a constant times t , by (25) we have for all s :

$$\mathbb{E}|T(H_{s\wedge\mu^\varepsilon}^{1,\varepsilon}) - T(H_{s\wedge\mu^\varepsilon}^{2,\varepsilon})| \leq C\eta\sqrt{t}.$$

Therefore,

$$\mathbb{E}\left|\int_0^{\mu^\varepsilon} T(H_s^{1,\varepsilon})ds - \int_0^{\mu^\varepsilon} T(H_s^{2,\varepsilon})ds\right| \leq \int_0^{t_0} \mathbb{E}|T(H_{s\wedge\mu^\varepsilon}^{1,\varepsilon}) - T(H_{s\wedge\mu^\varepsilon}^{2,\varepsilon})| \leq C\eta\sqrt{t}.$$

Since T is bounded from below, this together with (26) implies that

$$\mathbb{E}(\chi_{\{\mu^\varepsilon=\alpha^\varepsilon(t)\}}|\alpha^{1,\varepsilon}(t) - \alpha^{2,\varepsilon}(t)|) \leq C\eta\sqrt{t}. \quad (27)$$

If $\tau \leq \beta^{i,\varepsilon}$ is a stopping time, then by the Ito formula

$$\begin{aligned} |\mathbb{E}f(H_\tau^{i,\varepsilon}) - f(H_0^{i,\varepsilon})| &\leq \mathbb{E} \int_0^\tau |f'(H_s^{i,\varepsilon})| |\tilde{b}_i|(T_s^{i,\varepsilon}, B_s^{i,\varepsilon}) ds + \\ &\quad \frac{1}{2} \mathbb{E} \int_0^\tau |f''(H_s^{i,\varepsilon})| |\tilde{\sigma}_i|^2(T_s^{i,\varepsilon}, B_s^{i,\varepsilon}) ds \leq CE\tau, \end{aligned} \quad (28)$$

which holds for any initial point of the process $(T_t^{i,\varepsilon}, B_t^{i,\varepsilon})$.

Now,

$$\begin{aligned} &|\mathbb{E}f(H_{\alpha^{1,\varepsilon}(t)\wedge\beta^{1,\varepsilon}}^{1,\varepsilon}) - \mathbb{E}f(H_{\alpha^{2,\varepsilon}(t)\wedge\beta^{2,\varepsilon}}^{2,\varepsilon})| \leq \\ &|\mathbb{E}f(H_{\mu^\varepsilon}^{1,\varepsilon}) - \mathbb{E}f(H_{\mu^\varepsilon}^{2,\varepsilon})| + \mathbb{E}|\chi_{\{\mu^\varepsilon=\alpha^{1,\varepsilon}(t)\}} \left(f(H_{\mu^\varepsilon}^{2,\varepsilon}) - f(H_{\alpha^{2,\varepsilon}(t)\wedge\beta^{2,\varepsilon}}^{2,\varepsilon}) \right)| + \\ &\quad \mathbb{E}|\chi_{\{\mu^\varepsilon=\alpha^{2,\varepsilon}(t)\}} \left(f(H_{\alpha^{1,\varepsilon}(t)\wedge\beta^{1,\varepsilon}}^{1,\varepsilon}) - f(H_{\mu^\varepsilon}^{1,\varepsilon}) \right)| + \\ &\mathbb{E}|\chi_{\{\mu^\varepsilon=\beta^{1,\varepsilon}\}} \left(f(H_{\mu^\varepsilon}^{2,\varepsilon}) - f(H_{\alpha^{2,\varepsilon}(t)\wedge\beta^{2,\varepsilon}}^{2,\varepsilon}) \right)| + \mathbb{E}|\chi_{\{\mu^\varepsilon=\beta^{2,\varepsilon}\}} \left(f(H_{\alpha^{1,\varepsilon}(t)\wedge\beta^{1,\varepsilon}}^{1,\varepsilon}) - f(H_{\mu^\varepsilon}^{1,\varepsilon}) \right)|. \end{aligned} \quad (29)$$

The first term on the right hand side is estimated by $C\eta\sqrt{t}$ due to (25) since the derivative of f is bounded. The second and third terms are estimated by $C\eta\sqrt{t}$ using the Markov property, (27) and (28).

The last two terms are estimated using the proximity of $H_{\mu^\varepsilon}^{1,\varepsilon}$ and $H_{\mu^\varepsilon}^{2,\varepsilon}$. Indeed, as shown above, $\mathbb{E}|H_{\mu^\varepsilon}^{1,\varepsilon} - H_{\mu^\varepsilon}^{2,\varepsilon}| \leq C\eta\sqrt{t}$. Note that $H_{\mu^\varepsilon}^{1,\varepsilon}$ takes values h_1 or h_2 when $\mu^\varepsilon = \beta^{1,\varepsilon}$, and therefore

$$\mathbb{E}(\chi_{\{\mu^\varepsilon=\beta^{1,\varepsilon}\}} \min(H_{\mu^\varepsilon}^{2,\varepsilon} - h_1, h_2 - H_{\mu^\varepsilon}^{2,\varepsilon})) \leq C\eta\sqrt{t}.$$

Also note that there is a constant $C > 0$ with the property that if then initial data for the process $(H_t^{2,\varepsilon}, \varphi_t^{2,\varepsilon}, T_t^{2,\varepsilon})$ is such that $\min(H_0^{2,\varepsilon} - h_1, h_2 - H_0^{2,\varepsilon}) \leq \rho$, then $\mathbb{E}|H_\mu^{2,\varepsilon} - H_0^{2,\varepsilon}| \leq C\rho$

for each ρ and stopping time $\tilde{\mu}$. This easily follows from the boundedness from below of the diffusion coefficient $\tilde{\sigma}_i$ for the process $H_t^{2,\varepsilon}$ and the fact that $H_t^{2,\varepsilon}$ is stopped when it reaches the boundary. By applying the strong Markov property with respect to the stopping time μ^ε and using the smoothness of f , we obtain that

$$\mathbb{E}|\chi_{\{\mu^\varepsilon=\beta^{1,\varepsilon}\}} \left(f(H_{\mu^\varepsilon}^{2,\varepsilon}) - f(H_{\alpha^{2,\varepsilon}(t)\wedge\beta^{2,\varepsilon}}^{2,\varepsilon}) \right)| \leq C\eta\sqrt{t}.$$

The last term on the right hand side of (29) is estimated similarly. This completes the proof of the lemma.

4 Remarks and generalizations

1. Consider nonlinear perturbations of systems with more than one degree of freedom. Let the unperturbed system be completely integrable and in action-angle coordinates have the form

$$\dot{I}_t = 0, \dot{\Phi}_t = \Omega(I_t), \quad I \in \mathbb{R}^m, \Phi \in \mathbb{T}^m, \quad (30)$$

where \mathbb{T}^m is the m -torus, and $\Omega(I) = (\omega_1(I), \dots, \omega_m(I))$ is assumed to be sufficiently smooth and bounded.

Consider the following perturbation of the original system (in the fast time):

$$\begin{aligned} dX_s^{t,x,\varepsilon} &= \frac{1}{\varepsilon} \widehat{\Omega}(I_s^{t,x,\varepsilon}) ds + b(X_s^{t,x,\varepsilon}, u^\varepsilon(t-s, X_s^{t,x,\varepsilon})) ds + \sigma(X_s^{t,x,\varepsilon}) dW_s, \quad s \leq \tau^\varepsilon \wedge t, \\ \tau^\varepsilon &= \min\{s : X_s^{t,x,\varepsilon} \in \partial D\}, \quad X_s^{t,x,\varepsilon} = X_{\tau^\varepsilon}^{t,x,\varepsilon}, \quad \tau^\varepsilon \leq s \leq t, \quad X_0^{t,x,\varepsilon} = x, \\ u^\varepsilon(t, x) &= \text{Eg}(I_t^{t,x,\varepsilon}). \end{aligned}$$

Here $X_s^{t,x,\varepsilon} = (I_s^{t,x,\varepsilon}, \Phi_s^{t,x,\varepsilon})$, W_s is a Wiener process in \mathbb{R}^{2m} , $\widehat{\Omega}(I) = (0, \Omega(I)) \in \mathbb{R}^{2m}$, and the entries of $\sigma(x)$ and $b(x, u)$ are bounded and Lipschitz continuous. We assume as before that the first integrals are constant on connected components of the boundary ∂D of the domain $D \subset \mathbb{R}^{2m}$ and the boundary-initial function g depends only on I . We restrict ourselves to the case when the diffusion coefficients do not depend on u .

Together with the process $X_s^{t,x,\varepsilon}$, consider the process $\tilde{X}_s^{x,\varepsilon} = (\tilde{I}_s^{x,\varepsilon}, \tilde{\Phi}_s^{x,\varepsilon})$ defined by the equation

$$\begin{aligned} d\tilde{X}_s^{x,\varepsilon} &= \frac{1}{\varepsilon} \widehat{\Omega}(\tilde{I}_s^{x,\varepsilon}) ds + \sigma(\tilde{X}_s^{x,\varepsilon}) dW_s, \quad s \leq \tau^\varepsilon \wedge t, \\ \tau^\varepsilon &= \min\{s : \tilde{X}_s^{x,\varepsilon} \in \partial D\}, \quad \tilde{X}_s^{x,\varepsilon} = \tilde{X}_{\tau^\varepsilon}^{x,\varepsilon}, \quad \tau^\varepsilon \leq s \leq t, \quad \tilde{X}_0^{x,\varepsilon} = x. \end{aligned}$$

We assume that the matrix $a(x) = \sigma(x)\sigma^*(x)$ is non-degenerate. Then, using the Girsanov formula, we can write down the following equation for $u^\varepsilon(t, x)$:

$$\begin{aligned} u^\varepsilon(t, x) &= \text{Eg}(\tilde{I}_t^{t,x,\varepsilon}) \exp\left(\int_0^t \sigma^{-1}(\tilde{X}_s^{x,\varepsilon}) b(\tilde{X}_s^{x,\varepsilon}, u^\varepsilon(t-s, \tilde{X}_s^{x,\varepsilon})) dW_s - \right. \\ &\quad \left. \frac{1}{2} \int_0^t |\sigma^{-1}(\tilde{X}_s^{x,\varepsilon}) b(\tilde{X}_s^{x,\varepsilon}, u^\varepsilon(t-s, \tilde{X}_s^{x,\varepsilon}))|^2 ds \right). \quad (31) \end{aligned}$$

In the case of many degrees of freedom we should add one more assumption: because of resonances, the invariant measure of the fast motion, in general, is not unique for some values of I . Assume that the set

$$\{I \in \mathbb{R}^m : \text{frequencies } \omega_1(I), \dots, \omega_m(I) \text{ are rationally dependent}\}$$

has zero Lebesgue measure.

Under this assumption, one can apply the averaging principle to the process $(\tilde{I}_s^{x,\varepsilon}, \tilde{\Phi}_s^{x,\varepsilon})$ and describe the limiting slow motion (see [4]). Using this result and equation (31), one can prove that $\lim_{\varepsilon \downarrow 0} u^\varepsilon(t, I, \Phi) = \bar{u}(t, I)$ exists and solves the problem

$$\frac{\partial \bar{u}}{\partial t} = \frac{1}{2} \sum_{i,j=1}^m \bar{a}_{ij}(I) \frac{\partial^2 \bar{u}}{\partial I_i \partial I_j} + \sum_{i=1}^m \bar{b}_i(I, \bar{u}) \frac{\partial \bar{u}}{\partial I_i},$$

$$\bar{u}(0, I) = g(I), \quad \bar{u}(t, I)|_{\partial D} = g(I)|_{\partial D},$$

where

$$\bar{a}_{ij}(I) = \frac{1}{(2\pi)^m} \int_{\mathbb{T}^m} a_{ij}(I, \Phi) d\Phi, \quad \bar{b}_i(I, u) = \frac{1}{(2\pi)^m} \int_{\mathbb{T}^m} b_i(I, \Phi, u) d\Phi, \quad i, j \in \{1, \dots, m\}.$$

2. We have assumed that the initial and the boundary functions were independent of the fast variable Φ . It is easy to show that this assumption, in general, can not be omitted: if, for instance, in the case of one degree of freedom $\omega(I) = \omega_0 = \text{const}$, and the initial function depends on the angle coordinate, then $\lim_{\varepsilon \downarrow 0} u^\varepsilon(t, I, \varphi)$ may not exist. On the other hand, one can prove, at least in the case of one degree of freedom, that if $d\omega(I)/dI$ has just a finite number of zeros, then $\lim_{\varepsilon \downarrow 0} u^\varepsilon(t, I, \varphi) = \bar{u}(t, I)$ exists and is the solution of the same equation as in the case of initial-boundary functions independent of φ , but the initial and boundary conditions should be replaced by the functions appropriately averaged in φ .

3. Let us again consider the system with one degree of freedom (10)-(12), but now allow H to have a finite number of non-degenerate critical points inside D . If $\sigma = \sigma(x)$ and $b = b(x)$ are independent of u , the limiting behavior of the slow component of the process can be described in terms of a diffusion process on a graph Γ homeomorphic to the set of connected components of the level sets of H inside D (see [3], Chapter 8).

Let $\mathcal{H} : D \rightarrow \Gamma$ be the identification mapping. The corresponding result for the parabolic equation is that $u^\varepsilon(t, x)$ converges to $\bar{u}(t, \mathcal{H}(x))$ as $\varepsilon \downarrow 0$, where the limiting function \bar{u} is defined on $[0, \infty) \times \Gamma$, satisfies the differential equations on the edges of the graph (as in (6), but with coefficients independent of \bar{u}) and certain gluing conditions at the interior vertices of Γ ([3], Chapter 8). Now we claim that a similar result holds even if b is allowed to depend on u . Namely, using the Girsanov formula, one can write an equation for $u^\varepsilon(t, x)$ in the form (31). Using this equation and the bounds obtained in Sections 2 and 3, one can check that the gluing conditions at the vertices will be the same

as in the case $b(x, u) \equiv 0$ (compare with [1]). The differential operators inside the edges of the graph are obtained in the same way as in Theorem 1.1.

Acknowledgements: While working on this article, M. Freidlin was supported by NSF grants DMS-0803287 and DMS-0854982 and L. Korolov was supported by NSF grants DMS-0706974 and DMS-0854982.

References

- [1] Brin M, Freidlin M.I., *On stochastic behavior of perturbed Hamiltonian system*, Ergodic Th. and Dynamical Sys., 2000, 20, pp 55-76.
- [2] Freidlin M.I., *Functional Integration and Partial Differential Equations*, Princeton University Press, 1985.
- [3] Freidlin M. I., Wentzell A. D., *Random Perturbations of Dynamical Systems*, Springer 1998.
- [4] Freidlin M. I., Wentzell A. D., *Averaging Principle for stochastic perturbations of multifrequency systems*, Stochastics and Dynamics, 3, pp 393-408, 2003.
- [5] Krylov N.V., *Nonlinear Elliptic and Parabolic Equations of the Second Order (Mathematics and its Applications)*, Springer 1987.