Data compression and definability of types in stable and dependent formulas

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Paris, 26 July, 2010

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Suppose  $\mathscr{C} \subseteq {}^X 2$  is a set of 'concepts'. Let  $\mathscr{C}|_{\operatorname{fin}} = \{c|Y : c \in \mathscr{C} \text{ and } Y \subseteq X, Y \text{ finite}\}\)$ and  $\mathscr{C}|_{\leq d} = \{c|Z : c \in \mathscr{C} \text{ and } Z \subseteq X, |Z| \leq d\}.$ 

### Definition (Littlestone-Warmuth, 1986)

A *d*-dimensional compression scheme consists of a compression function  $\kappa : \mathscr{C}|_{\text{fm}} \to \mathscr{C}|_{\leq d}$  and a reconstruction function  $\rho : \mathscr{C}|_{\leq d} \to X^2$  satisfying

$$\kappa(c|Y) \subseteq c|Y \subseteq \rho(\kappa(c|Y))$$

for all  $c \in \mathscr{C}$  and finite  $Y \subseteq X$ .

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# "Original" Compression schemes

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Open Question Does every *d*-dimensional VC class  $\mathscr{C}$  of concepts have a *d*-dimensional compression scheme?

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 $\kappa(c|Y) \subseteq c|Y \subseteq \rho(\kappa(c|Y))$ 

for all  $c \in \mathscr{C}$  and finite  $Y \subseteq X$ .

Open Question Does every *d*-dimensional VC class  $\mathscr{C}$  of concepts have a *d*-dimensional compression scheme? Warmuth has offered a \$600 prize for an answer in either direction.

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To get a better behaved notion, allow finitely many reconstruction functions.

### Definition

Fix  $\mathscr{C} \subseteq {}^{X}2$ . A *d*-dimensional extended compression scheme consists of a compression function  $\kappa : \mathscr{C}|_{\text{fin}} \to X^{d}$  and finitely many reconstruction functions  $\rho_{i} : X^{d} \to {}^{X}2$  such that for every  $c \in \mathscr{C}$  and  $Y \subseteq_{\text{fin}} X$ ,

• 
$$\operatorname{range}(\kappa(c|Y)) \subseteq Y$$
 and

•  $\rho_i(\kappa(c|Y))$  extends c|Y for at least one *i*.

This is equivalent to definitions proposed and studied by Litman-Ben-David, Basu, and Floyd-Warmuth.

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• If X is finite, then all  $\mathscr{C} \subseteq {}^{X}2$  do.

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• If X is finite, then all  $\mathscr{C} \subseteq {}^{X}2$  do.

• If X is infinite and  $\mathscr{C}$  has a d-dimensional extended compression scheme (with k reconstruction functions), then for  $Y \subseteq X$  finite, elements of  $\mathscr{C}_Y = \{c | Y : c \in \mathscr{C}\}$  are determined by  $\kappa(c|Y) \in Y^d$  and by the choice of  $\rho_i$ . Thus,  $|\mathscr{C}_Y| \leq k|Y|^d$ .

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# Which concept classes have extended compression schemes?

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Image: Image:

# Which concept classes have extended compression schemes?

This is a model theoretic question!

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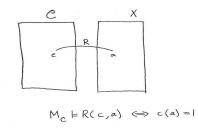
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# Which concept classes have extended compression schemes?

This is a model theoretic question! Given  $\mathscr{C} \subseteq {}^{X}2$ , form a structure  $M_{\mathscr{C}} = (\mathscr{C}, X, R(x, y))$ .



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If  $\mathscr{C} \subseteq {}^{X}2$  is given and the relation R(x, y) is stable in the associated structure  $M_{\mathscr{C}}$ , then  $\mathscr{C}$  has an extended compression scheme.

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Pf: Definability of types!

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### Pf: Definability of types!

There is a formula  $\psi(y, z_1, \ldots, z_d)$  such that for any  $Y \subseteq X$  and for any  $c \in \mathscr{C}$ , there are  $(b_1, \ldots, b_d) \in Y^d$  such that  $R(c, Y) = \psi(Y, b_1, \ldots, b_d)$ .

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If  $\mathscr{C} \subseteq {}^{X}2$  is given and the relation R(x, y) is stable in the associated structure  $M_{\mathscr{C}}$ , then  $\mathscr{C}$  has an extended compression scheme.

Pf: Definability of types! There is a formula  $\psi(y, z_1, \dots, z_d)$  such that for any  $Y \subseteq X$  and for any  $c \in \mathscr{C}$ , there are  $(b_1, \dots, b_d) \in Y^d$  such that  $R(c, Y) = \psi(Y, b_1, \dots, b_d)$ . Compress via  $\kappa(c|Y) = (b_1, \dots, b_d)$  and reconstruct by  $\rho(b_1, \dots, b_d) = \psi(X, b_1, \dots, b_d)$ .

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Question: If  $\varphi(x, y)$  is stable, can we bound the *d* in a uniform defining formula  $\psi(y, z_1, \dots, z_d)$ ?

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Answer: YES.

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Question: If  $\varphi(x, y)$  is stable, can we bound the *d* in a uniform defining formula  $\psi(y, z_1, \dots, z_d)$  ?

Answer: YES.  $d \leq R_{\varphi}(x = x, 2)$ .

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Why? Recall  $R_{\varphi}(\theta(x), 2) \ge 0$  iff  $\theta(x)$  is consistent and  $R_{\varphi}(\theta(x), 2) \ge n + 1$  iff for some *a*, both  $R_{\varphi}(\theta \land \varphi(x, a), 2) \ge n$  and  $R_{\varphi}(\theta \land \neg \varphi(x, a), 2) \ge n$ .

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Thus: • 
$$\varphi(x, y)$$
 is stable iff  $R_{\varphi}(x = x, 2)$  is finite;  
•  $\{e : R_{\varphi}(\theta(x, e), 2) \ge n\}$  is definable;  
• If  $R_{\varphi}(\theta, 2) = n$ , then for any *a*, **at most one** of  $\theta \land \varphi(x, a)$ ,  
 $\theta \land \neg \varphi(x, a)$  has  $R_{\varphi} = n$ .

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Given  $p \in S_{\varphi}(A)$ , call a subtype  $p_i \subseteq p$  one-element minimal if  $R_{\varphi}(q,2) = R_{\varphi}(p_i,2)$  for all  $p_i \subseteq q \subseteq p$  with  $|q \setminus p_i| = 1$ .

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Note: For any  $p \in S_{\varphi}(A)$  there is a one-element minimal  $p_i \subseteq p$ with  $|p_i| \leq R_{\varphi}(x = x, 2)$ . Why? Let  $p_0 = \emptyset$  and given  $p_i$ , let  $p_{i+1} \subseteq p$  be any one-element extension of  $p_i$  of smaller 2-rank (if one exists).

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why? Let  $p_0 = \emptyset$  and given  $p_i$ , let  $p_{i+1} \subseteq p$  be any one-element extension of  $p_i$  of smaller 2-rank (if one exists).

Check: For any  $p \in S_{\varphi}(A)$ , if  $p_i \subseteq p$  is one-element minimal then p is defined by the formula " $R_{\varphi}(p_i \land \varphi(x, y), 2) = R_{\varphi}(p_i, 2)$ ." Why? For  $a \in A$ ,  $\varphi(x, a) \in p \Rightarrow R_{\varphi}(p_i \land \varphi(x, a), 2) = R_{\varphi}(p_i, 2)$  by minimality of  $p_i$  and  $\varphi(x, a) \notin p \Rightarrow \neg \varphi(x, a) \in p \Rightarrow R_{\varphi}(p_i \land \neg \varphi(x, a), 2) = R_{\varphi}(p_i, 2) \Rightarrow R_{\varphi}(p_i \land \varphi(x, a), 2) \neq R_{\varphi}(p_i, 2).$ 

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Caution: Even though every  $\varphi$ -type has a definition  $\psi(y, z_1, \ldots, z_d)$  with  $d \leq R_{\varphi}(x = x, 2)$ , this does not imply that one can bound the size of a subtype  $p_0 \subseteq p$  such that  $R_{\varphi}(p_0, 2) = R_{\varphi}(p, 2)$ .

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A new notion:

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## A new notion:

## Definition

A formula  $\varphi(x, y)$  has **Uniform Definability Types over Finite Sets** (UDTFS) if there is a formula  $\psi(y, z_1, \ldots, z_d)$  such that for every finite set A,  $|A| \ge 2$  and every  $p \in S_{\varphi}(A)$ , there are  $(b_1, \ldots, b_d) \in A^d$  such that

$$\varphi(\mathbf{x}, \mathbf{a}) \in \mathbf{p} \qquad \Longleftrightarrow \qquad \models \psi(\mathbf{a}, \mathbf{b}_1, \dots, \mathbf{b}_d)$$

for every  $a \in A$ .

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#### Observation

If  $\varphi(x, y)$  has UDTFS, then the uniformly definable family  $\mathscr{C}_{\varphi(x,y)} = \{\varphi(c, M) : c \in Sort(x)\}$  has an extended compression scheme.

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Image: A matrix of the second seco

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• If  $\varphi(x, y)$  is stable, then  $\varphi(x, y)$  has UDTFS.

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Image: A math a math

- If  $\varphi(x, y)$  is stable, then  $\varphi(x, y)$  has UDTFS.
- If  $\varphi(x, y)$  has UDTFS via  $\psi(y, z_1, \dots, z_d)$ , then for any finite set  $Y, |S_{\varphi}(Y)| \leq |Y|^d$ , so  $\varphi(x, y)$  is dependent (NIP) with independence dimension at most d.

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Open Question Does every dependent formula have UDTFS?

• If  $\varphi(x, y)$  is stable, then  $\varphi(x, y)$  has UDTFS.

• If  $\varphi(x, y)$  has UDTFS via  $\psi(y, z_1, \dots, z_d)$ , then for any finite set  $Y, |S_{\varphi}(Y)| \leq |Y|^d$ , so  $\varphi(x, y)$  is dependent (NIP) with independence dimension at most d.

**Open Question** Does every dependent formula have UDTFS? If you can prove this, you can petition Warmuth for \$600.

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# Definability over Indiscernible Sequences

## A plausibility argument:

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# Definability over Indiscernible Sequences

## A plausibility argument:

#### Theorem

A partitioned formula  $\varphi(x, y)$ is stable if and only if there exists a formula  $\psi(y, \overline{z})$  so that for all order indiscernible sequences A and all  $p \in S_{\varphi}(A)$ , there exists  $\overline{a} \in A^d$ so that  $\psi(y, \overline{a})$  defines p.

#### Theorem

A partitioned formula  $\varphi(x, y)$ is dependent iff there exists a formula  $\psi(y, \overline{z})$  so that for all finite order indiscernible sequences A and all  $p \in S_{\varphi}(A)$ there exists  $\overline{a} \in A^d$  so that  $\psi(y, \overline{a})$  defines p.

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The class of UDTFS formulas is well behaved:

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The class of UDTFS formulas is well behaved:

• Closed under boolean combinations: If  $\varphi(x, y)$  and  $\psi(x, z)$  are both UDTFS, then so are  $\neg \varphi(x, y)$  and  $[\varphi \land \psi](x, yz)$ .

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The class of UDTFS formulas is well behaved:

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• "Finitely many defining formulas suffice" Given  $\varphi(x, y)$ , if there are finitely many  $\psi_i(y, z_1, \ldots, z_d)$  such that for every finite A, every  $p \in S_{\varphi}(A)$  is definable by some  $\psi_i(y, a_1, \ldots, a_d)$ , then  $\varphi$  has UDTFS.

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• "Sufficiency of a single variable" [Guingona] If every formula  $\varphi(x, \overline{y})$  with a single x-variable has UDTFS, then every formula  $\varphi(\overline{x}, \overline{z})$  has UDTFS.

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## Theorem (H. Johnson-L, 2008)

If T is o-minimal then every formula  $\varphi(\overline{x}, \overline{y})$  is UDTFS. It follows that the uniformly definable family  $\mathscr{C}_{\varphi(\overline{x},\overline{y})}$  has a d-dimensional extended compression scheme where  $d = lg(\overline{x})$ .

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### Theorem (H. Johnson-L, 2008)

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In some sense, this was proved by Marker-Steinhorn who established definability of types for o-minimal structures with Dedekind complete order types.

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• If T is weakly o-minimal, then every formula has UDTFS.

- If T is weakly o-minimal, then every formula has UDTFS.
- If  $\varphi$  has independence dimension one, then  $\varphi$  has UDTFS.

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- If T is VC-minimal, then every formula has UDTFS.

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Image: A matrix of the second seco

- If T is weakly o-minimal, then every formula has UDTFS.
- If  $\varphi$  has independence dimension one, then  $\varphi$  has UDTFS.
- If T is VC-minimal, then every formula has UDTFS.

• If  $\varphi$  has density one, i.e., there is a constant k so that  $|S_{\varphi}(A)| \leq k|A|$  for all finite sets A in the sort of y, then  $\varphi$  has UDTFS.

Some deeper results (also proved by Guingona):

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Some deeper results (also proved by Guingona):

# Theorem (Guingona)

Suppose there is an n such that for any set A of size n (in the sort of y),  $|S_{\varphi}(A)| \leq {n \choose 2} + {n \choose 1}$  then  $\varphi$  has UDTFS.

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Some deeper results (also proved by Guingona):

### Theorem (Guingona)

Suppose there is an n such that for any set A of size n (in the sort of y),  $|S_{\varphi}(A)| \leq {n \choose 2} + {n \choose 1}$  then  $\varphi$  has UDTFS.

Remark: If the independence dimension of  $\varphi$  is 2, then  $|S_{\varphi}(A)| \leq {n \choose 2} + {n \choose 1} + 1$  by Sauer's theorem.

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An *ict*-pattern with two rows consists of two formulas  $\varphi(x, y)$  and  $\psi(x, z)$  such that for every N there exist  $\{b_i : i < N\}$  and  $\{c_i : j < N\}$  such that each of the  $N^2$  formulas

$$arphi(x,b_{i^*})\wedge\psi(x,c_{j^*})\wedge\bigwedge_{i
eq i^*}
eg arphi(x,b_i)\wedge\bigwedge_{j
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eg \psi(x,c_j)$$

indexed by  $(i^*, j^*) \in N^2$  is consistent.

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A theory T is *dp*-minimal if it does not admit an *ict*-pattern with two rows.

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# Theorem (Guingona)

If T is dp-minimal then every formula has UDTFS.

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# Bibliography

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