While these notes are under construction, I expect there will be many typos.

The main reference for this is volume 1 of Hörmander, The analysis of liner partial differential equations. I have picked a few of the most useful and concrete highlights. The references are based on the 1989 hardcover second edition.

1. Generalities (from Ch. 2 and 3)

Definition 1.1. Let U be an open set in \mathbb{R}^n . A distribution $u \in \mathcal{D}'(U)$ is a linear function $u: C_0^{\infty}(U) \to \mathbb{C}$. One can write $u(\phi) = \langle u, \phi \rangle$ and think of this, informally, as $u(\phi) = \int u\phi$. It is required that u is continuous in the following sense:

For every $K \subset U$ compact there exist C, k such that

$$|u(\phi)| \le C \sum_{|\alpha| \le k} \sup_{x} |\partial^{\alpha} \phi| \tag{1}$$

for every $\phi \in C_0^{\infty}(U)$ supported in K.

If one k works for all K, u is of finite order. The smallest such k is the order of u.

We will need an equivalent formulation of the continuity condition.

Definition 1.2. Let $\phi_j, \phi \in C_0^{\infty}(U)$. The sequence $\phi_j \to \phi$ in $C_0^{\infty}(U)$ if there exists a compact subset of U which contains the support of all ϕ_j, ϕ and for every fixed α , $\sup_x |\partial^{\alpha} (\phi_j(x) - \phi(x))| \to 0$ as $j \to \infty$.

Theorem 1.3. A linear function $u: C_0^{\infty}(U) \to \mathbb{C}$ is a distribution if and only if $u(\phi_i) \to u(\phi)$ for every $\phi_i \to \phi$ in $C_0^{\infty}(U)$.

Proof. To show that if u is a distribution, then $u(\phi_j) \to u(\phi)$ for every $\phi_j \to \phi$ in $C_0^{\infty}(U)$ is clear from the definition. The other half is an easy exercise in negations.

Examples:

- (1) If \tilde{u} is a locally integrable function, $u(\phi) := \int \tilde{u}\phi$. This identifies the function \tilde{u} with a distribution u.
- (2) Dirac delta function. $\delta_a(\phi) = \phi(a)$

- (3) Weak derivatives: If u is a locally integrable function, $\langle \partial^{\alpha} u, \phi \rangle := (-1)^{|\alpha|} \int u \partial^{\alpha} \phi$. This agrees with integration by parts if u is a smooth function and is in fact the definition of $\partial^{\alpha} u$ for any distribution u: $\partial^{\alpha} u(\phi) = (-1)^{|\alpha|} u(\partial^{\alpha} \phi)$.
- (4) It takes some work (thm. 4.4.7 in Hörmander) and we will not prove this, but the above essentially accounts for all possible distributions:

If $u \in \mathcal{D}'(U)$ then there exists a locally finite family of continuous functions f_{α} (each compact subset of U intersects only finitely many of the supports of the f_{α} s) such that

$$u(\phi) = \sum \int f_{\alpha} \partial^{\alpha} \phi$$

Definition 1.4. A sequence of distributions u_i converges to u in $\mathcal{D}'(U)$ (or in the sense of distribution theory) if $u_i(\phi) \to u(\phi)$ for every $\phi \in C_0^{\infty}(U)$

Also, if $u_i \in \mathcal{D}'(U)$ and for each fixed $\phi \in C_0^{\infty}(U)$ the limit $u_i(\phi)$ exists and is denoted $u(\phi)$, then u is automatically a distribution. See Theorem 2.1.8. We will not prove this.

Definition 1.5. Let $u \in \mathcal{D}(U)$ and $f \in C^{\infty}(U)$. Then the distributions $\frac{\partial u}{\partial x_k}$ and fu are defined by

$$\left(\frac{\partial u}{\partial x_k}\right)(\phi) = -u\left(\frac{\partial}{\partial x_k}\right)$$
$$(fu)(\phi) = u(f\phi)$$

Unlike classical convergence, if $u_i \to u$ in $\mathcal{D}'(U)$, then $\partial^{\alpha} u_i \to \partial^{\alpha} u$ in $\mathcal{D}'(U)$ is trivial.

Example 1: Let H be the Heavyside function. Then $H' = \delta_0$.

The following two propositions will be proved in class. (See Chapter 3 in Hörmander)

Proposition 1.6. Let u be continuous on \mathbb{R} and C^1 on $\mathbb{R} \setminus x_0$. Let v = u' on $\mathbb{R} \setminus x_0$, and assume the function v is locally integrable. Then u' = v in the sense of distribution theory.

Proposition 1.7. Let $u \in \mathcal{D}'(\mathbb{R})$, and assume u' = 0. Then u is constant.

Remark that if u is the Cantor function, u is continuous and u' = 0 a.e, but $u' \neq 0$ in the sense of distribution theory.

More examples to be worked out in class:

- If E is the fundamental solution of the Laplace operator, ∇E in the sense of distributions agrees with the locally integrable function ∇E defined for $x \neq 0$, but ΔE in the sense of distributions does not agree with the locally integrable function $\Delta E = 0$ defined for $x \neq 0$. In fact $\Delta E = \delta_0$.
- $\frac{\partial f}{\partial \overline{z}} \frac{1}{z} = \frac{1}{\pi} \delta_0$. This follows from the fundamental solution of the Laplace operator in the plane.
- Let f analytic in $\mathbb{C} \setminus \{0\}$, and assume f is bounded in a neighborhood of 0. Then $\frac{\partial f}{\partial \overline{z}} = 0$ in the sense of distribution theory. We will see later that this implies f analytic, thus f has a removable singularity.
- Let u continuous in the plane, and harmonic for y > 0 Assume u extends as a C^1 (but possibly not C^2) function to $y \ge 0$. Assume u(x,0) = 0, and u(x,y) = -u(x,-y). Then $\Delta u = 0$ in the plane (weakly). We will see that this implies u is harmonic classically. This is why Schwarz reflection works.

Definition 1.8. A distribution u is defined to be 0 in an open set $V \subset U$ if $u(\phi) = 0$ for every $\phi \in C_0^{\infty}(V)$. The union of all such subsets V is the largest open set where u is 0, and the complement of that is defined to be the support of u.

Thus the support of a distribution $u \in \mathcal{D}(U)$ is always (relatively) closed in U. If the support of u is compact, u is called compactly supported. The set of compactly supported distributions in U is denoted by $\mathcal{E}'(U)$

Recall the support of a function ϕ is the closure of the set $\{\phi(x) \neq 0\}$. If $u \in \mathbb{R}^n$ and $\phi \in C_0^{\infty}(\mathbb{R}^n)$, and the support of ϕ and u are disjoint, then $u(\phi) = 0$. However, if ϕ is zero on the support of u, it does not follow that $u(\phi) = 0$. Example: $\delta'(x)$.

If $u \in \mathcal{E}'(U)$, $u(\phi)$ is well defined for $\phi \in C^{\infty}$: Let K be the support of $u, K \subset V \subset U$ with V open. There exists a smooth cut-off function $\zeta \in C_0^{\infty}(U)$, and $\zeta = 1$ in V. Then $u(\zeta\phi)$ is well-defined, and is independent of the choice of ζ . Define $u(\phi) = u(\zeta\phi)$ for ζ as above.

Definition 1.9. A distribution u is defined to be smooth in an open set $V \subset U$ if there exists $\tilde{u} \in C^{\infty}(V)$ such that $u(\phi) = \int \tilde{u}(x)\phi(x)dx$ for all $\phi \in C_0^{\infty}(V)$ The union of all such subsets V is the largest open set where u is smooth, and the complement of that is defined to be the singular support of u.

The major goals of this sections of the course are to prove 1) If $f \in \mathcal{E}'$, then there exists $u \in \mathcal{D}'$ such that $\Delta u = f$.

2) If u, f are as above, and $f \in C^{\infty}(V)$ for some open set V, then $u \in C^{\infty}(V)$.

Both of these goals follow from the properties of the convolution of a distribution with a compactly supported distribution. Part 1 follows by writing u=E*f, $\Delta u=(\Delta E)*f=\delta*f=f$, but we have to assign rigorous meaning to this. Part 2 follows from the fact that the fundamental solution E is C^{∞} away from 0. The exact same results hold for $\frac{\partial}{\partial t}-\Delta$ and $\frac{\partial}{\partial \overline{z}}$, but not $\frac{\partial^2}{\partial t^2}-\Delta$.

First, two short digressions.

2. Distributions supported at one point

Theorem 2.1. If $u \in \mathcal{D}'(\mathbb{R}^n)$ is supported at a point, say 0, then u is a finite linear combination

$$u = \sum c_{\alpha} \partial^{\alpha} \delta$$

Proof. Assume u is of order k (and prove: any compactly supported distribution is of finite order). Pick a test function ϕ and write $\phi(x) = T(x) + R(x)$ the kth order Taylor polynomial plus remainder. u(T) is what we want (check!), and the point is to show that u(R) = 0 where R is the remainder. We know $|R(x)| \leq C|x|^{k+1}$ for $|x| \leq 1$ and in fact $|\partial^{\alpha}R(x)| \leq C|x|^{k+1-|\alpha|}$ for all $|\alpha| \leq k$. Let $\epsilon > 0$, and let χ be a cut-off function, identically 1 in a neighborhood of 0.

Then $|u(R)| = |u(\chi(\frac{x}{\epsilon})R)| \le C \sum_{|\alpha| \le k} \sup_{x} |\partial^{\alpha}(\chi(\frac{x}{\epsilon})R)| \le C\epsilon$. Now let $\epsilon \to 0$.

Application to PDE: Let $E = \frac{1}{|x|^{n-2}}$ $(n \ge 3)$. Then $\Delta E = 0$ for x away from 0 by calculation, thus ΔE is a distribution supported at 0. It is a finite linear combination of the delta function and its derivatives. An additional homogeneity argument shows $\Delta E = c\delta$.

If u is a locally integrable function in $\mathbb{R}^n - \{0\}$, u is homogeneous of degree α if $u(tx) = t^{\alpha}u(x)$ for all t > 0 and $x \neq 0$. Denoting $\phi_t(x) = t^n \phi(tx)$ this is equivalent to

$$\int u\phi = t^{\alpha} \int u\phi_t$$

and the definition of a homogeneous distribution in \mathbb{R}^n (or $\mathbb{R}^n - \{0\}$) is

$$u(\phi) = t^{\alpha} u(\phi_t)$$

for every $\phi \in C_0^{\infty}(\mathbb{R}^n)$ or $C_0^{\infty}(\mathbb{R}^n - \{0\})$.

3. The gradient of a characteristic function and homogeneous distributions

Our next theorem (formula 3.1.5 in Hörmander's book) is

Theorem 3.1. Let U be an open set with C^1 boundary. Then

$$\nabla \chi_U = -\nu dS$$

where ν is the outward pointing normal.

Proof. Let $h : \mathbb{R} \to \mathbb{R}$ be a smoothed out Heaviside function: h(x) = 0 if $x \leq 0$, h(x) = 1 if $x \geq 1$ and smooth in-between. It suffices the prove the theorem for test functions ϕ supported in a small neighborhood of $x_0 \in \partial U$, where U agrees with $x_n > r(x_1, \dots, x_{n-1})$. Then

$$\int \chi_U \phi = \lim_{\epsilon \to 0} \int h(\frac{x_n - r(x_1, \dots x_{n-1})}{\epsilon}) \phi(x_1, \dots, x_n)$$

by the Lebesgue dominated convergence theorem, and

$$\nabla \chi_{U}(\phi) = \lim_{\epsilon \to 0} \int \nabla \left(h(\frac{x_{n} - r(x_{1}, \dots x_{n-1})}{\epsilon}) \right) \phi(x_{1}, \dots, x_{n})$$

$$= \lim_{\epsilon \to 0} \int_{\mathbb{R}^{n}} \frac{1}{\epsilon} h'(\frac{x_{n} - r(x_{1}, \dots x_{n-1})}{\epsilon}) \cdot (-\nabla r(x_{1}, \dots, x_{n-1}), 1) \phi(x) dx$$

$$= \int_{\mathbb{R}^{n-1}} \phi(x_{1}, \dots x_{n-1}, r(x_{1}, \dots r_{x-1})) \cdot (-\nabla r(x_{1}, \dots, x_{n-1}), 1) \phi dx_{1} \dots dx_{n-1}$$
integrate x_{n} first

$$= -\int_{\partial U} \phi \cdot \nu \phi dS$$

(by the Calculus formulas for ν and dS). We used the fact that $\frac{1}{\epsilon}h'(\frac{x}{\epsilon})$ is an "approximation to the identity". We will see another proof of this important fact in the chapter on compositions with smooth functions.

4. Convolutions (Chapter 4 in Hörmander's book)

Definition 4.1. If $u \in \mathcal{D}'(\mathbb{R}^n)$ and $\phi \in C_0^{\infty}(\mathbb{R}^n)$,

 $u * \phi(x) = u(\phi(x - \cdot))$ (where · stands for y, and u acts in the y variable)

Check
$$u * \phi \in C^{\infty}$$
, $\partial^{\alpha}(u * \phi)(x) = (\partial^{\alpha}u) * \phi = u * (\partial^{\alpha}\phi)(x)$: We have
$$\phi(x - y + \epsilon e_i) - \phi(x - y) = \frac{\partial}{\partial x_i}\phi(x - y) + R(x - y, \epsilon)$$

where

$$R(x - y, \epsilon) = \int_0^1 \frac{d^2}{dt^2} \left(\phi(x - y + t\epsilon e_i) \right) (1 - t) dt$$
$$= \epsilon^2 \int_0^1 \left(\frac{\partial^2 \phi}{\partial x_i^2} \right) (x - y + t\epsilon e_i) (1 - t) dt$$

Fix x. $R(x-y,\epsilon)$ is in C_0^{∞} , and $\sup_y |\partial_y^{\alpha} R(x-y,\epsilon)| \leq C_{\alpha} \epsilon^2$. Using the continuity condition (1) we see

$$\lim_{\epsilon \to 0} \frac{R(x - \cdot, \epsilon)}{\epsilon} = 0$$

and

$$\lim_{\epsilon \to 0} \frac{u\left(\phi(x - \cdot + \epsilon e_i)\right) - u\left(\phi(x - \cdot)\right)}{\epsilon} = u\left(\frac{\partial}{\partial x_i}\phi(x - \cdot)\right) = \frac{\partial u}{\partial x_i}(\phi(x - \cdot))$$

Check $support(u * \phi) \subset support u + support \phi$: Fix x. If $\phi(x - \cdot)$ is supported in the complement of support u, then $u(\phi(x - \cdot) = 0)$ by the definition of support u. If $u(\phi(x - \cdot) \neq 0)$, then $\exists y \in support u$ and $y \in support \phi(x - \cdot)$. Thus $y = \lim y_i$ with $\phi(x - y_i) \neq 0$, and

 $x = \lim (x - y_i + y) \in \overline{support \phi + support u} = support \phi + support u$ because support u is compact.

We also have

Theorem 4.2. Let $u \in \mathcal{D}'(\mathbb{R}^n)$, and $\phi, \psi \in C_0^{\infty}(\mathbb{R}^n)$. Then $(u*\phi)*\psi = u*(\phi*\psi)$.

Proof. Before starting the proof, review Definition (1.2). $u * \phi \in C^{\infty}$. Fix x.

$$(u * \phi) * \psi(x) = \int (u * \phi)(x - y)\psi(y)dy$$

$$= \lim_{h \to 0+} \sum_{k \in \mathbb{Z}^n} (u * \phi)(x - kh)\psi(kh)h^n$$

$$= \lim_{h \to 0+} u \left(\sum_{k \in \mathbb{Z}^n} \phi(x - kh - \cdot)\psi(kh)h^n\right)$$

$$= u \left(\int \phi(x - z - \cdot)\psi(z)dz\right)$$

In the last line, we used the (obvious) fact that, for x fixed,

$$\sum_{k \in \mathbb{Z}^n} \phi(x - kh - y)\psi(kh)h^n \to \int \phi(x - z - y)\psi(z)dz$$

uniformly in y, and the same is true for after differentiating with respect to y an arbitrary number of times. Also, both LHS and RHS are supported in a fixed compact set. In other words, LHS \to RHS in C_0^{∞} .

This implies the important theorem on approximating distributions by C^{∞} functions.

Theorem 4.3. Let $u \in \mathcal{D}'(\mathbb{R}^n)$, and let η_{ϵ} be the standard mollifier. Then $u * \eta_{\epsilon} \in C^{\infty}(\mathbb{R}^n)$ and $u * \eta_{\epsilon} \to u$ in the sense of distribution theory (as $\epsilon \to 0$).

Proof. We have to check

$$(u * \eta_{\epsilon})(\phi) \to u(\phi)$$

for every $\phi \in C_0^{\infty}(\mathbb{R}^n)$. The proof is based on the observation that $u(\phi) = u * \phi_{-}(0)$ where $\phi_{-}(x) = \phi(-x)$. So it suffices to show $(u * \eta_{\epsilon}) * \phi(0) \to u * \phi(0)$. But

$$(u * \eta_{\epsilon}) * \phi(0) = u * (\eta_{\epsilon} * \phi)(0) \to u * \phi(0)$$

since $\eta_{\epsilon} * \phi \to \phi$ in C_0^{∞} .

Now we define the convolution of two distribution u_1, u_2 , one of which is compactly supported.

This is defined so that the formula

$$(u_1 * u_2) * \phi = u_1 * (u_2 * \phi)$$

holds for all $\phi \in C_0^{\infty}(\mathbb{R}^n)$. For simplicity, let's assume u_2 is compactly supported. Instead of defining $(u_1 * u_2)(\phi)$ it suffices to define $(u_1 * u_2) * \phi(0)$. This is done in the obvious way:

$$(u_1 * u_2) * \phi(0) = u_1 * (u_2 * \phi)(0)$$

We have to check that $u_1 * u_2$ satisfies the continuity condition. Let $\phi_j \to 0$ in $C_0^{\infty}(\mathbb{R}^n)$ (see Definition (1.2)). Then so does $u_2 * \phi_j$, and $u_1 * (u_2 * \phi_j)(0) \to 0$.

Also, it τ_h denotes a translation, $(\tau_h \phi)(x) = \phi(x+h)$, then $\tau_h(u*\phi) = u*(\tau_h \phi)$ and

$$(u_1 * u_2) * \phi(h) = \tau_h ((u_1 * u_2) * \phi) (0) = ((u_1 * u_2) * \tau_h \phi) (0)$$

= $u_1 * (u_2 * \tau_h \phi) (0) = u_1 * (\tau_h (u_2 * \phi)) (0)$
= $u_1 * (u_2 * \phi) (h)$

Proposition 4.4. Let $u_1, u_2 \in \mathcal{D}'(\mathbb{R}^n)$, one of which is compactly supported. Then

$$support(u_1 * u_2) \subset support(u_1 + support(u_2))$$

Proof. Let η_{ϵ} be a standard mollifier supported in a ball or radius ϵ . It suffices to show

 $support (u_1 * u_2) \subset support u_1 + support u_2 + support \eta_{\epsilon_0}$ for all $\epsilon_0 > 0$. We do know

 $support (u_1 * u_2 * \eta_{\epsilon}) \subset support u_1 + support u_2 + support \eta_{\epsilon}$ $\subset support u_1 + support u_2 + support \eta_{\epsilon_0}$

for all $0 < \epsilon < \epsilon_0$. Also remark that if A is closed and u is a distribution such that $support\ u * \eta_{\epsilon} \subset A$ for all $\epsilon_0 > \epsilon > 0$, then $support\ u \subset A$. This amounts to showing that if $u * \eta_{\epsilon} = 0$ in A^c , then u = 0 in A^c , which follows from $u * \eta_{\epsilon} \to u$ in the sense of distributions.

Theorem 4.5. Let u_1, u_2, u_3 distributions in \mathbb{R}^n , two of which are compactly supported. Then

$$(u_1 * u_2) * u_3 = u_1 * (u_2 * u_3)$$

Proof. The proof follows by noticing it suffices to check $((u_1 * u_2) * u_3) * \phi = (u_1 * (u_2 * u_3)) * \phi$ for every $\phi \in C_0^{\infty}(\mathbb{R}^n)$ which follows easily from the defining property of Theorem (4.2).

Theorem 4.6. Let $u_1, u_2 \in \mathcal{D}'(\mathbb{R}^n)$, one of which is compactly supported. Then

$$u_1 * u_2 = u_2 * u_1$$

Proof. The strategy is to show that $(u_1 * u_2) * (\phi * \psi) = (u_2 * u_1) * (\phi * \psi)$ for all test functions ϕ, ψ . This is done using the associativity property Theorem (4.2) together with the fact that convolutions of functions is commutative. We will not prove this

Theorem 4.7. Let $u_1, u_2 \in \mathcal{D}'(\mathbb{R}^n)$, one of which is compactly supported. Then

$$\partial^{\alpha}(u_1 * u_2) = (\partial^{\alpha}u_1) * u_2 = u_1 * \partial^{\alpha}u_2 \tag{2}$$

Proof. We already know $\partial^{\alpha}(u * \phi) = (\partial^{\alpha}u) * \phi = u * (\partial^{\alpha}\phi)$, so the theorem is proved by convolving (2) with ϕ .

Theorem 4.8. Let $u_1, u_2 \in \mathcal{D}'(\mathbb{R}^n)$, one of which is compactly supported. Then

 $sing \, support \, (u_1 * u_2) \subset sing \, support \, u_1 + sing \, support \, u_2$

Proof. The proof is based on the fact that if one of u_1 , u_2 is smooth, so is u_1*u_2 . Let χ_1, χ_2 be supported in small neighborhoods of $sing\ support\ u_1$, $sing\ support\ u_2$, so that $(1-\chi_1)u_1$ and $(1-\chi_2)u_2$ are smooth. Then

 $sing\ support\ (u_1*u_2)\subset sing\ support\ (\chi_1u_1)*(\chi_2u_2)\subset support\ \chi_1u_1+support\ \chi_2u_2$

Now we come back to PDEs. Let P(D) be a constant coefficient differential operator. A distribution $E \in \mathcal{D}'(\mathbb{R}^n)$ is called a fundamental solution if $P(D)E = \delta$. We already know formulas for (the) fundamental solution of the Laplace and heat operators. We will write down later several fundamental solutions of the wave operator.

Theorem 4.9. If sing support $(E) = \{0\}$, U is open and $u \in \mathcal{D}'(U)$ is such that $P(D)u \in C^{\infty}(U)$, then $u \in C^{\infty}(U)$

Proof. Let $V \subset\subset U$ an arbitrary open subset. It suffices to show $u \in C^{\infty}(V)$. Let $\zeta \in C_0^{\infty}(U)$, $\zeta = 1$ on V. Then $P(D)(\zeta u) = P(D)u$ in V, and in particular is C^{∞} there. Finally,

$$\zeta u = \zeta u * \delta = \zeta u * P(D)(E) = (P(D)(\zeta u)) * E$$

and therefore

 $sing\ support\ (\zeta u) \subset sing\ support\ (P(D)(\zeta u)) + \{0\} = sing\ support\ (P(D)(\zeta u))$

But we know that $sing \, support \, (P(D)(\zeta u))$ is disjoint from V, so $sing \, support \, (\zeta u)$ is also disjoint from V, in other words ζu , which equals u in V, is smooth there.

5. The Fourier transform

Definition 5.1. The space of Schwartz functions \mathcal{S} is defined by the requirement that all semi-norms

$$\sup_{x} |x^{\alpha} \partial^{\beta} f|$$

be finite. Convergence in this space means

$$\sup_{x} |x^{\alpha} \partial^{\beta} (f_n - f)| \to 0$$

for all α, β .

The Fourier transform $\mathcal{F}(f) = \hat{f}$ is defined by

$$\hat{f}(\xi) = \int_{\mathbb{R}^n} e^{-ix\cdot\xi} f(x) dx$$

The following are elementary properties which will be checked in class:

Lemma 5.2. Let $f \in \mathcal{S}$, denote $f_{\lambda}(x) = f(\lambda x)$ $(\lambda > 0)$, $\tau_y f(x) = f(x+y)$ $(y \in \mathbb{R}^n)$ and $D_j = \frac{1}{i} \frac{\partial}{\partial x_j}$. Then $\hat{f} \in \mathcal{S}$ and $f \to \hat{f}$ is continuous in the topology of \mathcal{S} . Also,

$$\hat{f}_{\lambda}(\xi) = \frac{1}{\lambda^{n}} \hat{f}(\frac{\xi}{\lambda})$$

$$\mathcal{F}(\tau_{y}f)(\xi) = e^{ix \cdot \xi} \hat{f}(\xi)$$

$$\mathcal{F}(D_{j}f)(\xi) = \xi_{j} \hat{f}(\xi)$$

$$\mathcal{F}(x_{j}f)(\xi) = -D_{j} \hat{f}(\xi)$$

$$\mathcal{F}\left(e^{-\frac{|x|^{2}}{2}}\right)(\xi) = (2\pi)^{n/2} e^{-\frac{|\xi|^{2}}{2}}$$

$$\int f \hat{h} = \int \hat{f}g \quad \text{for all } \hat{f}, \, \hat{h} \in \mathcal{S}$$

These easily imply the inversion formula and Plancherel formulas, which will be proved in class.

Theorem 5.3. Let $f \in \mathcal{S}$. Then

$$f(x) = \frac{1}{(2\pi)^n} \int_{\mathbb{R}^n} e^{ix\cdot\xi} \hat{f}(\xi) d\xi$$

Also,

$$\int_{\mathbb{R}^n} f(x)\overline{g}(x)dx = \frac{1}{(2\pi)^n} \int_{\mathbb{R}^n} \hat{f}(\xi)\overline{\hat{g}}(\xi)d\xi$$

Definition 5.4. The space of continuous linear functionals $u: \mathcal{S} \to \mathbb{C}$ is the space of tempered distributions \mathcal{S}' . $u \in \mathcal{S}'$ if and only if there exists N and C such that

$$|\langle u, \phi \rangle| \le C \sum_{|\alpha|, |\beta| \le N} \sup_{x} |x^{\alpha} \partial^{\beta}(f)|$$

for all $\phi \in \mathcal{S}$. If $u \in \mathcal{S}'$, then $\hat{u} \in \mathcal{S}'$ is defined by

$$<\hat{u},\phi>=< u,\hat{\phi}>$$

for all $\phi \in \mathcal{S}$.

Example: The constant function $1 \in \mathcal{S}$ and $\hat{1} = (2\pi)^n \delta$.

6. Fractional H^s spaces and the sharp trace theorem

Let $u \in \mathcal{S}$. Since $||D^{\alpha}u||_{L^2(\mathbb{R}^n)}^2 = \frac{1}{(2\pi)^n} ||\xi^{\alpha}\hat{u}||_{L^2(\mathbb{R}^n)}^2$, there exist constants c > 0, C > 0 such that

$$c\sum_{\alpha=k} \|D^{\alpha}u\|_{L^{2}(\mathbb{R}^{n})}^{2} \leq \||\xi|^{k} \hat{u}\|_{L^{2}(\mathbb{R}^{n})}^{2} \leq C\sum_{\alpha=k} \|D^{\alpha}u\|_{L^{2}(\mathbb{R}^{n})}^{2}$$

Thus an equivalent definition of $W^{k,2}$ is

$$H^{k} = \left\{ u \in L^{2} \middle| ||u||_{H^{k}} = \sum_{0 \le l \le k} |||\xi|^{k} \hat{u}||_{L^{2}(\mathbb{R}^{n})} < \infty \right\}$$

We can also define the homogeneous (semi-) norms

$$||u||_{\dot{H}^k} = |||\xi|^k \hat{u}||_{L^2(\mathbb{R}^n)}$$

There are semi-norms because $||u||_{\dot{H}^k} = 0$ does not imply u = 0. Polynomials of degree $\leq k - 1$ have \dot{H}^k norm 0. We can get around this problem by requiring $u \in L^2$ or modding out polynomials.

Let us define H^s for $s \geq 0$, not necessarily an integer:

Definition 6.1. H^s is defined as

$$\left\{u \in L^2 \big| \|u\|_{H^s} = \|u\|_{L^2(\mathbb{R}^n)} + \||\xi|^s \hat{u}\|_{L^2(\mathbb{R}^n)} < \infty\right\}$$

Theorem 6.2. Let $x = (x', x_n) \in \mathbb{R}^{n-1} \times \mathbb{R}$. The following sharp estimate holds for s > 0:

$$||u(x',0)||_{H^{s}(\mathbb{R}^{n-1})} \le C||u||_{H^{1/2+s}(\mathbb{R}^n)}$$

where $u \in \mathcal{S}$, but C is independent of u, thus the trace operator extends as a bounded linear operator from $H^1(\mathbb{R}^n)$ to $H^{1/2}(\mathbb{R}^{n-1})$.

Remark 6.3. This can be modified to show T is bounded from $H^1(U)$ to $H^{1/2}(\partial U)$ for C^1 bounded domains.

Proof. Let $\hat{u}(\xi',0)$ denote the Fourier transform in the first (n-1) variables, with $x_n=0$ kept fixed. and let $\tilde{u}(\xi)$ denote the Fourier transform in all variables. We have

$$\hat{u}(\xi',0) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \tilde{u}(\xi) d\xi_n$$

thus we have the pointwise estimate (Cauchy-Schwarz)

$$\left| |\xi'|^s \hat{u}(\xi',0) \right|^2 \le \left(\frac{1}{2\pi} \right)^2 \int_{-\infty}^{\infty} \frac{|\xi'|^{2s}}{|\xi'|^{1+2s} + |\xi_n|^{1+2s}} d\xi_n \int_{-\infty}^{\infty} \left(|\xi'|^{1+2s} + |\xi_n|^{1+2s} \right) |\tilde{u}(\xi)|^2 d\xi_n$$

Check, using a change of variables, that the first integral is some finite C_s . Now integrate $d\xi'$:

$$\int_{\mathbb{R}^{n-1}} \left| |\xi'|^s \hat{u}(\xi',0) \right|^2 d\xi' \le \left(\frac{1}{2\pi} \right)^2 C_s \int_{\mathbb{R}^n} \left(|\xi'|^{1+2s} + |\xi_n|^{1+2s} \right) |\tilde{u}(\xi)|^2 d\xi \le C \|u\|_{H^{1/2+s}}^2$$

7. The Hardy-Littlewood-Sobolev estimates

Theorem 7.1. Let $1 < \alpha < \infty$ and define

$$Tf(x) = \int_{\mathbb{R}^n} \frac{1}{|x - y|^{\frac{n}{\alpha}}} f(y) dy$$

Let 1 satisfying

$$\frac{1}{q} = \frac{1}{p} + \frac{1}{\alpha} - 1$$

Then Tf(x) is finite for a.e x if $f \in L^p$ and there exists C depending only on n, p, q, α such that

$$||Tf||_{L^q(\mathbb{R}^n)} \le C||f||_{L^p(\mathbb{R}^n)}$$

Before proving this, notice that this says that $\frac{1}{|x-y|^{\frac{n}{\alpha}}}$ behaves as if it were in L^{α} from the point of view of Hausdorff-Young. Also, check that $\alpha = \frac{n}{n-2}$ and $\alpha = \frac{n}{n-1}$ generalize the Sobolev embedding theorem for $W^{2,p}(\mathbb{R}^n)$ and $W^{1,p}(\mathbb{R}^n)$.

Proof. I will follow Hedberg's short proof which depends on the Hardy-Littewood maximal function. Recall

$$Mf(x) = \sup_{r>0} \frac{1}{|B(r)|} \int_{B(x,r)} |f(y)| dy$$

and that there exists C such that

$$||Mf||_{L^p(\mathbb{R}^n)} \le C||f||_{L^p(\mathbb{R}^n)}$$

for all 1 . The proof has 3 steps.

Pick $\delta > 0$ and write

$$|Tf(x)| \le \int_{|x-y| < \delta} \frac{1}{|x-y|^{\frac{n}{\alpha}}} |f(y)| dy + \int_{|x-y| > \delta} \frac{1}{|x-y|^{\frac{n}{\alpha}}} |f(y)| dy$$

= $T_1(x) + T_2(x)$

Step 1. Write

$$|T_1 f(x)| = \sum_{i=0}^{\infty} \int_{\frac{\delta}{2^{i+1}} < |x-y| < \frac{\delta}{2^i}} \frac{1}{|x-y|^{\frac{n}{\alpha}}} |f(y)| dy$$

$$\leq C \delta^{n-\frac{n}{\alpha}} M f(x) = C \delta^{\frac{n}{p} - \frac{n}{q}} M f(x)$$

This follows from the definition of Mf and summing a geometric series. Step 2.

$$|T_2 f(x)| \le C \delta^{-\frac{n}{\alpha} + \frac{n}{p'}} ||f||_{L^p(\mathbb{R}^n)} = C \delta^{-\frac{n}{q}} ||f||_{L^p(\mathbb{R}^n)}$$

This follows from Hölder's inequality and the conditions on p, q.

Step 3. For each x, optimize the choice of δ by making the two upper bounds equal:

$$\delta = \left(\frac{\|f\|_{L^p}}{Mf(x)}\right)^{\frac{p}{n}}$$

so that

$$|Tf(x)| \le C(Mf(x))^{\frac{p}{q}} ||f||_{L^p}^{1-\frac{p}{q}}$$

This implies the result.

8. The fundamental solution of the Schrödinger equation We already know how to solve the heat equation

$$(\frac{\partial}{\partial t} - \Delta)u(t, x) = 0 \text{ if } t > 0$$

with initial conditions u(0,x) = f. It is obtained by convolving in x with

$$\frac{1}{(4\pi t)^{n/2}}e^{\frac{-|x|^2}{4t}}H(t)$$

The Schrödinger equation is

$$\left(\frac{1}{i}\frac{\partial}{\partial t} - \Delta\right)u(t, x) = 0$$

and it is solved by convolving in x with

$$\frac{1}{(4\pi it)^{n/2}}e^{\frac{-|x|^2}{4it}}H(t)$$

We have to decide which square root to use in n is odd. Also, we must prove

$$\lim_{t \to 0} \frac{1}{(4\pi i t)^{n/2}} \int e^{\frac{-|x-y|^2}{4it}} f(y) dy = f(x)$$

for sufficiently nice f. The reason behind this is stationary phase: let $T = \frac{1}{2t}$. In its simplest form, it states

$$\lim_{T \to \infty} T^{\frac{n}{2}} \int e^{iT\frac{|x|^2}{2}} f(x) dx = (2\pi i)^{n/2} f(0)$$

How much regularity we need for f and which square root of i is used will drop out of the proof (next time). We need some facts about the Fourier transform.

9. The method of stationary phase

Theorem 9.1. Let $f \in \mathcal{S}$. Then

$$\lim_{T \to \infty} T^{\frac{n}{2}} \int e^{iT\frac{|x|^2}{2}} f(x) dx = (2\pi i)^{n/2} f(0)$$

where $i^{n/2} = e^{\frac{in\pi}{4}}$.

Proof.

$$\int e^{iT|x|^2} f(x) dx = \lim_{\epsilon \to 0} \int e^{(-\epsilon + iT)\frac{|x|^2}{2}} f(x)$$
$$= (2\pi)^{-n} \lim_{\epsilon \to 0} \int e^{(-\epsilon + iT)\frac{|x|^2}{2}} \hat{f}_{-}(x)$$

Since $f(0) = f_{-}(0)$, we don't have to carry the minus sign.

$$A_{\epsilon} = \int e^{(-\epsilon + iT)\frac{|x|^2}{2}} \hat{f}(x) dx$$
$$= \int \mathcal{F}\left(e^{(-\epsilon + iT)\frac{|x|^2}{2}}\right) (\xi) \hat{f}(\xi) d\xi$$

Now we do the analytic continuation with which we are familiar by now:

$$\mathcal{F}\left(e^{-\frac{|x|^2}{2}}\right) = (2\pi)^{n/2}e^{-\frac{|\xi|^2}{2}}$$
$$\mathcal{F}\left(e^{-\frac{a|x|^2}{2}}\right) = (2\pi)^{n/2}\frac{1}{a^{n/2}}e^{-\frac{|\xi|^2}{2a}}$$

for a>0 and therefore for $\Re a>0$, with the usual branch of the argument function. Take $a=\epsilon-iT$. We get

$$\mathcal{F}\left(e^{(-\epsilon+iT)\frac{|x|^2}{2}}\right) = (2\pi)^{n/2} \frac{1}{(\epsilon-iT)^{n/2}} e^{\frac{-|\xi|^2}{2(\epsilon-iT)}}$$

So

$$A_{\epsilon} = (2\pi)^{n/2} \frac{1}{(\epsilon - iT)^{n/2}} \int e^{\frac{-|\xi|^2}{2(\epsilon - iT)}} \hat{f}(\xi) d\xi$$
$$\to A = (2\pi T^{-1})^{n/2} e^{i\frac{n\pi}{4}} \int e^{\frac{|\xi|^2}{2iT}} \hat{f}(\xi) d\xi$$

EXPOSITORY NOTES ON DISTRIBUTION THEORY, AMSC/MATH 673, FALL 2018 and the quantity in the statement of the theorem,

$$\begin{split} &T^{\frac{n}{2}} \int e^{iT\frac{|x|^2}{2}} f(x) dx \text{ equals} \\ &T^{n/2} (2\pi)^{-n} A \\ &= (2\pi)^{-n/2} e^{i\frac{n\pi}{4}} \int e^{\frac{|\xi|^2}{2iT}} \hat{f}(\xi) d\xi \\ &= \left((2\pi)^{n/2} e^{i\frac{n\pi}{4}} \right) \frac{1}{(2\pi)^n} \int \left(1 + O(\frac{|\xi|^2}{T}) \right) \hat{f}(\xi) d\xi \to \left((2\pi)^{n/2} e^{i\frac{n\pi}{4}} \right) f(0) \end{split}$$

by the dominated convergence theorem, provided $\int (1+|\xi|^2)|f(\xi)|d\xi \le C$. This tells us how much regularity we need for this proof to work. We used $|e^{ix}-1| \le C|x|$.

There is an obvious generalization by Taylor expanding $e^{\frac{|\xi|^2}{2iT}}$.

10. ESTIMATES FOR THE SCHRÖDINGER EQUATION

In this section we look at solutions to Schrödinger equation

$$\left(\frac{1}{i}\frac{\partial}{\partial t} - \Delta\right)u(t, x) = 0$$

$$u(0, x) = f_0(x)$$

where, for the time being, $f_0 \in \mathcal{S}(\mathbb{R}^n)$. The solution can be written (formally, if you wish, or using the Fourier transform) as $u = e^{it\Delta} f_0$. One way of writing down the solution (which is unique) is

$$u(t,x) = \frac{e^{-n\pi i/4}}{(4\pi t)^{n/2}} \int_{\mathbb{R}^n} e^{\frac{-|x-y|^2}{4it}} f_0(y) dy$$

which gives

$$||u(t,\cdot)||_{L^{\infty}} \le \frac{1}{(4\pi t)^{n/2}} ||f_0||_{L^1}$$

Another way of representing the solution is

$$\hat{u}(t,\xi) = e^{-it|\xi|^2} \hat{f}_0(\xi)$$

From here we get

$$||u(t,\cdot)||_{L^2} = ||f_0||_{L^2}$$

Recall the Riesz-Thorin complex interpolation theorem:

Theorem 10.1. Let $1 \le p_1, p_2, q_1, q_2 \le \infty$. Let T be a linear operator (initially defined on a dense subset) such that

$$||T(f)||_{L^{q_1}} \le C_1 ||f||_{L^{p_1}}$$
$$||T(f)||_{L^{q_2}} \le C_1 ||f||_{L^{p_2}}$$

Let $0 \le \theta \le 1$, and define

$$\frac{1}{p} = \frac{\theta}{p_1} + \frac{1 - \theta}{p_2}$$

$$\frac{1}{q} = \frac{\theta}{q_1} + \frac{1 - \theta}{q_2}$$

$$C = C_1^{\theta} C_2^{1 - \theta}$$

Then

$$||T(f)||_{L^q} \le C||f||_{L^p}$$

for all $f \in L^p$.

Applying this to $T(f_0) = u(t, \cdot)$ we get, for all $2 \le q \le \infty$,

$$||u(t,\cdot)||_{L^q} \le \frac{1}{(4\pi t)^{\frac{n(q-2)}{2q}}} ||f_0||_{L^{q'}}$$
(3)

This leads to an example of a Strichartz estimate.

Theorem 10.2. Let

$$q = \frac{2(n+2)}{n}$$

Then

$$||u||_{L^q(\mathbb{R}^{n+1})} \le C||f_0||_{L^2(\mathbb{R}^n)}$$

Proof. By duality, it suffices to show

$$\left| \int \left(e^{it\Delta} f_0 \right)(x) G(t, x) dt dx \right| \le C \|f_0\|_{L^2(\mathbb{R}^n)} \|G\|_{L^{q'}(\mathbb{R}^{n+1})}$$

This is equivalent to showing

$$A = |\int f_0(x) \left(e^{it\Delta} G(t, \cdot) \right) (x) dt dx| \le C ||f_0||_{L^2(\mathbb{R}^n)} ||G||_{L^{q'}(\mathbb{R}^{n+1})}$$

which, in turn, is equivalent to

$$B = \| \int e^{it\Delta} G(t, \cdot) dt \|_{L^2(\mathbb{R}^n)} \le C \| G \|_{L^{q'}(\mathbb{R}^{n+1})}$$
 (4)

Doubling, this is the same as

$$B^{2} = \left| \int \left(\int e^{it\Delta} G(t, \cdot) dt \right) \left(\overline{\int e^{is\Delta} G(s, \cdot) ds} \right) dx \right| \leq C^{2} \|G\|_{L^{q'}(\mathbb{R}^{n+1})}^{2}$$

The LHS is

$$B^{2} = \left| \int \int \int \left(e^{i(t-s)\Delta} G(t, \cdot) \right) \overline{G(s, x)} dt ds dx \right|$$

By Fubini and Hölder's inequality, B^2 is dominated by

$$D = \int \int \|e^{i(t-s)\Delta}G(t,\cdot)\|_{L^q(\mathbb{R}^n)} \|G(s,\cdot)\|_{L^{q'}(\mathbb{R}^n)} dt ds$$

Now apply (3) with $q = \frac{2(n+2)}{n}$ so that $\frac{n(q-2)}{2q} = \frac{n}{n+2}$.

$$||e^{i(t-s)\Delta}G(t,\cdot)||_{L^q(\mathbb{R}^n)} \le \frac{C}{|t-s|^{\frac{n}{n+2}}}||G(t,\cdot)||_{L^{q'}(\mathbb{R}^n)}$$

so that

$$D \le \int \int \frac{C}{|t-s|^{\frac{n}{n+2}}} \|G(t,\cdot)\|_{L^{q'}(\mathbb{R}^n)} \|G(s,\cdot)\|_{L^{q'}(\mathbb{R}^n)} dt ds$$

Now,
$$q' = \frac{2(n+2)}{n+4}$$
 and $\frac{1}{q'} + \frac{n}{n+2} - 1 = \frac{1}{q}$ so, by HLS

$$\|\int \frac{1}{|t-s|^{\frac{n}{n+2}}} \|G(s,\cdot)\|_{L^{q'}(\mathbb{R}^n)} ds\|_{L^q(dt)} \le C \|G(\cdot,\cdot)\|_{L^{q'}(\mathbb{R}^{n+1})}$$
 (5)

so, finally,

$$D \le \|G(\cdot, \cdot)\|_{L^{q'}(\mathbb{R}^{n+1})}^2$$

We have actually also found an estimate for the inhomogeneous equation

$$(\frac{1}{i}\frac{\partial}{\partial t} - \Delta)u(t, x) = F(t, x) \ (t > 0, x \in \mathbb{R}^n)$$

$$u(0, x) = 0$$

The solution is given by Duhamel's formula

$$u(t,x) = i \int_0^t e^{i(t-s)\Delta} F(s,\cdot) ds$$

and we have

Proposition 10.3. Let $q = \frac{2(n+2)}{n}$. There exists C such that

$$||u||_{L^q(dtdx)} \le C||F||_{L^{q'}(dtdx)}$$

Proof.

$$||u||_{L^{q}(dtdx)} = ||\int_{0}^{t} e^{i(t-s)\Delta} F(s,\cdot) ds||_{L^{q}(dtdx)}$$

$$\leq ||\int_{0}^{t} ||e^{i(t-s)\Delta} F(s,\cdot)||_{L^{q}(dx)} ds||_{L^{q}(dt)}$$

$$\leq C||\int_{0}^{\infty} \frac{1}{|t-s|^{\frac{n}{2}(1-\frac{2}{q})}} ||F(s,\cdot)||_{L^{q'}(dx)} ds||_{L^{q}(dt)}$$

$$\leq C||F||_{L^{q'}(dtdx)}$$

by HLS, just as in (5).

Remark 10.4. The easiest explanation for the exponent $q = \frac{2(n+2)}{n}$ is scaling. There is a much more subtle reason (the "Knapp counterexample"). On the Fourier transform side, (4) reads

$$\|\hat{G}(|\xi|^2, \xi)\|_{L^2(d\xi)} \le C\|G\|_{L^{q'}(\mathbb{R}^{n+1})} \tag{6}$$

This is an instance of the Stein-Tomas restriction theorem. It is clear that the Fourier transform of any L^1 function has a well-defined restriction to a hypersurface (because it is continuous). It is also clear that the Fourier transform of general L^2 functions don't have well-defined restrictions to a hypersurface (because they are just L^2). We have just proved that any $L^{q'}$ function has a well-defined restriction to the hyperboloid. The Knapp counterexample shows that if (6) holds for all G such that \hat{G} is supported in the unit ball, then $q' \leq \frac{2(n+2)}{n+4}$. Let ϕ be a fixed even bump function, $\delta > 0$ small, and take

$$\hat{G}(\tau,\xi) = \phi(\frac{\tau}{\delta^2})\phi(\frac{\xi_1}{\delta})\cdots\phi(\frac{\xi_n}{\delta})$$

then

$$G(t,x) = \frac{1}{(2\pi)^{n+1}} \delta^{n+2} \hat{\phi}(\delta^2 t) \hat{\phi}(\delta x_1) \cdots \hat{\phi}(\delta x_n)$$

With this choice, the LHS of (6) is $\sim \delta^{n/2}$ (draw a picture), while the RHS is $\sim \delta^{\frac{n+2}{q}}$ so $q \geq \frac{2(n+2)}{n}$.