AMSC/CMSC 666

NUMERICAL ANALYSIS I

HOMEWORK # 3 (Pbs 1-3 due Tue Oct 22, Pbs 4-7 due Thu Oct 31)

1 (20 pts). Conjugate gradient. Consider the two-point boundary value problem in (0,1):

$$-u'' + u = f, u(0) = u(1) = 0. (1)$$

- (a) Let $\{x_i\}_{i=0}^{N+1}$ be a uniform partition of (0,1) with meshsize h=1/(N+1). Derive the discrete equations resulting from applying centered differences to (1). Write the equations in matrix form $\mathbf{A}\mathbf{U} = \mathbf{F}$, where $\mathbf{U} = (U_i)_{i=1}^N$ is the vector of nodal values and $\mathbf{F} = (f(x_i))_{i=1}^N$.
- (b) Show that **A** is strictly diagonally dominant, symmetric and positive definite.
- (c) Write a MATLAB function [x,k] = cg(A,b,x0,tol) which implements the CG method for an $n \times n$ symmetric and positive definite matrices A, right-hand side b, and starting value x0. The program should compute the 2-norm of the residual and stop when such a norm is less than a given tolerance tol, giving the current iterate vector x and number of iterations k.
- (d) Write a MATLAB function [x,k] = gradient(A,b,x0,tol) which implements the steepest descent (or gradient) method. The arguments have the same meaning as in (c).
- (e) Let f be the right-hand side of (1) corresponding to the exact solution $u(x) = \sin(\pi x) \sin(3\pi x)$. Run the functions cg and gradient for $N = 10, 20, 40, \times 0=0$ and tol = 10^{-8} . Plot the computed solutions together with u(x). Plot also the log of the 2-norm of the residual in terms of the log of the number of steps, and draw conclusions.
- 2 (15 pts). Singular matrices. Let **A** be a symmetric positive semi-definite matrix. Let the linear system $\mathbf{A}\mathbf{x} = \mathbf{b}$ be consistent, that is, **b** belongs to the range of **A** and thus solution exists. Prove that with initial guess $\mathbf{x}^{(0)} = 0$, the conjugate gradient method (CG) is guaranteed to produce a solution without component in the kernel of **A**. To this end proceed as follows.
- (a) Show that the singular value decomposition of **A** can be written as $\mathbf{A} = \mathbf{U}\Sigma\mathbf{U}^T$ with Σ diagonal, and study the properties of Σ .
- (b) Derive a system equivalent to $\mathbf{A}\mathbf{x} = \mathbf{b}$ for $\hat{\mathbf{x}} = \mathbf{U}\mathbf{x}$ and $\hat{\mathbf{b}} = \mathbf{U}\mathbf{b}$, and study the structure of $\hat{\mathbf{b}}$.
- (c) Show that CG with $\mathbf{x}^{(0)} = 0$ is equivalent to CG for a symmetric positive definite matrix with zero initial guess.
- 3 (10 pts). Preconditioning. Let $\mathbf{A}, \mathbf{B} \in \mathbb{R}^{n \times n}$ be symmetric and positive definite matrices, and let $\mathbf{b} \in \mathbb{R}^n$. Consider the quadratic function $Q(\mathbf{x}) = \frac{1}{2}\mathbf{x}^T\mathbf{A}\mathbf{x} \mathbf{x}^T\mathbf{b}$ for $\mathbf{x} \in \mathbb{R}^n$ and a descent method to approximate the solution of $\mathbf{A}\mathbf{x} = \mathbf{b}$:

$$\mathbf{x}_{k+1} = \mathbf{x}_k + \alpha_k \mathbf{d}_k.$$

- (a) Formulate the steepest descent (or gradient) method and write a pseudocode which implements it.
- (b) Let \mathbf{B}^{-1} be a preconditioner of \mathbf{A} . Show how to modify the steepest descent method to work for $\mathbf{B}^{-1}\mathbf{A}\mathbf{x} = \mathbf{B}^{-1}\mathbf{b}$, and write a pseudocode. Note that $\mathbf{B}^{-1}A$ may not be symmetric.
- 4 (10 pts). Quadratic convergence. Let $F: D \subset \mathbb{R}^n \to \mathbb{R}^n$ be a map of class C^2 with a zero $\mathbf{x}_* \in D$. Show that if F satisfies $F''(\mathbf{x}_*)\langle \mathbf{h}, \mathbf{h} \rangle \neq 0$ for all $\mathbf{h} \neq 0$, $\mathbf{h} \in \mathbb{R}^n$, then the convergence of Newton method is at most quadratic, namely

$$\frac{\|\mathbf{x}_{k+1} - \mathbf{x}_*\|}{\|\mathbf{x}_k - \mathbf{x}_*\|^2} \ge C \ne 0 \quad \forall k \ge 0.$$

5 (15 pts). Shamanskii method. Let $F: \mathbb{R}^n \to \mathbb{R}^n$ have a Lipschitz continuous derivative and suppose $F(\mathbf{x}^*) = 0$ and $F'(\mathbf{x}^*)$ is nonsingular. Consider the following modification of Newton's method in which F' need be evaluated only every other iterate:

$$\mathbf{x}_{k+1} = \begin{cases} \mathbf{x}_k - F'(\mathbf{x}_k)^{-1} F(\mathbf{x}_k), & k \text{ even,} \\ \mathbf{x}_k - F'(\mathbf{x}_{k-1})^{-1} F(\mathbf{x}_k), & k \text{ odd.} \end{cases}$$

Set $\mathbf{y}_k := \mathbf{x}_{2k}$ and prove that the combined method has order of convergence at least 3. To this end derive the expression

$$\mathbf{y}_k = G(\mathbf{y}_{k-1}) - F'(\mathbf{y}_{k-1})^{-1} F(G(\mathbf{y}_{k-1})),$$

and recall that Newton's function $G(\mathbf{x}) = \mathbf{x} - F'(\mathbf{x})^{-1}F(\mathbf{x})$ satisfies $||G(\mathbf{x}) - \mathbf{x}^*|| \le C||\mathbf{x} - \mathbf{x}^*||^2$. Use this result to determine the order of convergence of the original method.

6 (15 pts). Jacobi-Newton method. The Jacobi iteration for solving systems of linear equations can also be applied to nonlinear systems. For the $n \times n$ system $F(\mathbf{x}) = (f_i(\mathbf{x}))_{i=1}^n = 0$ with $F \in C^2$, the iteration reads: for $k \ge 0$ solve

$$f_i(x_1^k, \dots, x_{i-1}^k, x_i^{k+1}, x_{i+1}^k, \dots, x_n^k) = 0, \quad 0 \le i \le n.$$

Thus each iteration involves solving n scalar nonlinear equations.

(a) If we use one iteration of Newton's method to solve each of these equations we get the Jacobi-Newton method. Show that one such iteration reads

$$\mathbf{x}_{k+1} = \mathbf{x}_k - \mathbf{D}(\mathbf{x}_k)^{-1} F(\mathbf{x}_k) = G(\mathbf{x}_k), \tag{2}$$

where $\mathbf{D}(\mathbf{x})$ stands for the diagonal of $F'(\mathbf{x})$.

- (b) Conversely, we can first formulate a Newton step and then perform one Jacobi iteration for the corresponding linear system. Show that the resulting Newton-Jacobi method coincides with (2).
- (c) Determine under what conditions this algorithm converges, and under what conditions does it superlinearly and quadratically.

7 (15 pts). Newton method. This is about experimenting with the Newton's method and some of its variants.

- (a) Write a simple MATLAB program Newton(F,DF,x,tol,miter) to solve an n-by-n nonlinear system of equations $F(\mathbf{x}) = 0$ by the Newton's Method. The input parameters are the functions F its Jacobian DF, the starting point x, an absolute error tolerance tol, and the maximum number of iterations miter. Solve the resulting linear systems using the MATLAB command "\".
- (b) The following system has four zeros in the domain $(-4,4) \times (-4,4)$

$$f(x,y) = x^2 + xy^3 - 9 = 0,$$
 $g(x,y) = 3x^2y - y^3 - 4 = 0.$

Use the command contour to plot the zero level sets of both f and g in the same picture to determine reasonable initial guesses (use help contour to find out information about the command). Use the commands hold on and hold off to produce this picture. Use a syntax such as:

```
x = -4:0.1:4;
y = -4:0.1:4;
[X,Y] = meshgrid(x, y);
contour(x, y, X.^2+X.*Y.^3-9, [0 0])
```

- (c) Use Newton to approximate the four zeros with tol= 10^{-7} . Determine the number of iterations and the rate of convergence. To this end show that $\|\mathbf{x}_{k+1} \mathbf{x}_k\|/\|\mathbf{x}_k \mathbf{x}^*\| \to 1$ for superlinear convergent methods.
- (d) Write a Matlab code Newdiff that replaces the Jacobian with forward differences with $h = 10^{-7}$. Repeat (b) and compare results. You can use the code nsol.
- (e) Repeat (b) with the Broyden method, which is implemented in brsol.m. Both codes nsol and brsol.m are available from the SIAM website https://archive.siam.org/books/kelley/fr16/index.php