

# Lecture 3: Geometric Graph Embeddings: Isometric and Nearly Isometric Embeddings of Geometric Graphs.

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# Embeddings with Full Data

## Problem Statement and Ambiguities

### Main Problem

*Isometric Embedding:* Given the set of all squared-distances  $\{d_{ij}^2; 1 \leq i, j \leq n\}$  find a dimension  $d$  and a set of  $n$  points  $\{y_1, \dots, y_n\} \subset \mathbb{R}^d$  so that  $\|y_i - y_j\|^2 = d_{ij}^2, 1 \leq i, j \leq n$ .

### Main Problem

*Nearly Isometric Embedding:* Given the set of all squared-distances  $\{d_{ij}^2; 1 \leq i, j \leq n\}$  find a dimension  $d$  and a set of  $n$  points  $\{y_1, \dots, y_n\} \subset \mathbb{R}^d$  so that  $\|y_i - y_j\|^2 \approx d_{ij}^2, 1 \leq i, j \leq n$ .

Note the set of points is unique up to rigid transformations: translations, rotations and reflections:  $\mathbb{R}^d \times O(d)$ . This means two sets of  $n$  points in  $\mathbb{R}^d$  have the same pairwise distances if and only if one set is obtained from the other set by a combination of rigid transformations.

# Isometric Embeddings with Full Data

Converting pairwise distances into the Gram matrix

Let  $S = (S_{i,j})_{1 \leq i,j \leq n}$  denote the  $n \times n$  symmetric matrix of squared pairwise distances:

$$S_{i,j} = d_{i,j}^2, S_{i,i} = 0$$

Denote by  $\mathbf{1}$  the  $n$ -vector of 1's (the Matlab `ones(n,1)`). Let  $\nu = (\|y_i\|^2)_{1 \leq i \leq n}$  denote the unknown  $n$ -vector of squared-norms. Finally, let  $G = (\langle y_i, y_j \rangle)_{1 \leq i,j \leq n}$  denote the Gram matrix of scalar products between  $y_i$  and  $y_j$ .

We can remove the translation ambiguity by fixing the center:

$$\sum_{i=1}^n y_i = 0$$

# Isometric Embeddings with Full Data

## Converting pairwise distances into the Gram matrix

Expand the square:

$$d_{i,j}^2 = \|y_i - y_j\|^2 = \|y_i\|^2 + \|y_j\|^2 - 2\langle y_i, y_j \rangle \Rightarrow 2\langle y_i, y_j \rangle = \|y_i\|^2 + \|y_j\|^2 - d_{i,j}^2$$

Rewrite the system as:

$$2G = \nu \cdot \mathbf{1}^T + \mathbf{1} \cdot \nu^T - S \quad (*)$$

The center condition reads:  $G \cdot \mathbf{1} = 0$ , which implies:

$$0 = \nu \cdot \mathbf{1}^T \mathbf{1} + \mathbf{1} \cdot \nu^T \mathbf{1} - S \cdot \mathbf{1} \Rightarrow 0 = 2n\nu^T \cdot \mathbf{1} - \mathbf{1}^T \cdot S \cdot \mathbf{1}$$

Let  $\rho := \nu^T \cdot \mathbf{1} = \sum_{i=1}^n \|y_i\|^2$ . We obtain:

$$\rho = \frac{1}{2n} \mathbf{1}^T \cdot S \cdot \mathbf{1} = \frac{1}{2n} \sum_{i=1}^n \sum_{j=1}^n d_{i,j}^2$$

$$\nu = \frac{1}{n} (S \cdot \mathbf{1} - \rho \mathbf{1}) = \frac{1}{n} (S - \rho I) \cdot \mathbf{1}$$

that you substitute back into (\*).

# Isometric Embeddings with Full Data

Converting pairwise squared-distances into the Gram matrix: Algorithm

## Algorithm (Alg 1)

*Input: Symmetric matrix of squared pairwise distances  $S = (d_{i,j}^2)_{1 \leq i,j \leq n}$ .*

① *Compute:*

$$\rho = \frac{1}{2n} \mathbf{1}^T \cdot S \cdot \mathbf{1} = \frac{1}{2n} \sum_{i=1}^n \sum_{j=1}^n d_{i,j}^2$$

② *Set:*

$$\nu = \frac{1}{n} (S \cdot \mathbf{1} - \rho \mathbf{1}) = \frac{1}{n} (S - \rho I) \cdot \mathbf{1}$$

③ *Compute:*

$$G = \frac{1}{2} \nu \cdot \mathbf{1}^T + \frac{1}{2} \mathbf{1} \cdot \nu^T - \frac{1}{2} S = \frac{1}{2n} (S - \rho I) \mathbf{1} \cdot \mathbf{1}^T + \frac{1}{2n} \mathbf{1} \cdot \mathbf{1}^T (S - \rho I) - \frac{1}{2} S.$$

*Output: Symmetric Gram matrix  $G$*

# Isometric/Nearly Isometric Embeddings with Full Data

## Factorization of the $G$ matrix

In the absence of noise (i.e. if  $S_{i,j}$  are indeed the Euclidean distances), the Gram matrix  $G$  should have rank  $d$ , the minimum dimension of the isometric embedding.

If  $S$  is noisy, then  $G$  has approximate rank  $d$ .

To find  $d$  and  $Y$ , the matrix of coordinates, perform the eigendecomposition:

$$G = Q\Lambda Q^T$$

where  $\Lambda$  is the diagonal matrix of eigenvalues, ordered monotonically decreasing. Choose  $d$  as the number of significant positive eigenvalues (i.e. truncate to zero the negative eigenvalues, as well as the smallest positive eigenvalues). Note  $G$  has always at least one zero eigenvalue:  $\text{rank}(G) \leq n - 1$ .

# Isometric Embeddings with Full Data

## Factorization of the $G$ matrix

Then we obtain an approximate factorization of  $G$  (exact in the absence of noise):

$$G \approx Q_1 \Lambda_1 Q_1^T$$

where  $Q_1$  is the  $n \times d$  submatrix of  $Q$  containing the first  $d$  columns.

Set  $Y = \Lambda_1^{1/2} Q_1^T$ , so that  $G \approx Y^T Y$ .

The  $d \times n$  matrix  $Y$  contains the embedding vectors  $y_1, \dots, y_n$  as columns:

$$Y = [y_1 | y_2 | \dots | y_n].$$

**Question:** What optimization problem is solved by the eigendecomposition? We shall discuss it after Algorithm 2.

# Isometric Embeddings with Full Data

Gram matrix factorization: Algorithm

## Algorithm (Alg 2)

*Input: Symmetric  $n \times n$  Gram matrix  $G$ .*

- ① *Compute the eigendecomposition of  $G$ ,  $G = Q\Lambda Q^T$  with diagonal of  $\Lambda$  sorted in a descending order;*
- ② *Determine the number  $d$  of significant positive eigenvalues;*
- ③ *Partition*

$$Q = [Q_1 \quad Q_2] \quad , \text{ and } \Lambda = \begin{bmatrix} \Lambda_1 & 0 \\ 0 & \Lambda_2 \end{bmatrix}$$

*where  $Q_1$  contains the first  $d$  columns of  $Q$ , and  $\Lambda_1$  is the  $d \times d$  diagonal matrix of significant positive eigenvalues of  $G$ .*

- ④ *Compute:*

$$Y = \Lambda_1^{1/2} Q_1^T$$

*Output: Dimension  $d$  and  $d \times n$  matrix  $Y$  of vectors  $Y = [y_1 | \cdots | y_n]$*



# Optimality of Eigendecompositions

Assume  $A \in \mathbb{R}^{n \times n}$  is a symmetric matrix,  $A = A^T$ .

Fix  $1 \leq d \leq n$ . Consider the following problem: Find  $d$  vectors  $\hat{f}_1, \dots, \hat{f}_d \in \mathbb{R}^n$  that minimize

$$J = \underset{\{f_1, \dots, f_d\} \subset \mathbb{R}^n}{\text{minimize}} \quad \|A - \sum_{k=1}^d f_k f_k^T\|_F \quad (1.1)$$

where the Frobenius norm is defined by  $\|X\|_F = \left(\sum_{1 \leq i, j \leq n} |X_{i,j}|^2\right)^{1/2}$ .

*Claim 1:* Without loss of generality (W.L.O.G.) we can assume  $\{\hat{f}_1, \dots, \hat{f}_d\}$  is orthogonal, i.e.,  $\langle \hat{f}_i, \hat{f}_j \rangle = 0$  for  $i \neq j$ .

Why?

$$I = \underset{\{g_1, \dots, g_d\} \text{ orthogonal set}}{\text{minimize}} \quad \|A - \sum_{k=1}^d g_k g_k^T\|_F \quad (1.2)$$

i) Obviously:  $J \leq I$  because less constraints in (1.1).

# Optimality of Eigendecompositions

## Equivalence between $I$ and $J$

ii) For the converse inequality  $I \leq J$ , we proceed as follows.

Let  $\{\hat{f}_1, \dots, \hat{f}_d\}$  be an optimizer of (1.1). Consider the eigenfactorization of matrix  $R = \sum_{k=1}^d \hat{f}_k \hat{f}_k^T$ . Say  $R = ED_1R^T$  where  $R$  is the  $n \times d$  matrix formed by the first  $d$  eigenvectors of  $R$  and  $D_1$  is the  $d \times d$  matrix of top  $d$  eigenvalues of  $R$ . Note that  $R$  has rank at most  $d$  (its range is the span of  $d$  vectors), hence at most  $d$  eigenvalues are nonzero; the other  $n - d$  eigenvalues are 0. Let  $\{e_1, \dots, e_d\}$  be the normalized eigenvectors of  $R$  that are columns in  $E$ , so that  $E = [e_1 | \dots | e_d]$ . Let  $\lambda_1, \dots, \lambda_d$  be the top eigenvalues of  $R$  that are also on the diagonal of  $D_1$ . Then, for  $g_1 = \sqrt{\lambda_1}e_1, \dots, g_d = \sqrt{\lambda_d}e_d$ , we have  $R = g_1g_1^T + g_2g_2^T + \dots + g_dg_d^T$ . On the other hand  $\langle g_i, g_j \rangle = \sqrt{\lambda_i\lambda_j}\langle e_i, e_j \rangle = 0$ , where the last equality comes from the fact that we the eigenvectors  $\{e_1, \dots, e_d\}$  were chosen orthonormal. It follows  $\{g_1, \dots, g_d\}$  is a feasible set for problem (1.2). Hence  $I \leq \|A - R\|_F = J$ .

# Optimality of Eigendecompositions

## Reduction to one vector

Assume  $(\hat{f}_1, \dots, \hat{f}_d)$  is an orthogonal set minimizer in (1.2). Then  $\hat{f}_d$  is the minimizer of

$$H = \underset{f \in \mathbb{R}^n}{\text{minimize}} \quad \|A - \sum_{k=1}^{d-1} \hat{f}_k \hat{f}_k^T - ff^T\|_F \quad (1.3)$$

*Why?*: Similarly,  $J \leq H$  (because less constraints). And  $H \leq I$  (because less constraints).

Consequence: we can solve the sequential optimization problems, i.e., peel-off one rank one at a time:

$$\underset{f \in \mathbb{R}^n}{\text{minimize}} \quad \|A_k - ff^T\|_F \quad (1.4)$$

where  $A_0 = A$  and  $A_k = A_{k-1} - \hat{f}_k \hat{f}_k^T$ .

# Optimality of Eigendecompositions

## Solution for one vector optimization

We are left to solve the minimization of  $\|A - xx^T\|_F$  for a symmetric matrix  $A = A^T \in \mathbb{R}^{n \times n}$  and  $x \in \mathbb{R}^n$ .

Expand the Frobenius norm:

$$\begin{aligned} \|A - xx^T\|_F^2 &= \text{trace}((A - xx^T)(A - xx^T)) = \text{trace}(A^2) - 2\text{trace}(Axx^T) + \\ &\quad + \text{trace}(xx^Txx^T) = \|A\|_F^2 - 2\langle Ax, x \rangle + \|x\|^4 \end{aligned}$$

(check!)

Let  $x = t \cdot e$  where  $t > 0$  is a scalar and  $e \in \mathbb{R}^n$  is a unit vector  $\|e\| = 1$ , i.e.,  $t = \|x\|$  and  $e = \frac{x}{\|x\|}$ . Then

$$\|A - xx^T\|_F^2 = \|A\|_F^2 - 2t^2\langle Ae, e \rangle + t^4$$

Minimization over  $t$  produces a bi-quadratic problem whose solution is

$$\hat{t} = \sqrt{\max(0, \langle Ae, e \rangle)}$$

# Optimality of Eigendecompositions

Solution for one vector optimization - 2

Substitute back  $\hat{f}$  into  $\|A - xx^T\|_F^2$ :

$$\|A - xx^T\|_F^2 = \begin{cases} \|A\|_F^2 & \text{if } \langle Ax, x \rangle < 0 \\ \|A\|_F^2 - (\langle Ax, x \rangle)^2 & \text{if } \langle Ax, x \rangle \geq 0 \end{cases}$$

Finally, consider the optimization problem

$$\begin{aligned} & \text{maximize} && \langle Ae, e \rangle \\ & e \in \mathbb{R}^n, \|e\| = 1 \end{aligned}$$

Use Lagrange multiplier technique to solve it:

$$L(e, \lambda) = \langle Ae, e \rangle - \lambda(\langle e, e \rangle - 1) \Rightarrow \nabla L = 0$$

Obtain:

$$Ae - \lambda e = 0 \quad , \quad \langle e, e \rangle - 1 = 0$$

Hence  $(\lambda, e)$  is an eigenpair. Solution:  $\hat{e}$  is the *principal unit-norm* eigenvector of matrix  $A$ .

# Optimality of Eigendecompositions

## Summary

### Theorem

Let  $A = A^T \in \mathbb{R}^{n \times n}$  be a symmetric matrix. Fix an integer  $1 \leq d \leq n$ . Let  $\{(\lambda_k, e_k); 1 \leq k \leq d\}$  be the top  $d$  eigenpairs, i.e.  $Ae_k = \lambda_k e_k$ ,  $\|e_k\| = 1$  and  $\{\lambda_1, \dots, \lambda_d\}$  the largest  $d$  eigenvalues. An optimizer of the problem:

$$J = \underset{\{f_1, \dots, f_d\} \subset \mathbb{R}^n}{\text{minimize}} \quad \|A - \sum_{k=1}^d f_k f_k^T\|_F \quad (1.5)$$

is given by  $\hat{f}_k = \sqrt{\max(0, \lambda_k)} e_k$ ,  $1 \leq k \leq d$ . Equivalently, the optimizer of the problem

$$J = \underset{\substack{R = R^T \in \mathbb{R}^{n \times n} \\ \text{rank}(R) \leq d \\ R \geq 0}}{\text{minimize}} \quad \|A - R\|_F \quad (1.6)$$

is given by  $R = \sum_{k=1}^d \max(0, \lambda_k) e_k e_k^T$ .

# Review of the Eigenproblems Theory

## Definitions

Recall: An *eigenpair*  $(\lambda, v)$  of a square matrix  $A \in \mathbb{C}^{n \times n}$  is pair composed of a non-zero vector  $v$  (called *eigenvector*) and a scalar  $\lambda$  (called *eigenvalue*) that satisfy  $Av = \lambda v$ . In general, we normalize  $v$  so that  $\|v\| = 1$ .

Any  $n \times n$  matrix admits exactly  $n$  (maybe complex and repeated) eigenvalues. They all are roots of the *characteristic polynomial*,  $P_A(z) = \det(zI - A)$ . If  $A$  admits  $n$  linearly independent eigenvectors  $\{v_1, \dots, v_n\}$  then  $A$  *diagonalizes*, that is, with  $V = [v_1 | v_2 | \dots | v_n]$  and  $\Lambda = \text{diag}(\lambda_1, \dots, \lambda_n)$ ,  $A = V\Lambda V^{-1}$ .

It is a remarkable fact that all symmetric matrices ALWAYS diagonalize. In fact more can be said about these matrices.

First, a bit of terminology:

A real matrix  $A \in \mathbb{R}^{n \times n}$  is said *symmetric*, or *self-adjoint*, if  $A = A^T$ .

A complex matrix  $A \in \mathbb{C}^{n \times n}$  is said *hermitian*, or *self-adjoint*, if  $A = \bar{A}^T$  (i.e., complex-conjugate and transpose). In general, we denote  $A^* = \bar{A}^T$ .

# Review of the Eigenproblems Theory

## Matrix Factorization

### Theorem (Factorization of self-adjoint matrices)

Assume  $A = A^*$  (either real or complex matrix).

- 1 All eigenvalues of  $A$  are real, i.e., the characteristic polynomial  $p_A(z)$  has exactly  $n$  real zeros.
- 2 There exists an orthonormal basis  $\{e_1, e_2, \dots, e_n\}$  composed of eigenvectors associated to eigenvalues  $\lambda_1, \dots, \lambda_n$  so that, with  $E = [e_1 | e_2 | \dots | e_n]$  and  $\Lambda = \text{diag}(\lambda_1, \dots, \lambda_n)$ ,

$$A = E\Lambda E^*$$

Furthermore, if  $A$  is a real matrix then all eigenvectors have real entries.

- 3 For every  $x, y \in \mathbb{C}^n$ ,  $\langle Ax, y \rangle = \langle x, Ay \rangle$ , and  $\langle Ax, x \rangle \in \mathbb{R}$  is always a real number



# Review of the Eigenproblems Theory

## Matrix Factorization

The last property allows us to define a *non-negative matrix*, also called *positive semi-definite* (PSD) matrix  $A$ , that matrix so that:  $A = A^*$  (i.e., it is self-adjoint), and for every  $x \in \mathbb{C}^n$ ,  $\langle Ax, x \rangle \geq 0$ . We denote this by  $A \geq 0$ . If, in addition, the matrix satisfies, for every  $x \in \mathbb{C}^n$ ,  $x \neq 0$ ,  $\langle Ax, x \rangle > 0$  then  $A$  is said *positive definite* (or just positive). We denote this by  $A > 0$ .

Given the factorization in this theorem, we conclude that:

### Corollary

Assume  $A = A^*$ . Then,

- 1  $A \geq 0$  if and only if all eigenvalues satisfy  $\lambda \geq 0$ .
- 2  $A > 0$  if and only if all eigenvalues satisfy  $\lambda > 0$ .

As a side remark: If a matrix  $A \in \mathbb{C}^{n \times n}$  satisfies, for every  $x \in \mathbb{C}^n$ ,  $\langle Ax, x \rangle \in \mathbb{R}$  then  $A = A^*$ .

# Review of the Eigenproblems Theory

## Optimization Problems solved by Eigenpairs

Assume  $A = A^* \in \mathbb{R}^{n \times n}$  (the hermitian case is similar, but for ease of notation we assume all variables are real).

Consider the following optimization problems:

$$\begin{aligned} & \text{maximize} && \langle Ax, x \rangle \\ & \|x\| = 1 \end{aligned} \tag{1.7}$$

and

$$\begin{aligned} & \text{minimize} && \langle Ax, x \rangle \\ & \|x\| = 1 \end{aligned} \tag{1.8}$$

Both problems can be solved using the Lagrange multiplier technique:

$$L(x, \lambda) = \langle Ax, x \rangle - \lambda(\langle x, x \rangle - 1) \Rightarrow \nabla L = 0$$

which produces eigenproblems for  $A$ :  $Ax = \lambda x$ . The first optimization problem has solution the largest eigenvalue of  $A$ , whereas the second problem has solution the smallest eigenvalue of  $A$ .

# Review of the Eigenproblems Theory

## Optimization Problems solved by Eigenpairs

To summarize:

### Theorem

Let  $A = A^* \in \mathbb{R}^{n \times n}$  be a self-adjoint matrix. Let  $\{(\lambda_k, e_k); 1 \leq k \leq n\}$  be the eigenpairs with  $\lambda_1 \geq \dots \geq \lambda_n$  and  $\|e_k\| = 1$ . Then for any vector  $x \in \mathbb{R}^n$ , with  $\|x\| = 1$ ,

$$\lambda_n = \langle Ae_n, e_n \rangle \leq \langle Ax, x \rangle \leq \langle Ae_1, e_1 \rangle = \lambda_1.$$

If  $A$  is not symmetric, then it can be replaced by its symmetrization via

$$\langle Ax, x \rangle = \frac{1}{2} \langle Ax, x \rangle + \frac{1}{2} \langle x, A^*x \rangle = \left\langle \frac{1}{2}(A + A^*)x, x \right\rangle$$

Hence:

$$\lambda_{\max} \left( \frac{1}{2}(A + A^*) \right) = \underset{\|x\|=1}{\text{maximize}} \langle Ax, x \rangle, \quad \lambda_{\min} \left( \frac{1}{2}(A + A^*) \right) = \underset{\|x\|=1}{\text{minimize}} \langle Ax, x \rangle$$

## References



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<http://stanford.edu/boyd/cvxbook/>



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