### Lecture 10: Review of graph modeling and inference

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### Main Problems

#### Main Problem

Input data: a weighted graph  $G = (\mathcal{V}, W)$  with n nodes. Issues:

- **1** Decide how well the two random graph models explain the data.
- 2 Partition the graph into two communities.
- Construct an embedding {y<sub>1</sub>,..., y<sub>n</sub>} ⊂ ℝ<sup>d</sup> such that W<sub>i,j</sub> ~ φ(||y<sub>i</sub> - y<sub>j</sub>||) for some monotonically decreasing function φ.

Typical weight functions:

- Exponential model:  $\varphi(t) = Ce^{-t^2}$ , for some C > 0.
- 2 Power law:  $\varphi(t) = \frac{C}{t^p}$ , for some C > 0 and p > 0.

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| Analysis                  |                              |                     |                     |                          |

Three studies need to be done:

Random graph hypothesis: Sort edges by weight: from the largest weight to the smallest weight. Then compare sample statistics of 3-cliques, 4-cliques with their expectations under the two stochastic models, Erdös-Rényi and SSBM.

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- Random graph hypothesis: Sort edges by weight: from the largest weight to the smallest weight. Then compare sample statistics of 3-cliques, 4-cliques with their expectations under the two stochastic models, Erdös-Rényi and SSBM.
- Ommunity Detection/Partition/Image Segmentation: Two classes of algorithms: spectral methods and SDP relaxations.

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Three studies need to be done:

- Random graph hypothesis: Sort edges by weight: from the largest weight to the smallest weight. Then compare sample statistics of 3-cliques, 4-cliques with their expectations under the two stochastic models, Erdös-Rényi and SSBM.
- Community Detection/Partition/Image Segmentation: Two classes of algorithms: spectral methods and SDP relaxations.
- Sembeddings: Laplacian eigenmaps: The geometric graph is obtained by solving the bottom d + 1 eigenproblems for the normalized symmetric Laplacian Δ̃ = I - D<sup>-1/</sup>WD<sup>-1/2</sup>. Additional algorithms: LLE and ISOMAP.

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#### Distribution of Cliques Expected Values

Let  $X_q$  denote the number of *q*-cliques in a random graph *G*. Then the expectation of  $X_q$  in  $\mathcal{G}_{n,p}$  class is

$$\mathbb{E}[X_q] = \begin{pmatrix} n \\ q \end{pmatrix} p^{q(q-1)/2}$$

The expectation of  $X_q$  in the class  $\Gamma^{n,m}$  is approximated by the above formula for  $p = \frac{2m}{n(n-1)}$ :

$$\mathbb{E}[X_q] \approx \binom{n}{q} \left(\frac{2m}{n(n-1)}\right)^{q(q-1)/2} \sim \theta_q \frac{m^{q(q-1)/2}}{n^{q(q-2)}}$$

$$\mathbb{E}[X_3] \sim \theta \frac{m^3}{n^3} \quad , \quad \mathbb{E}[X_4] \sim \theta \frac{m^6}{n^8}$$

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# 3-Cliques and 4-cliques

#### Thresholds

#### Theorem

Let m = m(n) be the number of edges in  $\Gamma^{n,m}$ .

• If  $m \gg n$  (i.e.  $\lim_{n\to\infty} \frac{m}{n} = \infty$ ) then  $\lim_{n\to\infty} Prob[G \in \Gamma^{n,m} has a 3 - clique] \to 1.$ 

2 If 
$$m \ll n$$
 (i.e.  $\lim_{n\to\infty} \frac{m}{n} = 0$ ) then  
 $\lim_{n\to\infty} Prob[G \in \Gamma^{n,m} has a 3 - clique] \to 0.$ 

#### Theorem

Let m = m(n) be the number of edges in  $\Gamma^{n,m}$ .

• If 
$$m \gg n^{4/3}$$
 (i.e.  $\lim_{n\to\infty} \frac{m}{n^{4/3}} = \infty$ ) then  $\lim_{n\to\infty} Prob[G \in \Gamma^{n,m} has a 4 - clique] \to 1.$ 

2 If  $m \ll n^{4/3}$  (i.e.  $\lim_{n\to\infty} \frac{m}{n^{4/3}} = 0$ ) then  $\lim_{n\to\infty} Prob[G \in \Gamma^{n,m} has a 4 - clique] \to 0.$ 

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# 3-Cliques and 4-Cliques

Behavior at the threshold

In general we obtain a "coarse threshold". Recall a Poisson process X with parameter  $\lambda$  has p.m.f.  $Prob[X = k] = e^{-\lambda} \frac{\lambda^k}{k!}$ .

#### Theorem

In  $\mathcal{G}_{n,p}$ ,

• For  $p = \frac{c}{n}$ ,  $X_3$  is asymptotically Poisson with parameter  $\lambda = c^3/6$ .

2 For  $p = \frac{c}{n^{2/3}}$ ,  $X_4$  is asymptotically Poisson with parameter  $\lambda = c^6/24$ .

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# 3-Cliques and 4-Cliques

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#### Theorem

In  $\mathcal{G}_{n,p}$ ,

For p = <sup>c</sup>/<sub>n</sub>, X<sub>3</sub> is asymptotically Poisson with parameter λ = c<sup>3</sup>/6.
 For p = <sup>c</sup>/<sub>p<sup>2/3</sup></sub>, X<sub>4</sub> is asymptotically Poisson with parameter λ = c<sup>6</sup>/24.

#### Theorem

In  $\Gamma^{n,m}$ ,

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# Eigenvalues of Laplacians $\Delta, L, \tilde{\Delta}$

What do we know about the set of eigenvalues of these matrices for a graph G with n vertices?

- $\Delta = \Delta^T \ge 0$  and hence its eigenvalues are non-negative real numbers.
- eigs( $\tilde{\Delta}$ ) = eigs(L)  $\subset$  [0, 2].
- 0 is always an eigenvalue and its multiplicity equals the number of connected components of G,

 $\dim \ker(\Delta) = \dim \ker(L) = \dim \ker(\tilde{\Delta}) = \#$  connected components.

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# Eigenvalues of Laplacians $\Delta, L, \tilde{\Delta}$

What do we know about the set of eigenvalues of these matrices for a graph G with n vertices?

- $\label{eq:delta} \bullet \Delta = \Delta^{\mathcal{T}} \geq 0 \mbox{ and hence its eigenvalues are non-negative real numbers.}$
- eigs( $\tilde{\Delta}$ ) = eigs(L)  $\subset$  [0, 2].
- 0 is always an eigenvalue and its multiplicity equals the number of connected components of G,

 $\dim \ker(\Delta) = \dim \ker(L) = \dim \ker(\tilde{\Delta}) = \#$  connected components.

Let  $0 = \lambda_0 \leq \lambda_1 \leq \cdots \leq \lambda_{n-1}$  be the eigenvalues of  $\tilde{\Delta}$ . Denote

$$\lambda(G) = \max_{1 \le i \le n-1} |1 - \lambda_i|.$$

Note  $\sum_{i=1}^{n-1} \lambda_i = trace(\tilde{\Delta}) = n$ . Hence the average eigenvalue is about 1.  $\lambda(G)$  is called *the absolute gap* and measures the spread of eigenvalues Radu Balan (UMD) MATH 420: Nonlinear modeling March 26, 2024

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# The spectral absolute gap $\lambda(G)$

The main result in [9]) says that for connected graphs w/h.p.:

$$\lambda_1 \geq 1 - rac{\mathcal{C}}{\sqrt{ ext{Average Degree}}} = 1 - rac{\mathcal{C}}{\sqrt{\mathcal{p}(n-1)}} = 1 - \mathcal{C}\sqrt{rac{n}{2m}}.$$

#### Theorem (For class $\mathcal{G}_{n,p}$ )

Fix  $\delta > 0$  and let  $p > (\frac{1}{2} + \delta)\log(n)/n$ . Let d = p(n-1) denote the expected degree of a vertex. Let  $\tilde{G}$  be the giant component of the Erdös-Rényi graph. For every fixed  $\varepsilon > 0$ , there is a constant  $C = C(\delta, \varepsilon)$ , so that

$$\lambda(\tilde{G}) \leq \frac{C}{\sqrt{d}}$$

with probability at least  $1 - Cn \exp(-(2 - \varepsilon)d) - C \exp(-d^{1/4}\log(n))$ .

Connectivity threshold:  $p \sim \frac{\log(n)}{n}$ .

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Fix  $\delta > 0$  and let  $m > \frac{1}{2}(\frac{1}{2} + \delta)n \log(n)$ . Let  $d = \frac{2m}{n}$  denote the expected degree of a vertex. Let  $\tilde{G}$  be the giant component of the Erdös-Rényi graph. For every fixed  $\varepsilon > 0$ , there is a constant  $C = C(\delta, \varepsilon)$ , so that

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Connectivity threshold:  $m \sim \frac{1}{2}n \log(n)$ .

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## Isometric Embeddings with Partial Data

Linear constraints

Given any set of vectors  $\{y_1, \dots, y_n\}$  and their associated matrix  $Y = [y_1| \dots |y_n]$  their invariant to the action of the rigid transformations (translations, rotations, and reflections) is the Gram matrix of the centered system:

$$G = (I - \frac{1}{n} 1 \cdot 1^{T}) Y^{T} Y (I - \frac{1}{n} 1 \cdot 1^{T}) =: LY^{T} Y L \quad , \quad L = I - \frac{1}{n} 1 \cdot 1^{T}.$$

On the other hand, the distance between points i and j can be computed by:

$$d_{i,j}^2 = \|y_i - y_j\|^2 = G_{i,i} - G_{i,j} + G_{j,j} - G_{j,i} = e_{ij}^T G e_{ij}$$

where

$$e_{ij} = \delta_i - \delta_j = [0 \cdots 0 \ 1 \cdots - 1 \ 0 \cdots 0]^T$$

where 1 is on position i, -1 is on position j, and 0 everywhere else.

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#### Almost Isometric Embeddings with Partial Data The SDP Problem

Reference [10] proposes to find the matrix G by solving the following Semi-Definite Program:

$$egin{aligned} & \min & trace(G) \ & G &= G^T \geq 0 \ & G &\cdot 1 &= 0 \ & |\langle \textit{Ge}_{ij}, e_{ij} 
angle - ilde{d}_{i,j}^2| \leq arepsilon \;, \; (i,j) \in \Theta \end{aligned}$$

where  $\tilde{d}_{i,j}^2$  are noisy estimates  $d_{i,j}$  and  $\varepsilon$  is the maximum noise level. The trace promotes low rank in this optimization. However, this is basically a feasibility problem: Decrease  $\varepsilon$  to the minimum value where a feasible solution exists. With probability 1 that is unique. How to do this: Use CVX with Matlab.

## Geometric Graph Embedding

Gram matrix factorization: The Algorithm Algorithm

Input: Symmetric  $n \times n$  Gram matrix G.

- Compute the eigendecomposition of G, G = QΛQ<sup>T</sup> with diagonal of Λ sorted in a descending order;
- Optimize the number d of significant positive eigevalues;

In Partition

$$Q = \begin{bmatrix} Q_1 & Q_2 \end{bmatrix}$$
 , and  $\Lambda = \begin{bmatrix} \Lambda_1 & 0 \\ 0 & \Lambda_2 \end{bmatrix}$ 

where  $Q_1$  contains the first d columns of Q, and  $\Lambda_1$  is the d × d diagonal matrix of significant positive eigenvalues of G.

• Compute:

$$Y = \Lambda_1^{1/2} Q_1^T$$

Output: Dimension d and d × n matrix Y of vectors  $Y = [y_1| \cdots |y_n]$ 

### Nearly Isometric Embeddings with Partial Data Stability to Noise

[10] proves the following stability result in the case of partial measurements. Here we denote  $\Theta_r = \{(i,j), ||y_i - y_j|| \le r\}$  the set of all pairs of points at distance at most r.

#### Theorem

Let  $\{y_1, \dots, y_n\}$  be n nodes distributed uniformly at random in the hypercube  $[-0.5, 0.5]^d$ . Further, assume that we are given noisy measurement of all distances in  $\Theta_r$  for some  $r \ge 10\sqrt{d}(\log(n)/n)^{1/d}$  and the induced geometric graph of edges is connected. Let  $\tilde{d}_{i,j}^2 = d_{i,j}^2 + \nu_{i,j}$  with  $|\nu_{i,j}| \le \varepsilon$ . Then with high probability, the error distance between the estimated  $\hat{Y} = [\hat{y}_1, |\cdots|\hat{y}_n]$  returned by the SDP-based algorithm and the correct coordinate matrix  $Y = [y_1|\cdots|y_n]$  is upper bounded as

$$\|L\hat{Y}^T\hat{Y}L - LY^TYL\|_1 \leq C_1(nr^d)^5\frac{\varepsilon}{r^4}.$$

## **Optimization Criterion**

Assume  $\mathcal{G} = (\mathcal{V}, W)$  is a undirected weighted graph with *n* nodes and weight matrix *W*.

We interpret  $W_{i,j}$  as the *similarity* between nodes *i* and *j*. The larger the weight the more similar the nodes, and the closer they are in a geometric graph embedding.

Thus we look for a dimension d > 0 and a set of points  $\{y_1, y_2, \dots, y_n\} \subset \mathbb{R}^d$  so that  $d_{i,j} = ||y_i - y_j||$ 's is small for large weight  $W_{i,j}$ . This means we want to minimize

$$J(y_1, y_2, \cdots, y_n) = \sum_{1 \le i,j \le n} W_{i,j} ||y_i - y_j||^2,$$

To avoid trivial solution Y = 0 we impose a normalization condition:

$$YDY^T = I_d.$$

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### The Optimization Problem

Combining the criterion with the constraint:

$$(LE) : \begin{array}{ll} \text{minimize} & trace \left\{ Y \Delta Y^T \right\} \\ \text{subject to} & Y D Y^T = I_d \end{array}$$

we obtained the Laplacian Eigenmap problem.

Good news: The optimizer Y is obtaind by solving an eigenproblem.

# Laplacian Eigenmaps Embedding Algorithm

#### Algorithm (Laplacian Eigenmaps)

Input: Weight matrix W, target dimension d

- Construct the diagonal matrix  $D = diag(D_{ii})_{1 \le i \le n}$ , where  $D_{ii} = \sum_{k=1}^{n} W_{i,k}$ .
- **2** Construct the normalized Laplacian  $\tilde{\Delta} = I D^{-1/2} W D^{-1/2}$ .
- Some compute the bottom d + 1 eigenvectors  $e_1, \dots, e_{d+1}$ ,  $\tilde{\Delta}e_k = \lambda_k e_k$ ,  $0 = \lambda_1 \dots \lambda_{d+1}$ .

# Laplacian Eigenmaps Embedding

Algorithm-cont's

#### Algorithm (Laplacian Eigenmaps - cont'd)

• Construct the  $d \times n$  matrix Y,

$$Y = \begin{bmatrix} e_2 \\ \vdots \\ e_{d+1} \end{bmatrix} D^{-1/2}$$

The new geometric graph is obtained by converting the columns of Y into n d-dimensional vectors:

$$\left[\begin{array}{cccc} y_1 & | & \cdots & | & y_n \end{array}\right] = Y$$

*Output:* Set of points  $\{y_1, y_2, \cdots, y_n\} \subset \mathbb{R}^d$ .

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### **Problem Formulation**

Given: It is assumed that we are given a set of points  $\{x_1, \dots, x_n\} \subset \mathbb{R}^N$ , or a weight matrix W, where  $W_{i,j}$  is inverse monotonically dependent to distances  $||x_i - x_j||$ ; the smaller the distance  $||x_i - x_j||$  the larger the weight  $W_{i,j}$ .

Target: We look for a dimension d > 0 and a set of points

 $\{y_1, y_2, \cdots, y_n\} \subset \mathbb{R}^d$  so that all  $d_{i,j} = ||y_i - y_j||$ 's are compatible with the raw data.

Approaches:

- Principal Component Analysis
- Independent Component Analysis
- 4 Laplacian Eigenmaps
- 4 Local Linear Embeddings (LLE)
- Isomaps

#### Principal Component Analysis Algorithm

#### Algorithm (Principal Component Analysis)

Input: Data vectors  $\{x_1, \cdots, x_n\} \in \mathbb{R}^N$ ; dimension d.

- If affine subspace is the goal, append '1' at the end of each data vector.
- **1** Compute the sample covariance matrix

$$R = \sum_{k=1}^{n} x_k x_k^T$$

**2** Solve the eigenproblems  $Re_k = \sigma_k^2 e_k$ ,  $1 \le k \le N$ , order eigenvalues  $\sigma_1^2 \ge \sigma_2^2 \ge \cdots \ge \sigma_N^2$  and normalize the eigenvectors  $||e_k||_2 = 1$ .

# Principal Component Analysis

Algorithm - cont'ed

#### Algorithm (Principal Component Analysis)

**3** Construct the co-isometry

$$U = \begin{bmatrix} e_1^T \\ \vdots \\ e_d^T \end{bmatrix}$$

Project the input data

$$y_1 = Ux_1 , y_2 = Ux_2 , \cdots , y_n = Ux_n.$$

Output: Lower dimensional data vectors  $\{y_1, \cdots, y_n\} \in \mathbb{R}^d$ .

The orthogonal projection is given by  $P = \sum_{k=1}^{d} e_k e_k^T$  and the optimal subspace is V = Ran(P)Radu Balan (UMD) MATH 420: Nonlinear modeling March 26, 2024 
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### Dimension Reduction using Laplacian Eigenmaps Algorithm

Algorithm (Dimension Reduction using Laplacian Eigenmaps)

Input: A geometric graph  $\{x_1, x_2, \dots, x_n\} \subset \mathbb{R}^N$ . Parameters: threshold  $\tau$ , weight coefficient  $\alpha$ , and dimension d.

Compute the set of pairwise distances ||x<sub>i</sub> - x<sub>j</sub>|| and convert them into a set of weights:

$$W_{i,j} = \begin{cases} exp(-\alpha ||x_i - x_j||^2) & \text{if } ||x_i - x_j|| \le \tau \\ 0 & \text{if } otherwise \end{cases}$$

② Compute the d + 1 bottom eigenvectors of the normalized Laplacian matrix  $\tilde{\Delta} = I - D^{-1/2} W D^{-1/2}$ ,  $\tilde{\Delta} e_k = \lambda_k e_k$ ,  $1 \le k \le d + 1$ ,  $0 = \lambda_0 \le \cdots \le \lambda_{d+1}$ , where  $D = diag(\sum_{k=1}^n W_{i,k})_{1 \le i \le n}$ .

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### Dimension Reduction using Laplacian Eigenmaps Algorithm - cont'd

Algorithm (Dimension Reduction using Laplacian Eigenmaps-cont'd)

**3** Construct the  $d \times n$  matrix Y,

$$Y = \begin{bmatrix} e_2^T \\ \vdots \\ e_{d+1}^T \end{bmatrix} D^{-1/2}$$

The new geometric graph is obtained by converting the columns of Y into n d-dimensional vectors:

$$\left[\begin{array}{cccc}y_1 & | & \cdots & | & y_n\end{array}\right] = Y$$

Output:  $\{y_1, \cdots, y_n\} \subset \mathbb{R}^d$ .

# Dimension Reduction using Isomaps

#### Algorithm (Dimension Reduction using Isomap)

Input: A geometric graph  $\{x_1, x_2, \dots, x_n\} \subset \mathbb{R}^N$ . Parameters: neighborhood size K and dimension d.

- **O** Construct the symmetric matrix *S* of squared pairwise distances:
  - Construct the sparse matrix *T*, where for each node *i* find the nearest *K* neighbors *V<sub>i</sub>* and set *T<sub>i,j</sub>* = ||*x<sub>i</sub>* − *x<sub>j</sub>*||<sub>2</sub>, *j* ∈ *V<sub>i</sub>*.
  - Por any pair of two nodes (i, j) compute d<sub>i,j</sub> as the length of the shortest path, ∑<sup>L</sup><sub>p=1</sub> T<sub>k<sub>p-1</sub>,k<sub>p</sub></sub> with k<sub>0</sub> = i and k<sub>L</sub> = j, using e.g. Dijkstra's algorithm.

**3** Set 
$$S_{i,j} = d_{i,j}^2$$
.

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# Dimension Reduction using Isomaps

Algorithm - cont'd

Algorithm (Dimension Reduction using Isomap - cont'd)

d

**2** Compute the Gram matrix G:

$$=\frac{1}{2n}\mathbf{1}^{T}\cdot S\cdot \mathbf{1} , \quad \nu=\frac{1}{n}(S\cdot \mathbf{1}-\rho\mathbf{1})$$

$$G = \frac{1}{2}\nu \cdot 1^{T} + \frac{1}{2}1 \cdot \nu^{T} - \frac{1}{2}S$$

So Find the top d eigenvectors of G, say  $e_1, \dots, e_d$  so that  $GE = E\Lambda$ , form the matrix Y and then collect the columns:

$$Y = \Lambda^{1/2} \begin{bmatrix} e_1^T \\ \vdots \\ e_d^T \end{bmatrix} = \begin{bmatrix} y_1 & | \cdots & | & y_n \end{bmatrix}$$

$$\underbrace{Output: \{v_1, \dots, v_n\} \subset \mathbb{R}}_{\text{Radu Balan (UMD)}}$$

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