

Example of an integral equation

Consider the integral equation: $f(x) = \int_{-\infty}^{\infty} f(u) \cdot \text{sinc}(x-u) du$

- 1) What can we infer about the Fourier transform of f ?
- 2) Find a solution of this equation.

Solution:

Note that $\int_{-\infty}^{\infty} f(u) \cdot \text{sinc}(x-u) du = (f * \text{sinc})(x)$.

Equation: $f = f * \text{sinc} \quad (*)$

Let F denote the Fourier transform of f .

We know: $\widehat{\text{sinc}} = \Pi$.

Therefore ~~the equation (*)~~ ~~bec~~ by applying Fourier transform on both sides of (*) we get:

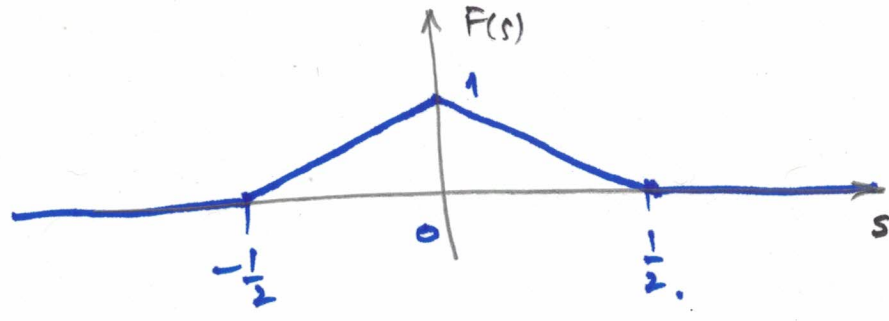
$$F(s) = F(s) \cdot \Pi(s) \quad (**)$$

$$\Rightarrow \text{For } |s| \geq \frac{1}{2}, \quad F(s) = 0.$$

For $|s| < \frac{1}{2}$, $(**)$ $\Rightarrow F(s) = F(s)$. \rightarrow Represents no constraint on F .

① \rightarrow We infer that $F(s) = 0$, for $s \leq -\frac{1}{2}$ or $s \geq \frac{1}{2}$.

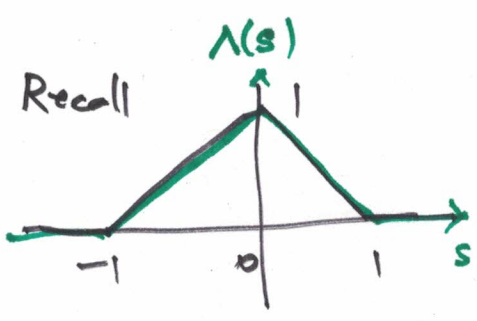
For $-\frac{1}{2} < s < \frac{1}{2}$, there is no constraint on $F(s)$.



For ②

Choose :

$$F(s) = \begin{cases} 0, & |s| \geq \frac{1}{2} \\ 1 - 2|s|, & |s| < \frac{1}{2} \end{cases}$$



$$\Lambda(s) = \begin{cases} 0, & |s| > 1 \\ 1 - |s|, & |s| \leq 1 \end{cases}$$

Therefore: $F(s) = \Lambda(2s)$

The function f is obtained by Fourier inversion:

Fourier Transform

Inverse Fourier Transform

$$\Pi(s)$$

$$\Lambda = \Pi * \Pi$$

$$F(s) = \Lambda(2s)$$

Conv. Rule \rightarrow

Scaling
Rule \rightarrow

$$\text{Sinc}(x)$$

$$\text{Sinc}^2(x)$$

$$f(x) = \frac{1}{2} \left(\text{Sinc}\left(\frac{x}{2}\right) \right)^2$$

Hence $f(x) = \frac{1}{2} \left(\text{Sinc}\left(\frac{x}{2}\right) \right)^2$ is a solution of $f * \text{Sinc} = f$.

Relationship between Convolutions and Linear Filters

(3)

If $f, g: \mathbb{R} \rightarrow \mathbb{C}$ are 1-periodic functions, then (periodic)

convolution:

$$f * g(x) = \int_0^1 f(x-y) g(y) dy.$$

On the other hand:

the Fourier Series expansion of f and g :

$$f(x) = \sum_{n=-\infty}^{\infty} c_n e^{2\pi i n x}, \quad c_n = \int_0^1 e^{-2\pi i n x} f(x) dx$$

$$g(x) = \sum_{n=-\infty}^{\infty} d_n e^{2\pi i n x}, \quad d_n = \int_0^1 e^{-2\pi i n x} g(x) dx.$$

Remark:

$f * g$ is also a 1-periodic function:

$$(f * g)(x+1) = \int_0^1 \underbrace{f(x+1-y)}_{f(x-y)} g(y) dy = \int_0^1 f(x-y) g(y) dy = (f * g)(x).$$

The Fourier series expansion of $f * g$:

$$f * g(x) = \sum_{n=-\infty}^{\infty} \gamma_n e^{2\pi i n x}, \quad \gamma_n = \int_0^1 e^{-2\pi i n x} (f * g)(x) dx$$

Question: How to compute γ_n directly from $(c_n)_n, (d_n)_n$?

$$\gamma_n = \int_0^1 e^{-2\pi i n x} (f * g)(x) dx = \int_0^1 e^{-2\pi i n x} \left(\int_0^1 f(x-y) g(y) dy \right) dx =$$

$$= \int_0^1 \int_0^1 \underbrace{e^{-2\pi i n(x-y+y)}}_{e^{-2\pi i n(x-y)} \cdot e^{-2\pi i n y}} f(x-y) g(y) dx dy =$$

$$= \int_0^1 e^{-2\pi i n y} g(y) \left(\int_0^1 e^{-2\pi i n(x-y)} f(x-y) dx \right) dy =$$

$$t = x - y.$$

$$dt = dx$$

$$\rightarrow \int_{-y}^{1-y} e^{-2\pi i n t} f(t) dt = \int_0^1 e^{-2\pi i n t} f(t) dt$$

$$= \int_0^1 e^{-2\pi i n y} g(y) \left(\int_0^1 e^{-2\pi i n t} f(t) dt \right) dy = c_n \cdot \underbrace{\int_0^1 e^{-2\pi i n y} g(y) dy}_{d_n} =$$

$$= c_n \cdot d_n$$

c_n : n^{th} Fourier coeff of f

d_n : n^{th} Fourier coeff of g .

Summary:

$$\gamma_n = c_n \cdot d_n.$$

n^{th} Fourier coeff of $f * g$.

\uparrow
1-periodic convolution.

The converse is also true!

So far:

$$f \leftrightarrow (c_n)_n$$

$$g \leftrightarrow (d_n)_n$$

$$f * g \leftrightarrow (c_n \cdot d_n)_n$$

Consider now: $c * d$, convolution over sequences of coefficients

$$\text{If } c = (c_n)_{n \in \mathbb{Z}}, d = (d_n)_{n \in \mathbb{Z}}$$

$$(c * d)_n = \sum_{k=-\infty}^{\infty} c_{n-k} \cdot d_k$$

Question: What is the 1-periodic function $h(x) = \sum_{n=-\infty}^{\infty} (c * d)_n e^{2\pi i n x}$?

$$h(x) = \sum_{n=-\infty}^{\infty} \left(\sum_{k=-\infty}^{\infty} c_{n-k} \cdot d_k \right) e^{2\pi i n x} =$$

$$= \sum_{k=-\infty}^{\infty} \sum_{n=-\infty}^{\infty} e^{2\pi i(n-k+k)x} c_{n-k} \cdot d_k = \sum_{k=-\infty}^{\infty} d_k \sum_{n=-\infty}^{\infty} e^{2\pi i(n-k)x} c_{n-k}$$

$$= \sum_k e^{2\pi i k x} d_k \cdot \sum_n e^{2\pi i(n-k)x} c_{n-k}$$

$$= \underbrace{\sum_k d_k e^{2\pi i k x}}_{g(x)} \cdot \underbrace{\sum_m c_m e^{2\pi i m x}}_{f(x)} = f(x) \cdot g(x)$$

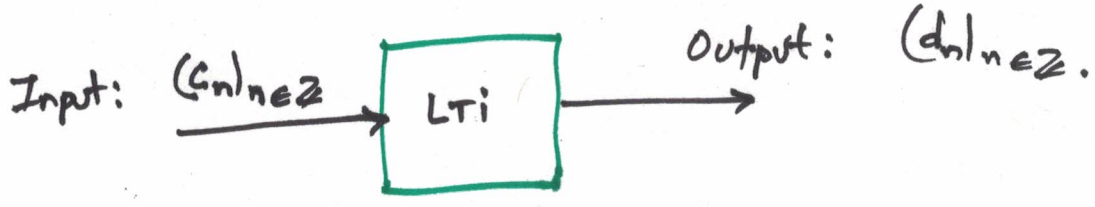
Rule:

If $f : 1\text{-periodic} \longleftrightarrow (c_n)_n$
 $g : 1\text{-periodic} \longleftrightarrow (d_n)_n$

Then: $f * g \longleftrightarrow (c_n * d_n)_n$
 $f \cdot g \longleftrightarrow (c_n \cdot d_n)_n$

Linear Systems : Linear Time Invariant (LTI) Systems

An discrete-time LTI system :



LTI: takes an input sequence $(c_n)_n$ and returns an output sequence $(d_n)_n$

Linearity

such that:

① If input is $(a \cdot c_n)_{n \in \mathbb{Z}}$ then output is $(a \cdot d_n)_{n \in \mathbb{Z}}$

for any $a \in \mathbb{C}$

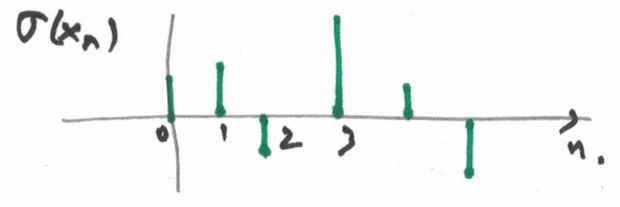
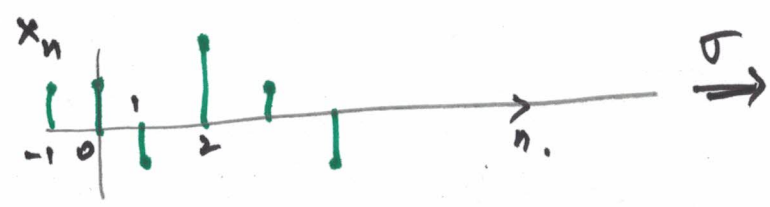
② If $\text{input}_1 = (c_n)_n \longrightarrow \text{output}_1 = (d_n)_n$

$\text{input}_2 = (x_n)_n \longrightarrow \text{output}_2 = (y_n)_n$

Then $\text{input} = (c_n + x_n)_n \longrightarrow \text{output} = (d_n + y_n)_n$

Let: $\sigma: x = (x_n)_{n \in \mathbb{Z}} \longrightarrow (\sigma(x))_n = x_{n-1}$.

denote the time-shift.



③ If input $c = (c_n)_{n \in \mathbb{Z}}$

$\xrightarrow{\text{LTI}}$ output: $d = (d_n)_{n \in \mathbb{Z}}$

Then for input $\sigma(c)$

$\xrightarrow{\text{LTI}}$ output: $\sigma(d)$.

Time-Invariance.

Remark: ③ \Rightarrow If input $c = (c_n)$

$\xrightarrow{\text{LTI}}$ output: $d = (d_n)_{n \in \mathbb{Z}}$

Then for any integer m ,

input $\sigma^m(c)$

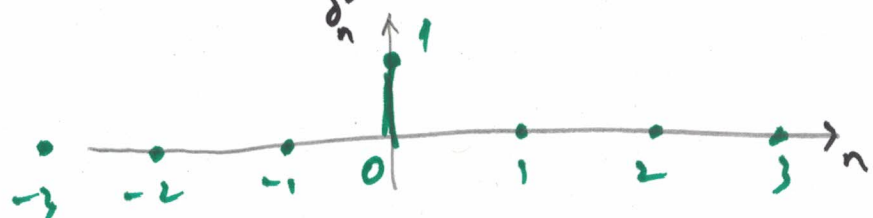
$\xrightarrow{\text{LTI}}$ output: $\sigma^m(d)$.

$(\sigma^m(c))_n = c_{n-m}$

$\xrightarrow{\text{LTI}}$ output: $(\sigma^m(d))_n = d_{n-m}$

Let $\delta = (\delta_{n,0})_{n \in \mathbb{Z}}$, where $\delta_{n,0} = \begin{cases} 1, & n=0 \\ 0, & n \neq 0 \end{cases}$

be the unit sequence, also known as the impulse.



Note:
$$\left(\sigma^m(\delta) \right)_n = \delta_{n-m,0} = \delta_{n,m} = \begin{cases} 1, & n=m \\ 0, & n \neq m. \end{cases}$$

Then:

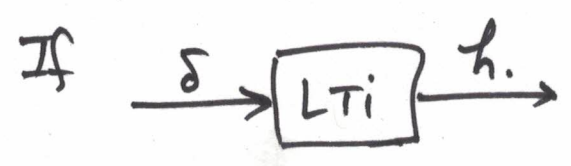
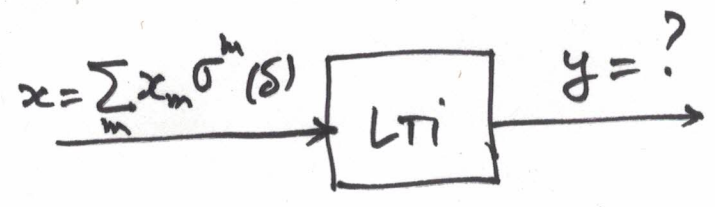
$$x = (x_n)_{n \in \mathbb{Z}} = \left(\sum_{m=-\infty}^{\infty} x_m \cdot \sigma^m(\delta) \right)_n$$

For a fixed n :
$$\sum_m x_m \cdot \left(\sigma^m(\delta) \right)_n = \sum_m x_m \cdot \delta_{n,m} = x_n.$$

We showed:

$$x = \sum_{m=-\infty}^{\infty} x_m \cdot \sigma^m(\delta)$$

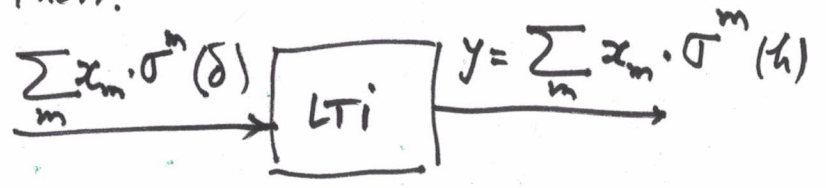
$\dots \rightarrow \{ \sigma^m(\delta), m \in \mathbb{Z} \}$ is a basis for sequences.



h denotes the output when input = δ (impulse).

h = "impulse response".

Then:

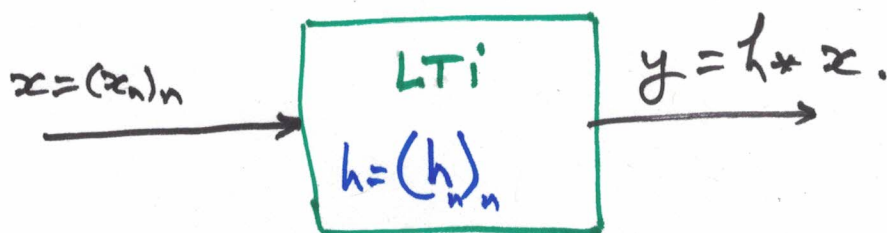


Therefore:

(9)

$$y_n = \left(\sum_m x_m \sigma^m(h) \right)_n = \sum_m x_m \cdot (\sigma^m(h))_n = \\ = \sum_m x_m \cdot h_{n-m} = \sum_{m=-\infty}^{\infty} h_{n-m} \cdot x_m = (h * x)_n.$$

Conclusion: Any LTI is characterized by the following input-output relationship:



where $h = (h_n)_n$ is the impulse response.

A different characterization:

$$x = (x_n)_{n \in \mathbb{Z}} \longrightarrow \underline{X}(\omega) = \sum_{n=-\infty}^{\infty} x_n e^{2\pi i n \omega}$$

$$y = (y_n)_{n \in \mathbb{Z}} \longrightarrow \underline{Y}(\omega) = \sum_{n=-\infty}^{\infty} y_n e^{2\pi i n \omega}$$

$$h = (h_n)_n \longrightarrow H(\omega) = \sum_{n=-\infty}^{\infty} h_n e^{2\pi i n \omega}$$

We obtain:

$$\underline{Y}(\omega) = H(\omega) \cdot \underline{X}(\omega)$$

↳ Transfer Function of LTI