

(L3) Scalar Product. Orthonormal basis. Approximations (1)

Assume  $(V, \langle \cdot, \cdot \rangle)$  is a vector space with scalar product.

Theorem [Cauchy-Schwarz Inequality]. Let  $x, y \in V$ . Then:

$$|\langle x, y \rangle| \leq \sqrt{\langle x, x \rangle} \cdot \sqrt{\langle y, y \rangle}.$$

Why?

Assume.  $\langle x, y \rangle$  is real. (Not too complicated to extend to  $\mathbb{C}$ )

Let  $\varphi: \mathbb{R} \rightarrow \mathbb{R}$ ,  $\varphi(t) = \langle x + ty, x + ty \rangle$ .

We know:  $\varphi(t) \geq 0$ , for every  $t \in \mathbb{R}$ . (by positivity of the inner product).

$\varphi(t) = \langle x + ty, x + ty \rangle \stackrel{\text{by linearity}}{=} \langle x, x + ty \rangle + t \langle y, x + ty \rangle =$

$\stackrel{\text{by linearity}}{=} \langle x, x \rangle + t \langle x, y \rangle + t \langle y, x \rangle + t^2 \langle y, y \rangle =$

$\stackrel{\text{by (skew)symmetry}}{=} \langle x, x \rangle + 2t \langle x, y \rangle + t^2 \langle y, y \rangle.$

Let  $a = \langle y, y \rangle$ ,  $b = 2 \langle x, y \rangle$ ,  $c = \langle x, x \rangle$ .

Then:  $\varphi(t) = at^2 + bt + c \geq 0$ ,  $\forall t \in \mathbb{R}$   
(for every real  $t$ ).

Case 1:  $a = 0$ :  $\langle y, y \rangle = 0 \Rightarrow y = 0 \Rightarrow \langle x, y \rangle = 0$ .

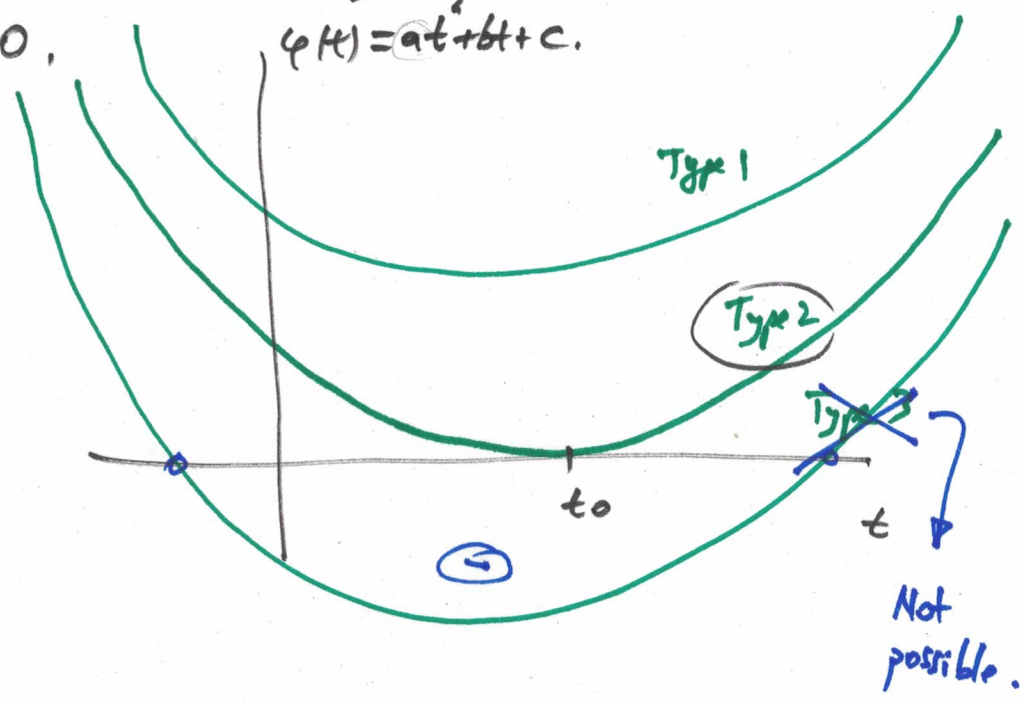
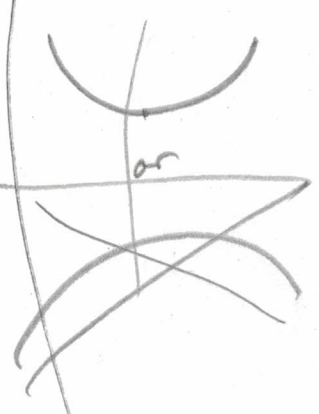
$\Rightarrow 0 \leq \sqrt{\langle x, x \rangle} \cdot 0 = 0$  (why:  $\langle 2xy \rangle = \langle x, 2y \rangle = \langle x, 0 \rangle = 2 \langle x, 0 \rangle$ )

Case 2:  $a \neq 0 \Leftrightarrow y \neq 0$ .

$[at^2 + bt + c \geq 0, \forall t \in \mathbb{R}]$  quadratic function.

But:  $a = \langle y, y \rangle > 0$ ,

$\varphi(t) = at^2 + bt + c$ .



Parabola is either of type 1 or type 2.

$\Leftrightarrow \Delta = b^2 - 4ac \leq 0$ .

$(2\langle x, y \rangle)^2 - 4\langle y, y \rangle \cdot \langle x, x \rangle \leq 0$ .

$(\langle x, y \rangle)^2 \leq \langle x, x \rangle \cdot \langle y, y \rangle$ .

$|\langle x, y \rangle| \leq \sqrt{\langle x, x \rangle} \cdot \sqrt{\langle y, y \rangle}$ .

CS inequality.

Equality:

$\Delta = 0 \Leftrightarrow at^2 + bt + c = 0$ , for some  $t_0$ .  
(Type 2)

$\langle x + t_0 y, x + t_0 y \rangle = 0 \Leftrightarrow x + t_0 y = 0$

(x, y) are linearly dependent

Other examples of scalar products:

$$(1) \quad V = \mathbb{R}^n, \quad x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}, \quad y = \begin{pmatrix} y_1 \\ \vdots \\ y_n \end{pmatrix}$$

$$\langle x, y \rangle_1 = x_1 y_1 + 2 \cdot x_2 y_2 + 3 \cdot x_3 y_3 + \dots + n \cdot x_n y_n.$$

(2) For any  $a_1, a_2, \dots, a_n > 0$  (real):

$$V = \mathbb{R}^n,$$

$$\langle x, y \rangle_2 = a_1 x_1 y_1 + a_2 x_2 y_2 + \dots + a_n x_n y_n.$$

(3) If  $A = A^T \in \mathbb{R}^{n \times n}$ ,  $V = \mathbb{R}^n$

consider:

$$\begin{aligned} \langle x, y \rangle_A &= x^T \cdot A \cdot y = (x_1, \dots, x_n) \cdot \begin{pmatrix} A_{11} & A_{12} & \dots & A_{1n} \\ A_{21} & A_{22} & \dots & A_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ A_{n1} & A_{n2} & \dots & A_{nn} \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix} \\ &= \sum_{i=1}^n \sum_{j=1}^n A_{ij} x_i y_j \end{aligned} \quad (*)$$

Fact: The matrix  $A = A^T$  defines a scalar product via  $\langle \cdot, \cdot \rangle_A$  as in (\*) if and only if  $A$  is a positive definite matrix.

$\Downarrow$   
Each eigenvalue of  $A$  is positive.

$\Downarrow$  CHOLSKY  
there is  $W \in \mathbb{R}^{n \times n}$  s.t.  $A = W \cdot W^T$  (Cholesky factorization).

NORM: Let  $V$  be a vector space.

(4)

Definition: A function  $\|\cdot\|: V \rightarrow \mathbb{R}$  is called a norm on  $V$  if it satisfies:

(1) Positivity: (i)  $\forall x \in V, \|x\| \geq 0$ .

(ii)  $\|x\| = 0$  if and only if  $x = 0$ .

(2) Homogeneity:  $\forall x \in V, \forall a \in \mathbb{C}$ :

$$\|a \cdot x\| = |a| \cdot \|x\|$$

(3) Triangle inequality:  $\forall x, y \in V$

$$\|x + y\| \leq \|x\| + \|y\|.$$

Remark: If  $(V, \langle \cdot, \cdot \rangle)$  is a vector space with scalar product

then  $x \mapsto \sqrt{\langle x, x \rangle}$

defines a norm, known as the associated norm (induced norm).

$$\|x\| = \sqrt{\langle x, x \rangle}.$$

Example:  $V = \mathbb{R}^n, \langle x, y \rangle = x_1 y_1 + \dots + x_n y_n$ .

Then  $\|x\| = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2}$  (Euclidean norm)

(distance)

Notation:  $\|x\|_2 = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2}$ .



If  $V = \mathbb{C}^n$ :

(5)

$$x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \in \mathbb{C}^n \quad \longrightarrow \quad \|x\| = \|x\|_2 = \sqrt{|x_1|^2 + |x_2|^2 + \dots + |x_n|^2}$$

Example:  $V = \mathbb{C}^n$ ,  $1 \leq p$

Set:

$$\|x\|_p = \left( |x_1|^p + |x_2|^p + \dots + |x_n|^p \right)^{1/p}$$

Example:  $p = \infty$ .

$$\|x\|_\infty = \max_{1 \leq k \leq n} |x_k|$$

Fact: For each  $1 \leq p \leq \infty$ ,  $\|\cdot\|_p$  defines a norm.

Example. For  $1 \leq p \leq \infty$ , sequence of complex numbers indexed by  $\mathbb{Z}$

$$l^p(\mathbb{Z}) = \left\{ x = (x_n)_{n \in \mathbb{Z}} : \sum_{n=-\infty}^{\infty} |x_n|^p < \infty \right\}$$

Norm:  $\|x\|_p = \left( \sum_{n=-\infty}^{\infty} |x_n|^p \right)^{1/p}$  : Fact:  $\|\cdot\|_p$  defines a norm on  $l^p(\mathbb{Z})$ .

Example  $p = \infty$ :

$$l^\infty(\mathbb{Z}) = \left\{ x = (x_n)_{n \in \mathbb{Z}} : \exists M > 0 : |x_n| \leq M, \text{ for every } n \right\}$$

$(x_n)_n$  is bounded.

$\|x\|_\infty = \sup_n |x_n| = \text{supremum of } \{ |x_n|, n \in \mathbb{Z} \}$ .

Defines a norm

ONB: Orthonormal Basis.

Let:  $V = \mathbb{C}^n$  and  $\langle \cdot, \cdot \rangle$  is a scalar product on  $V$ .

Definition A set  $\{e_1, e_2, \dots, e_n\} \subset V$  is called an orthonormal basis (ONB) if:

- (1)  $\{e_1, e_2, \dots, e_n\}$  is basis for  $V$  ↖ BASIS
- (2)  $\langle e_i, e_j \rangle = \begin{cases} 1, & \text{if } i=j \\ 0, & \text{if } i \neq j \end{cases}$  ↖ ORTHONORMALITY!  
for every  $1 \leq i, j \leq n$ .

Remark: If  $V$  is finite dimensional (which is the case here,  $V = \mathbb{C}^n$ ).

(2)  $\Rightarrow$  (1) : [ORTHONORMAL & there are  $n$  vectors]  $\Rightarrow$  BASIS.

What is an ONB good for?

Let  $(V, \langle \cdot, \cdot \rangle)$  be a <sup>vector space with</sup> scalar product.

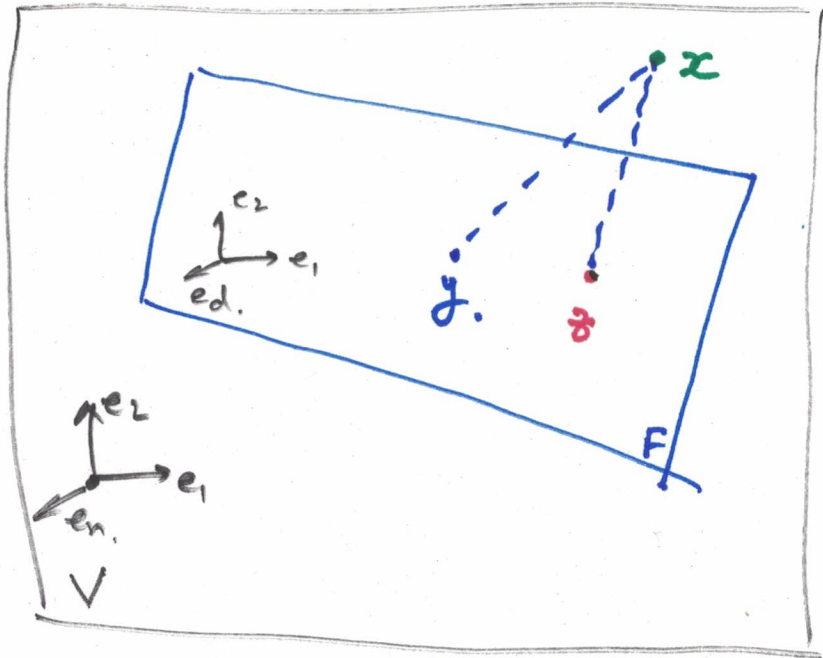
Assume  $\{e_1, e_2, \dots, e_n\}$  is ONB in  $V$ .

Fix  $1 \leq d \leq n$ . Let  $F = \text{span}\{e_1, e_2, \dots, e_d\} = \left\{ \sum_{k=1}^d c_k e_k = c_1 e_1 + \dots + c_d e_d \mid c_1, \dots, c_d \in \mathbb{C} \right\}$ .

Note:  $F$  is a vector space, subset of  $V$ .  
 $\dim F = d$ .

Problem: Given  $x \in V$ , find  $z \in F$  that minimizes:

$\min_{y \in F} \|y - x\|$



Want: Find a (the) point  $z \in F$  such that:

$$\|z - x\| \leq \|y - x\|, \text{ for every } y \in F$$

Theorem. Assume the setup introduced before:  $(V, \langle \cdot, \cdot \rangle)$  is a vector space with scalar product;  $\{e_1, \dots, e_n\}$  ONB in  $V$ ;  $1 \leq d \leq n$ ;  $F = \text{Span}\{e_1, \dots, e_d\}$ . Let  $x \in V$ .

Then the vector  $z = \langle x, e_1 \rangle e_1 + \langle x, e_2 \rangle e_2 + \dots + \langle x, e_d \rangle e_d$

satisfies:

$$\|z - x\| \leq \|y - x\|, \text{ for every } y \in F.$$

Notation: The map  $x \mapsto z$  is called the orthogonal projection

of  $x$  onto  $F$ . Notation:  $P_F : x \mapsto P_F(x) = \langle x, e_1 \rangle e_1 + \dots + \langle x, e_d \rangle e_d$

Remark: If  $d = n$ . Then  $F = V$  and  $z = x$ :

$$x = \langle x, e_1 \rangle e_1 + \langle x, e_2 \rangle e_2 + \dots + \langle x, e_n \rangle e_n. \quad \left. \vphantom{x} \right\} \begin{array}{l} \text{ONB} \\ \text{decomposition} \\ \text{of } x. \end{array}$$

Why (Theorem)

Need:

$$\|z-x\|^2 \leq \|y-x\|^2$$

$$c_1 e_1 + \dots + c_d e_d$$

for any  $c_1 \dots c_d \in \mathbb{C}$

$$\langle x, e_1 \rangle e_1 + \dots + \langle x, e_d \rangle e_d.$$

Check in a simplified case:  $d=2, n=3.$

and  $\langle x, y \rangle =$

$$= x_1 \bar{y}_1 + x_2 \bar{y}_2 + x_3 \bar{y}_3$$

$$e_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, e_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, e_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}.$$

$$z = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}, \dots \rightarrow z = x_1 \cdot \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} + x_2 \cdot \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} x_1 \\ x_2 \\ 0 \end{pmatrix}.$$

$$F = \text{Span} \{e_1, e_2\} = \left\{ c_1 e_1 + c_2 e_2 = \begin{pmatrix} c_1 \\ c_2 \\ 0 \end{pmatrix}, c_1, c_2 \in \mathbb{C} \right\}.$$

$$\left\| \begin{pmatrix} x_1 \\ x_2 \\ 0 \end{pmatrix} - \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \right\|^2 \leq \left\| \begin{pmatrix} c_1 \\ c_2 \\ 0 \end{pmatrix} - \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \right\|^2$$

$$\underline{\underline{|x_3|^2}} \leq \underbrace{|c_1 - x_1|^2 + |c_2 - x_2|^2 + \underline{\underline{|x_3|^2}}}$$

always true.

$\geq 0. \Rightarrow z$  is unique!