ZERO SET OF ZAK TRANSFORM AND THE HRT CONJECTURE

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ABSTRACT. The HRT (Heil-Ramanathan-Topiwala) posits the linear independence of any set of nonzero square-integrable vectors obtained from a single nonzero vector f by applying a finite set of time-frequency shift operators. In this short note, we present findings centered on the zero set of the Zak transform of f, and a distinct arrangement involving a finite set of N points on an integer lattice in the time-frequency plane, excluding a specific point.

1. INTRODUCTION

The HRT Conjecture [3] posits that a finite system of time-frequency shifted copies of a nonzero square-integrable function will always be linearly independent. For an updated overview of this conjecture, please refer to our latest work [5].

Following up on [5], the primary objective of this short note is to present a number of new results for this conjecture. Let's consider a function f that is nonzero in $L^2(\mathbb{R}^n)$. Choose an arbitrary natural number N. Following this, we construct a finite system of vectors, which we will denote as $\mathcal{F}_{(N,1)}$ in the following manner

$$\left\{t \mapsto e^{-2\pi i \left\langle y^{(j)}, t\right\rangle} f\left(t - x^{(j)}\right) : \left(x^{(1)}, y^{(1)}\right), \cdots, \left(x^{(N)}, y^{(N)}\right) \in \mathbb{Z}^{2n}\right\} \cup \left\{t \mapsto e^{-2\pi i \left\langle y, t\right\rangle} f\left(t - x\right)\right\}.$$

This system includes functions of the form

$$t \mapsto e^{-2\pi i \langle y^{(j)}, t \rangle} f\left(t - x^{(j)}\right) \in L^2\left(\mathbb{R}^n\right)$$

where each $(x^{(1)}, y^{(1)}), \dots, (x^{(N)}, y^{(N)})$ belongs to the integer full-rank lattice \mathbb{Z}^{2n} . Furthermore, it includes a time-frequency-shifted vector of the form $t \mapsto e^{-2\pi i \langle y, t \rangle} f(t-x) \in L^2(\mathbb{R}^n)$ where (x, y) can be identified with a point on the time-frequency plane. We establish the following as valid:

Proposition 1. Suppose that the Zak transform of f is continuous. Then the system of vectors $\mathcal{F}_{(N,1)}$ is linearly independent under the condition that the group which is generated by (-x, y) modulo \mathbb{Z}^{2n} is a dense subset of the 2n-dimensional torus $[0,1)^n \times [0,1)^n$.

The subsequent finding indicates that for functions that decay at a sufficiently rapid rate, the zero set of their Zak transform remains unchanged under a specific symmetry.

Proposition 2. If $\mathcal{F}_{(N,1)}$ is linearly dependent then the zero set of the Zak transform of f is invariant under the action

 $[0,1)^n \times [0,1)^n \ni z \mapsto z + (-x,y) \mod \mathbb{Z}^{2n} \in [0,1)^n \times [0,1)^n.$

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Proposition 3. Suppose that the Zak transform of f is continuous and has a finite number of zeros in the unit square $[0,1)^n \times [0,1)^n$. The system of vectors $\mathcal{F}_{(N,1)}$ is linearly independent under the condition that the group which is generated by (-x, y) modulo \mathbb{Z}^{2n} forms a countably infinite subset (not necessarily dense) of the 2n-dimensional torus $[0,1)^n \times [0,1)^n$.

As a straightforward application of Proposition 3, we settle the HRT Conjecture with respect to the configuration at hand for a certain class of totally positive functions.

Corollary 4. Let f be a totally positive nonzero function without Gaussian factor in its Fourier transform. Then the system of vectors

$$\mathcal{F} = \left\{ t \mapsto e^{-2\pi i y^{(j)} t} f\left(t - x^{(j)}\right) : x^{(1)}, y^{(1)}, \cdots, x^{(N)}, y^{(N)} \in \mathbb{Z} \right\} \cup \left\{ t \mapsto e^{-2\pi i y t} f\left(t - x\right) \right\}$$

is linearly independent.

Proof. Let's consider a function, f, which is totally positive and does not have a Gaussian factor in its Fourier transform. According to [4], the Zak transform of f is continuous and admits only one zero on its fundamental domain of quasi-periodicity. If $\dim_{\mathbb{Q}} (\mathbb{Q} + \mathbb{Q}x + \mathbb{Q}y) = 1$ then we are in the case of rational time-frequency shifts, and in this case, the HRT Conjecture is known to always be true. Suppose next that $\dim_{\mathbb{Q}} (\mathbb{Q} + \mathbb{Q}x + \mathbb{Q}y) > 1$. Then the group generated by (-x, y) modulo \mathbb{Z}^2 is infinite and the stated corollary is immediate. \Box

2. Proof of Propositions 1, 2, and 3

Let \mathfrak{h}_n be the (2n+1)-dimensional Heisenberg algebra. For a concrete realization [1], one may choose an algebra constructed on the basis set $\{X_1, \dots, X_n, Y_1, \dots, Y_n, Z\}$. This algebra can be expressed as follows: $\sum_{k=1}^n x_k X_k + \sum_{k=1}^n y_k Y_k + zZ$ where

$$\sum_{k=1}^{n} x_k X_k + \sum_{k=1}^{n} y_k Y_k + zZ = \begin{bmatrix} 0 & x_1 & \cdots & x_n & z \\ & & & y_1 \\ & & \ddots & & \vdots \\ & & & & y_n \\ 0 & & & & 0 \end{bmatrix}$$

Its associated Lie group denoted as H_n is given by:

$$H_n = \left\{ \exp\left(zZ\right) \exp\left(\sum_{k=1}^n y_k Y_k\right) \exp\left(\sum_{k=1}^n x_k X_k\right) = \begin{bmatrix} 1 & x_1 & \cdots & x_n & z \\ & & & y_1 \\ & & \ddots & & \vdots \\ & & & & y_n \\ 0 & & & & 1 \end{bmatrix} : x_j, y_k, z \in \mathbb{R} \right\}.$$

It is a well-established fact that H_n acts unitarily and irreducibly on $L^2(\mathbb{R}^n)$ via π as follows: Given points $y = (y_1, \dots, y_n), x = (x_1, \dots, x_n) \in \mathbb{R}^n$ and a vector $f \in L^2(\mathbb{R}^n)$, one has: (a) multiplication by characters

$$\left[\pi \exp\left(zZ\right)f\right]\left(\exp\left(\sum_{k=1}^{n} t_k X_k\right)\right) = e^{2\pi i z} f\left(\exp\left(\sum_{k=1}^{n} t_k X_k\right)\right)$$

(b) a modulation action of the form

$$\left[\pi\left(\exp\left(\sum_{k=1}^{n} y_k Y_k\right)\right)f\right]\left(\exp\left(\sum_{k=1}^{n} t_k X_k\right)\right) = e^{-2\pi i \langle y,t \rangle} f\left(\exp\left(\sum_{k=1}^{n} t_k X_k\right)\right)$$

and (c) a translation action defined as

$$\left[\pi\left(\exp\left(\sum_{k=1}^{n} x_k X_k\right)\right)f\right](t) = f\left(\exp\left(\sum_{k=1}^{n} \left(t_k - x_k\right) X_k\right)\right).$$

Suppose that there exists a nonzero vector $f \in L^2(\mathbb{R}^n)$ such that

$$\left\{\pi\left(\exp\left(\sum_{k=1}^{n}\ell_{k}^{(j)}Y_{k}\right)\exp\left(\sum_{k=1}^{n}m_{k}^{(j)}X_{k}\right)\right)f:1\leq j\leq N\right\}\cup\left\{\pi\left(\exp\left(\sum_{k=1}^{n}y_{k}Y_{k}\right)\exp\left(\sum_{k=1}^{n}x_{k}X_{k}\right)\right)f\right\}$$

is linearly dependent for some finite points lattice points of the form

$$\sum_{k=1}^{n} \ell_k^{(j)} Y_k \in \sum_{k=1}^{n} \mathbb{Z} Y_k,$$
$$\sum_{k=1}^{n} m_k^{(j)} X_k \in \sum_{k=1}^{n} \mathbb{Z} X_k, 1 \le j \le N$$

and

$$\sum_{k=1}^{n} y_k Y_k \in \sum_{k=1}^{n} \mathbb{R} Y_k,$$
$$\sum_{k=1}^{n} x_k X_k \in \sum_{k=1}^{n} \mathbb{R} X_k.$$

In other words, there exist nonzero complex numbers c_1, \dots, c_N such that

$$\sum_{j=1}^{N} c_j \pi \left(\exp\left(\sum_{k=1}^{n} \ell_k^{(j)} Y_k\right) \exp\left(\sum_{k=1}^{n} m_k^{(j)} X_k\right) \right) f = \pi \left(\exp\left(\sum_{k=1}^{n} y_k Y_k\right) \exp\left(\sum_{k=1}^{n} x_k X_k\right) \right) f.$$

Next, let $Z: L^2(\mathbb{R}^n) \to L^2([0,1)^n \times [0,1)^n)$ be the Zak transform [2], formally defined as follows:

$$Zf(t,\omega) = \sum_{\tau_1 \in \mathbb{Z}} \cdots \sum_{\tau_n \in \mathbb{Z}} f\left(\exp\left(\sum_{k=1}^n \left(t_k + \tau_k\right) X_k\right)\right) e^{-2\pi i \langle \omega, \tau \rangle}$$

where $\tau = (\tau_1, \dots, \tau_n)$. Then it is known that the Zak transform is a unitary operator whose range consists of quasi-periodic functions (see [2], Section 8.1 on Page 147 and Theorem 8.2.5 on Page 154.)

Furthermore, it is perhaps worth noting the following properties of the Zak transform:

- If f is integrable then $Zf \in L^1([0,1)^n \times [0,1)^n)$
- If f is continuous and additionally,

$$\sum_{\ell \in \mathbb{Z}^n} \mathrm{esssup}_{t \in [0,1)^n} \left| f\left(t + \ell \right) \right| < \infty$$

then Zf is continuous.

• The Zak transform maps Schwartz functions to smooth function on $[0,1)^n \times [0,1)^n$. Also, if F is quasiperiodic on $\mathbb{R}^n \times \mathbb{R}^n$ then F = Zf for some unique Schwartz function f.

Applying the Zak transform to each side of the following equation:

$$\sum_{j=1}^{N} c_j \pi \left(\exp\left(\sum_{k=1}^{n} \ell_k^{(j)} Y_k\right) \exp\left(\sum_{k=1}^{n} m_k^{(j)} X_k\right) \right) f = \pi \left(\exp\left(\sum_{k=1}^{n} y_k Y_k\right) \exp\left(\sum_{k=1}^{n} x_k X_k\right) \right) f$$

we obtain:

$$\sum_{j=1}^{N} c_j \sum_{\tau_1 \in \mathbb{Z}} \cdots \sum_{\tau_n \in \mathbb{Z}} e^{-2\pi i \langle t+\tau, \ell^{(j)} \rangle} f\left(\exp\left(\sum_{k=1}^{n} \left(t_k + \tau_k - m_k^{(j)} \right) X_k \right) \right) e^{-2\pi i \langle \omega, \tau \rangle} \\ = \sum_{\tau_1 \in \mathbb{Z}} \cdots \sum_{\tau_n \in \mathbb{Z}} e^{-2\pi i \langle t+\tau, y \rangle} f\left(\exp\left(\sum_{k=1}^{n} \left(t_k + \tau_k - x_k \right) X_k \right) \right) e^{-2\pi i \langle \omega, \tau \rangle}.$$

On the one hand,

$$\sum_{j=1}^{N} c_j \sum_{\tau_1 \in \mathbb{Z}} \cdots \sum_{\tau_n \in \mathbb{Z}} e^{-2\pi i \langle t+\tau, \ell^{(j)} \rangle} f\left(\exp\left(\sum_{k=1}^{n} \left(t_k + \tau_k - m_k^{(j)} \right) X_k \right) \right) e^{-2\pi i \langle \omega, \tau \rangle} \\ = \sum_{j=1}^{N} c_j e^{-2\pi i \langle t, \ell^{(j)} \rangle} \sum_{\tau_1 \in \mathbb{Z}} \cdots \sum_{\tau_n \in \mathbb{Z}} e^{-2\pi i \langle \tau, \ell^{(j)} \rangle} f\left(\exp\left(\sum_{k=1}^{n} \left(t_k + \tau_k - m_k^{(j)} \right) X_k \right) \right) e^{-2\pi i \langle \omega, \tau \rangle} \\ \left(e^{-2\pi i \langle \tau, \ell^{(j)} \rangle} = 1 \right) = \sum_{j=1}^{N} c_j e^{-2\pi i \langle t, \ell^{(j)} \rangle} \sum_{\tau_1 \in \mathbb{Z}} \cdots \sum_{\tau_n \in \mathbb{Z}} f\left(\exp\left(\sum_{k=1}^{n} \left(t_k + \tau_k - m_k^{(j)} \right) X_k \right) \right) e^{-2\pi i \langle \omega, \tau \rangle}.$$

Moreover, the change of variable $\tau_k\mapsto \tau+m_k^{(j)}$ yields

$$\begin{split} &\sum_{j=1}^{N} c_{j} \sum_{\tau_{1} \in \mathbb{Z}} \cdots \sum_{\tau_{n} \in \mathbb{Z}} e^{-2\pi i \langle t+\tau, \ell^{(j)} \rangle} f\left(\exp\left(\sum_{k=1}^{n} \left(t_{k}+\tau_{k}-m_{k}^{(j)}\right) X_{k}\right)\right) e^{-2\pi i \langle \omega, \tau \rangle} \\ &= \sum_{j=1}^{N} c_{j} e^{-2\pi i \langle t, \ell^{(j)} \rangle} \sum_{\tau_{1} \in \mathbb{Z}} \cdots \sum_{\tau_{n} \in \mathbb{Z}} f\left(\exp\left(\sum_{k=1}^{n} \left(t_{k}+\tau_{k}\right) X_{k}\right)\right) e^{-2\pi i \langle \omega, \tau+m^{(j)} \rangle} \\ &= \sum_{j=1}^{N} c_{j} e^{-2\pi i \langle t, \ell^{(j)} \rangle} e^{-2\pi i \langle \omega, m^{(j)} \rangle} \sum_{\tau_{1} \in \mathbb{Z}} \cdots \sum_{\tau_{n} \in \mathbb{Z}} f\left(\exp\left(\sum_{k=1}^{n} \left(t_{k}+\tau_{k}\right) X_{k}\right)\right) e^{-2\pi i \langle \omega, \tau \rangle} \\ &= \left(\sum_{j=1}^{N} c_{j} e^{-2\pi i \langle t, \ell^{(j)} \rangle} e^{-2\pi i \langle \omega, m^{(j)} \rangle} \right) \cdot Zf\left(t, \omega\right). \end{split}$$

Furthermore,

$$\sum_{\tau_1 \in \mathbb{Z}} \cdots \sum_{\tau_n \in \mathbb{Z}} e^{-2\pi i \langle t+\tau, y \rangle} f\left(\exp\left(\sum_{k=1}^n \left(t_k - x_k + \tau_k\right) X_k\right) \right) e^{-2\pi i \langle \omega, \tau \rangle} \\ = e^{-2\pi i \langle t, y \rangle} \sum_{\tau_1 \in \mathbb{Z}} \cdots \sum_{\tau_n \in \mathbb{Z}} e^{-2\pi i \langle \tau, y \rangle} f\left(\exp\left(\sum_{k=1}^n \left(t_k - x_k + \tau_k\right) X_k\right) \right) e^{-2\pi i \langle \omega, \tau \rangle}$$

$$= e^{-2\pi i \langle t,y \rangle} \sum_{\tau_1 \in \mathbb{Z}} \cdots \sum_{\tau_n \in \mathbb{Z}} f\left(\exp\left(\sum_{k=1}^n \left(t_k - x_k + \tau_k \right) X_k \right) \right) e^{-2\pi i \langle \omega + y, \tau \rangle}$$
$$= e^{-2\pi i \langle t,y \rangle} Z f\left(t - x, \omega + y \right).$$

In summary, we have

$$\left(\sum_{j=1}^{N} c_{j} e^{-2\pi i \langle t, \ell^{(j)} \rangle} e^{-2\pi i \langle \omega, m^{(j)} \rangle}\right) \cdot Zf(t, \omega) = e^{-2\pi i \langle t, y \rangle} Zf(t - x, \omega + y)$$

For more compact notation, let $(t, \omega) = z \in [0, 1)^n \times [0, 1)^n$, F = Zf, $\gamma = (-x, y)$ and let P be the trigonometric polynomial given by

$$P(t,\omega) = \sum_{j=1}^{N} c_j e^{-2\pi i \left\langle t, \ell^{(j)} \right\rangle} e^{-2\pi i \left\langle \omega, m^{(j)} \right\rangle}.$$

Given these definitions, we can see that the product of the absolute values of P and F at the point z equals the absolute value of F at the point z shifted by γ . In other words, for $z \in [0,1)^n \times [0,1)^n$,

$$|P(z)| \cdot |F(z)| = |F(z + \gamma)|$$

Furthermore, |F| is a \mathbb{Z}^{2n} -periodic square-integrable function.

As referenced in Lemma 8.4.2 of [2], if F is a continuous function, it is guaranteed to have at least one zero within the unit square defined by $[0,1)^n \times [0,1)^n$. By successively applying the equation

$$|P(z)| \cdot |F(z)| = |F(z + \gamma)|$$

we deduce that for any natural number m,

$$|F(z+m\gamma)| = \prod_{j=0}^{m-1} |P(z+j\gamma)| \cdot |F(z)|.$$

Let Γ be the group generated by γ modulo \mathbb{Z}^{2n} . Then Γ is a countable subgroup of the 2*n*-dimensional torus $[0,1)^n \times [0,1)^n$.

2.1. **Proof of Proposition 1.** If the set Γ is dense in the torus $[0,1)^n \times [0,1)^n$, it implies that the zero set of the function F must also be densely distributed in this unit square as well. Considering that F is a continuous function, it logically follows that F must be identically zero across its domain. This validates Proposition 1.

2.2. Proof of Proposition 2. Fix $\lambda \in \text{Zero}(Zf)$ then for any natural number m,

$$|F(\lambda + m\gamma)| = \prod_{j=0}^{m-1} |P(\lambda + j\gamma)| \cdot |F(\lambda)| = 0.$$

The calculation above suggests that if λ belongs to the zero set of Zf (denoted as Zero (Zf)), then the term $(\lambda + m\gamma) \mod \mathbb{Z}^{2n}$ is also a member of the zero set of Zf. This highlights that the zero set of Zf is invariant under the operation of Γ . More specifically, it underlines that the zero set of Zf remains unaltered under the action of γ . 2.3. **Proof of Proposition 3.** Suppose that Γ is an infinite set and let Zero(Zf) be the zero set of the Zak transform of f. Fix $\lambda \in \text{Zero}(Zf)$ then for any natural number m,

$$|F(\lambda + m\gamma)| = \prod_{j=0}^{m-1} |P(\lambda + j\gamma)| \cdot |F(\lambda)| = 0.$$

This means that

$$\lambda \in \operatorname{Zero}(Zf) \Rightarrow (\lambda + m\gamma) \mod \mathbb{Z}^{2n} \in \operatorname{Zero}(Zf)$$

and this shows that $|\text{Zero}(Zf)| = \infty$, contradicting the assumption that the zero set of the Zak transform of f is finite.

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