

# Statistical Computing with **R**

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## Overview of Course

This course was originally developed jointly with Benjamin Kedem and Paul Smith. It consists of modules as indicated on the Course Syllabus. These fall roughly into three main headings:

- (A). **R** (& **SAS**) language elements and functionality, including computer-science ideas;
- (B). Numerical analysis ideas and implementation of statistical algorithms, primarily in **R**; and
- (C). Data analysis and statistical applications of (A)-(B).

The object of the course is to reach a point where students have some facility in generating statistically meaningful models and outputs. Whenever possible, the use of **R** and numerical-analysis concepts is illustrated in the context of analysis of real or simulated data. The assigned homework problems will have the same flavor.

The course formerly introduced **Splus**, where now we emphasize the use of **R**. The syntax is very much the same for the two packages, but **R** costs nothing and by now has much greater capabilities. Also, in past terms **SAS** has been introduced primarily in the context of linear and generalized-linear models, to contrast its treatment of those models with the treatment in **R**. Students in this course have often had a separate and more detailed introduction to **SAS** in some other course, so in the present term we will

not present details about **SAS**, in order to leave time for interesting data-analytic topics such as Markov Chain Monte Carlo (MCMC) and multi-level modeling in **R**.

Various public datasets will be made available for illustration, homework problems and data analysis projects, as indicated on the course web-page.

The contents of these notes, not all of which are posted currently, and which will be augmented as the term progresses, are:

- 1. Introduction to R**  
Unix and R preliminaries, R language basics, inputting data, lists and data-frames, factors, functions.
- 2. Random Number Generation & Simulation**  
Pseudo-random number generators, shuffling, goodness of fit testing.
- 3. Graphics**
- 4. Simulation Speedup Methods**
- 5. Numerical Maximization & Root-finding**  
(respectively for log-likelihoods and estimating equations)
- 6. Commands for Subsetting**  
Manipulating Arrays and Data Frames
- 7. Spline Smoothing Methods**
- 8. EM Algorithm**
- 9. The Bootstrap Idea**
- 10. Markov Chain Monte Carlo**  
Metropolis and Gibbs Sampling Algorithms  
Convergence Diagnostics for MCMC  
Bayesian Data Analysis applications using WinBugs
- 11. Multi-level Model Data Analysis**  
Linear and Generalized Linear Model Fitting and Interpretation

A few Exercises are contained in these notes, but all formal Homework assignments are posted separately in the course web-page Homework directory.

## 8 Notes on Markov Chain Monte Carlo

Markov Chain Monte Carlo is a big, and currently very rapidly developing, subject in statistical computation. Many complex and multivariate types of random data, useful for maximizing likelihood in missing-data settings or for calculating expectations and conditional expectations in Bayesian analysis, can be simulated in this way (generally, via the **Metropolis-Hastings Algorithm** or the **Gibbs Sampler**, the two main simulation algorithms understood under the heading of MCMC). We give a brief sketch of each of these, and give a computational example of somewhat realistic complexity connected with the simulation of conditional distribution for random effects given the observed data in a *random intercept logistic regression* setting.

A good general reference for Markov Chain Monte Carlo topics is the book

**Monte Carlo Statistical Methods**, by C. Robert and G. Casella, Springer-Verlag 1999.

There is a good deal of background on continuous-state discrete-time Markov Chains to understand, if you want a solid theoretical understanding of the methods. In general, the idea and usefulness of the methods is that if you want to estimate expectations via averages of simulated vector random values  $X_t$  from a density  $f(\cdot)$ , it is enough to simulate values of a Markov Chain which asymptotically becomes stationary and has unique equilibrium distribution with density  $f$ . In general, one deals with continuous-state discrete-time chains. The main idea of the subject is given in the

**Metropolis-Hastings Algorithm:** fix an initial data-vector  $X_0$ , and a conditional density (or *proposal distribution* or *transition kernel*  $q(x|y)$ , which can be arbitrary except that it should (in both  $x, y$  arguments) have the same support as  $f$  and for good properties of the algorithm should have  $f(x)/q(x|y)$  uniformly bounded in  $x, y$ . Then simulate values  $X_{t+1}$ ,  $t \geq 0$ , according to the Markovian inductive step,

$$Y_t \sim q(\cdot | X_t) \quad \text{and} \quad \xi_t \sim Unif[0, 1] \quad \text{independent}$$

and

$$X_{t+1} = Y_t \quad \text{if} \quad \xi_t \leq \frac{f(Y_t) q(X_t | Y_t)}{f(X_t) q(Y_t | X_t)}, \quad \text{otherwise} \quad = X_t$$

The key idea of this algorithm is that the distribution of  $X_{t+1}$  is a mixture of that of  $X_t$  and  $Y_t$ , so that if  $\rho(x, y) = \min(1, f(y)q(x|y)/(f(x)q(y|x)))$ , then the (mixed discrete and continuous type) transition kernel for the simulated Markov chain is

$$K(y|x) = \delta_x(y) \int q(z|x) (1 - \rho(x, z)) dz + q(y|x) \rho(x, y)$$

Since the definitions imply  $q(y|x) f(x) \rho(x, y) = \min(q(y|x)f(x), q(x|y)f(y)) = q(x|y) f(y) \rho(y, x)$ , it is easy to check the *detailed-balance* or *reversibility* condition relating the kernel  $K$  to the equilibrium density  $f$  in the form

$$\begin{aligned} K(y|x) f(x) &= \delta_{x,y} \int q(z|x) (1 - \rho(x, z)) dz + \min(q(y|x)f(x), q(x|y)f(y)) \\ &\equiv K(x|y) f(y) \end{aligned}$$

The reversibility of the Markov Chain  $X_t$  implies there is a unique invariant measure (mutually absolutely continuous to the measure  $f(x) dx$ ) follow. The consequence is that  $f$  is an essentially unique invariant density with given support, i.e. the unique density solving  $f(x) = \int K(x|z) f(z) dz$ .

The general idea of the **Gibbs Sampler** is apparently different but turns out to be closely related. Suppose that one wants to simulate from a complicated joint density  $h(X^{(1)}, \dots, X^{(p)})$  for which all of the conditional densities of  $X^{(j)}$  given the other  $(X^{(i)} : 1 \leq i \leq p, i \neq j)$  are not too hard to simulate from. Then it turns out that by alternately simulating successively for rotating values  $i$  the pieces  $X_t^{(i)}$  conditionally from these densities, a Markov-chain equilibrium can again under general conditions guarantee the asymptotic stationarity of the simulated concatenated vectors  $(X_t^{(j)}, 1 \leq j \leq p)$  with the desired density as essentially unique invariant density. This approach is particularly fruitful for carefully designed *hierarchical models*.

## 8.1 EXTENDED EXAMPLE: RANDOM-INTERCEPT LOGISTIC REGRESSION

Consider the problem of ML estimation based on independent trivariate data-vectors  $((R_i, W_i, n_i), i = 1, \dots, m)$  for parameters  $\vartheta = (a, b, \sigma^2)$  in the following model: sample sizes  $n_i$  and predictors  $W_i$  are either fixed design

constants (such that their histogram settles down to some reasonably stable shape for large  $m$ ) or are *iid* pairs with distribution not depending on the parameters  $\vartheta$ , and

$$U_i \sim \mathcal{N}(0, \sigma^2) \quad \text{iid independent of } \{W_j\}_{j=1}^m$$

$$R_i \sim \text{Binom}(n_i, \frac{e^{a+bW_i+U_i}}{1 + e^{a+bW_i+U_i}}) \quad \text{conditionally given } \{(W_j, U_j)\}_{j=1}^m$$

Our objective is therefore to maximize over  $(a, b, \sigma^2)$

$$\sum_{i=1}^m \log \left\{ \int \frac{e^{(a+bW_i+u)R_i}}{(1 + e^{a+bW_i+u})^{n_i}} \cdot \frac{1}{\sqrt{2\pi\sigma^2}} e^{-u^2/(2\sigma^2)} du \right\} \quad (1)$$

Clearly, this kind of random-effect model is a ‘missing-data’ model in the same sense as the models which are studied using the EM algorithm. The model would be relatively simple to analyze if the intercept-effects  $U_i$  were observable. Without observability of the  $U_i$ , one must either numerically integrate the log-likelihood terms in (1) or simulate to estimate them. For documentation of a numerical integration approach to accurate calculation and maximization of log-likelihood for models including this one, see Technical Report #2 of Slud (2000) under

<http://www.census.gov/hhes/www/saipe/tecrep.html>

For an extended discussion of estimation strategies involving MCMC in problems like the one discussed here, see

McCulloch, C. (1997) Maximum likelihood algorithms for generalized linear mixed models. *Jour. Amer. Statist. Assoc.* **92**, 162-70.

**A Direct Monte Carlo Method.** In the ML problem posed here, the log-likelihood terms could all be directly estimated via Monte Carlo by choosing a large  $M$ , simulating an array  $(V_{ik}, 1 \leq i \leq m, 1 \leq k \leq M)$  of *iid*  $\mathcal{N}(0, 1)$  random variables, and maximizing instead

$$\sum_{i=1}^m \log \left\{ M^{-1} \sum_{k=1}^M \frac{e^{(a+bW_i+\sigma V_{ik})R_i}}{(1 + e^{a+bW_i+\sigma V_{ik}})^{n_i}} \right\} \quad (2)$$

This Monte Carlo evaluation of integrals could work here, but would not be preferred to a numerical integration, e.g. by (adaptive) Gaussian quadratures. The maximization, e.g. by Newton-Raphson, is feasible by either method of evaluation of integrals, but quite costly computationally by this Monte Carlo method, and not especially accurate if some of the  $n_i$  are large.

**EM Algorithm Method.** Another approach would be to use the EM algorithm, if one could simulate  $\{U_{it}\}_{t=1}^T$  from the conditional distribution of  $U_i$  given  $X_i, W_i$ . The E-step would then, for a fixed parameter-triple  $\vartheta_1 = (a_1, b_1, \sigma_1^2)$ , replace the  $i$ 'th term of (1) by

$$T^{-1} \sum_{t=1}^T \log \left( \frac{e^{(a+bW_i+\sigma U_{it})R_i}}{(1 + e^{a+bW_i+\sigma U_{it}})^{n_i}} \right) \quad (3)$$

The M-step would maximize over  $\vartheta = (a, b, \sigma^2)$  the resulting (E-step estimated conditional expected) log-likelihood summation, the summation over  $i = 1, \dots, m$  of (3), to find the next parameter-iterates  $\vartheta_2 = (a_2, b_2, \sigma_2^2)$ .

So we continue this example by exploring how to simulate (without numerical integration) approximately stationary random sequences from the conditional distribution of  $U_i$  given  $(R_i, W_i)$ . To keep the discussion simple, we restrict to the case  $n_i = 1$  and strip the subscript  $i$ . (In the more complicated case of varying  $n_i$ , one would use a Metropolis-Hastings idea similar to the following one, but with  $g$  replaced by a normal distribution designed to approximate the integrand in the ( $i$ 'th term of) expression (1).

We adopt an 'independent' Metropolis-Hastings Algorithm, with  $q(x|y) \equiv g(x) \equiv e^{-x^2/(2\sigma)^2}/\sqrt{2\pi\sigma^2}$ . The algorithm takes the following form:  $\xi_t \sim Unif[0, 1]$ ,  $Y_t \sim \mathcal{N}(0, \sigma^2)$  are simulated independently of each other and of variables indexed smaller than  $t$ , and

$$X_{t+1} = Y_t \quad \text{if} \quad \xi_t \leq \frac{e^{(Y_t - X_t)R} (1 + e^{a+bW+X_t})^n}{(1 + e^{a+bW+Y_t})^n} \quad , \quad \text{otherwise} \quad = X_t$$

Our next task is to implement and test this algorithm in Splus. Here is a general function to do it, using input-vectors  $\mathbf{Uv}$ ,  $\mathbf{Rv}$ ,  $\mathbf{nv}$ ,  $\mathbf{etav}$  (respectively corresponding to  $U, R, n, \eta = a + bW$ ) of the same length  $m$ , and also using  $m \times T$  matrices  $\mathbf{Um}$ ,  $\mathbf{Ym}$  respectively of *iid* standard Uniform and Normal( $0, \sigma^2$ ) deviates.

```

> MHblk
function(Uv,Rv,etav, nv, sig, nblk=1) {
  LR <- length(Rv)
  Ym <- sig*matrix(rnorm(LR*nblk), ncol=nblk)
  auxm <- matrix(runif(LR*nblk), ncol=nblk)
  Um <- array(0, dim=c(LR, nblk))
  for(ctr in 1:nblk) {
    Yv <- Ym[,ctr]
    probs <- pmin(exp(Rv*(Yv-Uv))*((1+exp(
      etav+Uv))/(1+exp(etav+Yv)))^nv,1)
    Um[,ctr] <- ifelse(auxm[,ctr] < probs,
      Yv, Uv)
    if(ctr < nblk) Uv <- Um[,ctr]
  }
  Um
}

```

We test this function on a simple case, by finding the analytical (conditional) expectation of  $u_i$  and  $\log(\exp(\eta + u_i)R/(1 + \exp(\eta + u_i))^n)$  and then reproducing the values by MCMC simulation. Here we use the values  $n = 5, R = 2, a = -1, b = 1, \sigma = .3, W = .65$ :

```

> integrate(function(x) x*exp((- .35+x)*2)*dnorm(x,sd=.3)/
  (1+exp(-.35+x))^5, -15,15)$value/
  integrate(function(x) exp((- .35+x)*2)*dnorm(x,sd=.3)/
  (1+exp(-.35+x))^5, -15,15)$value
[1] -0.006108636 ### conditional expected u
> integrate(function(x) log(exp((- .35+x)*2)/(1+
  exp(-.35+x))^5)*exp((- .35+x)*2)*dnorm(x,sd=.3)/
  (1+exp(-.35+x))^5, -15,15)$value/
  integrate(function(x) exp((- .35+x)*2)*dnorm(x,sd=.3)/
  (1+exp(-.35+x))^5, -15,15)$value
[1] -3.41531 ## desired logLik expectation

```

## Now generate the U trajectory, starting with U=0.

```

> Useq <- c(MHblk(0,2,-.35,5,.3, nblk=100))
> c(mean(Useq), var(Useq))
[1] -0.01676858 0.07532460

```

```

> mean(log(exp((-0.35+Useq)*2)/(1+exp(-0.35+Useq))^5))
[1] -3.41071

> Useq <- c(Useq[51:100],MHblk(Useq[100],2,-0.35,5,.3,
  nblk=200)) ## uses last 50 of the previously
### generated values, plus 250 new ones
> c(mean(Useq), var(Useq))
[1] -0.02240471 0.07836955
> mean(log(exp((-0.35+Useq)*2)/(1+exp(-0.35+Useq))^5))
[1] -3.412525

### Now 1000 more:
> Useq <- c(MHblk(Useq[250],2,-0.35,5,.3,nblk=1000))
> c(mean(Useq), var(Useq))
[1] -0.01181766 0.08160613
> mean(log(exp((-0.35+Useq)*2)/(1+exp(-0.35+Useq))^5))
[1] -3.415085
### The answers are very stable.

```

These calculations were all very quick (1 second or less for each simulation-block).

## 8.2 EXAMPLE CONTINUED: MCMC IN EM

Finally ,we provide a summary and **R** log of the use of this MCMC step in an EM iteration for maximizing logLik. We begin by simulating a random-intercept logistic regression dataset of size 100 with vector `nv` of sample sizes generated as *Poisson*(3) random variables plus 1, with vector `W` of *Unif*[0,1] predictors, and parameters  $a = -1$ ,  $b = 1$ ,  $\sigma = .3$ .

```

> nv <- rpois(100,3) + 1
  etav <- -1 + runif(100)
  Rv <- rbinom(100, nv, plogis(etav+0.3*rnorm(100)))
> summary(Rv/nv)
  Min. 1st Qu.  Median    Mean 3rd Qu.    Max.
0.0000 0.1500 0.3333 0.3709 0.5000 1.0000

```

We generate starting values for  $a, b$  by ordinary logistic regression (without regard to the random intercept).

```
> glm(cbind(Rv, nv-Rv) ~ I(etav+1), family=binomial)$coef
(Intercept) I(etav + 1)
-1.089849    1.083622 ### Use these with sig=.5
> etav1 <- -1.08985 + 1.08362*(1+etav)
```

Now, our inductive EM step involves generating a block of 100 imputed  $U$  values for each data-item. Note that the imputed values fill up a  $100 \times 100$  matrix.

```
> unix.time(Um <- MHblk(rep(0,100),Rv,etav1,nv,0.5, nblk=100))
### very quick !!
> summary(c(Um))
      Min.   1st Qu.   Median     Mean   3rd Qu.     Max.
-1.850000 -0.341900 -0.007248 -0.008859  0.318800  1.716000
```

The next step is to average over the imputed columns to obtain the function to maximize in  $a, b$  at the next M-step.

```
> .01*sum(Rv*(etav1+Um)-nv*log(1+exp(etav1+Um)))
[1] -245.0789    ### estimated log of conditional expected
### complete-data Likelihood.
### Next an M-step maximization over a,b:
> tmpmin <- nlm(function(thet) {
  etapu <- thet[1]+thet[2]*(1+etav)+Um
  .01*sum(nv*log(1+exp(etapu))-Rv*etapu)
}, c(-1.090, 1.084))
$minimum
[1] 245.0337
$estimate
[1] -1.155570  1.160729
$gradient
[1] -1.606080e-05 -2.791413e-06 ### OK, approx converged
### On this iteration we have improved (conditional-
### expected complete-data) logLik to -245.034
```

```

### For comparison, calculate logLik at true values:
> Um0 <- MHblk(Um[,100],Rv,etav,nv,0.3, nblk=100)
### estimated H0 cond'l expected logLik:
> .01*sum(Rv*(etav+Um0)-nv*log(1+exp(etav+Um0)))
[1] -249.5472
> Um0 <- MHblk(Um0[,100],Rv,etav,nv,0.3, nblk=100)
> .01*sum(Rv*(etav+Um0)-nv*log(1+exp(etav+Um0)))
[1] -249.1056
### Recall: this is not the actual logLik
### but the estimate of the conditional expectation
### of the full-data logLik

### Now how would we update the estimate of sigma ?
### The simplest way would seem to be, use the formula
###   for sig^2 = unconditional variance of u =
###   expected conditional variance of u plus
###   variance of conditional expectation of u :

> mean(apply(Um,1,var)) + var(apply(Um,1,mean))
[1] 0.2441128 ### Not bad: two pieces are .204, .040
### and
> sig.old <- sqrt(.244) ### = 0.4940

```

Next we try a proper 3-parameter M-step in our quasi-EM algorithm. ('Quasi' because we are doing MCMC in place of numerical quadratures to obtain conditional expectations in the E-step.) In this step, we treat  $Um/\sigma$  as the imputed standard-normal deviates. We do a series of quasi-EM iterations in this way.

```

> th.old <- c(-1.089849, 1.083622, 0.5)
  Uma <- Um
  eta.old <- th.old[1] + th.old[2]*(etav+1)
  Uma <- MHblk(Uma[,100],Rv,eta.old,nv,th.old[3],
    nblk=100)/th.old[3]
  tmpmin3 <- nlm(function(thet) {
    etapu <- thet[1]+thet[2]*(1+etav)+thet[3]*Uma
    .01*sum(nv*log(1+exp(etapu))-Rv*etapu)

```

```

    }, th.old) ### converged, 9 iterations
$minimum
[1] 243.9371
$estimate
[1] -1.1382352  1.1268970  0.4618309
### successive additional iterates of exactly the same type
-1.1433864  1.1292849  0.4418853
-1.1291498  1.1123130  0.4070816
-1.1319344  1.1338868  0.3786870
-1.1252628  1.1193708  0.3348035
-1.1333165  1.1340783  0.3227082
-1.1144844  1.1136013  0.3161008
-1.1143326  1.1020129  0.3052926
-1.1186356  1.1016660  0.3010774
-1.0945004  1.0725082  0.2747137
-1.1063528  1.0811459  0.2855079
-1.1148067  1.1088207  0.2687424
-1.0987998  1.0840951  0.2569771
-1.1065303  1.0925731  0.2513654
-1.1077716  1.1034591  0.2502139
-1.1044592  1.0967187  0.2226806
-1.1061799  1.0973809  0.2266805
-1.1033295  1.0832668  0.2158493
-1.1074619  1.0941746  0.2242768

```

At this point, the EM iterations seem to have essentially converged. We conclude with a simple estimate of actual log-likelihood obtained by averaging complete-data likelihoods over imputed conditional u-values.

```

## (Recall Um0 is imputed array at true values:)
> sum(log(apply(exp((etav+Um0)*Rv)*dnorm(Um0,sd=0.3)/
  (1+exp(etav+Um0))^outer(nv,rep(1,100),"*"),1, mean)))
[1] -255.0079 ### actual logLik est at true params

> etab <- tmpmin3$est[1] + tmpmin3$est[2]*(etav+1)
Umb <- MHblk(Uma[,100],Rv, etab, nv,tmpmin3$est[3], nblk=100)
sum(log(apply(exp((etab+Umb)*Rv)*dnorm(Umb,sd=tmpmin3$est[3])/
  (1+exp(etab+Umb))^outer(nv,rep(1,100),"*"),1, mean)))

```

```
[1] -227.4631 ### logLik est at converged param ests
```

It looks as though we should have cause for concern here: why is the (estimated) log-likelihood so different at the true and final estimated parameter values ? In fact, careful numerically integrated log-likelihoods (not shown here) do show that the quasi-EM steps do work as they are supposed to, increasing or at worst slightly decreasing the true logLik at each EM step: it is the Monte-Carlo estimated log-likelihood values which are at fault here !