

1. Let

$$A = \begin{pmatrix} 1 & 1 & -1 \\ 1 & 2 & -2 \\ -2 & 1 & 1 \end{pmatrix}$$

- (a) Write  $A = LU$  where  $L$  is lower triangular and  $U$  is upper triangular.  
 (b) Use the decomposition of part (a) to solve  $A\mathbf{x} = \mathbf{b}$  where  $\mathbf{b} = (1, 0, 1)^T$  by forward elimination and back substitution.

2. Consider the linear system

$$\begin{aligned} 6x_1 + 2x_2 + 2x_3 &= -2 \\ 2x_1 + \frac{2}{3}x_2 + \frac{1}{3}x_3 &= 1 \\ x_1 + 2x_2 - x_3 &= 0 \end{aligned}$$

(a) Verify that its solution is

$$x_1 = 2.6 \quad x_2 = -3.8 \quad x_3 = -5.0$$

- (b) Using four digit floating-point decimal arithmetic with rounding, solve the system by Gaussian elimination without pivoting.  
 (c) Repeat part (b) using partial pivoting. In performing the arithmetic operations, remember to round to four significant digits after each operation, just as would be done on a computer. If you are careful you should see a significant difference.

3. Let

$$A = \begin{bmatrix} 2.25 & -3.0 & 4.5 \\ -3.0 & 5.0 & -10.0 \\ 4.5 & -10.0 & 34.0 \end{bmatrix}, \quad B = \begin{bmatrix} 15 & -18 & 15 & -3 \\ -18 & 24 & -18 & 4 \\ 15 & -18 & 18 & -3 \\ -3 & 4 & -3 & 1 \end{bmatrix}.$$

In each case compute the Choleski decomposition. For  $A$  do it by hand and check using MATLAB. For  $B$ , use MATLAB

4. The Hilbert matrix of order  $n$ ,  $H_n$  is defined by

$$(H_n)_{i,j} = \frac{1}{i+j-1}, \quad i = 1, \dots, n, \quad j = 1, \dots, n.$$

$H_n$  is nonsingular. However, as  $n$  increases, the condition number of  $H_n$  increases rapidly.  $H_n$  is a library function in MATLAB, `hilb(n)`. Let  $n = 10$ ,  $\mathbf{x} = \text{ones}(10, 1)$  and  $\mathbf{b} = H_{10}\mathbf{x}$ . Now use the backslash operator to solve the system  $H_n\mathbf{x} = \mathbf{b}$ , obtaining  $\mathbf{x}^*$ . Since we know  $\mathbf{x}$  exactly, we can compute  $\mathbf{e} = \mathbf{x} - \mathbf{x}^*$ , the error, and  $\mathbf{r} = \mathbf{b} - H_{10}\mathbf{x}^*$ , the residual. Compute these quantities and also `cond(H_n)` (a MATLAB function). Show that the two basic principles of solving linear systems by

G.E./P.P. in floating point arithmetic hold. How many correct digits does  $\mathbf{x}^*$  have? Repeat with  $n = 11, 12, \dots$ . Stop when some component of  $\mathbf{x}^*$  has no correct digits.

5. Ex.3, p.302, *Atkinson & Han*.

6. Suppose  $\mathbf{x}$  satisfies  $A\mathbf{x} = \mathbf{b}$  and  $\mathbf{x} + \Delta\mathbf{x}$  satisfies  $(A + \Delta A)(\mathbf{x} + \Delta\mathbf{x}) = \mathbf{b} + \Delta\mathbf{b}$ . Then we have the *condition number inequality*: If  $\rho = \|A^{-1}\| \cdot \|\Delta A\| < 1$

$$\frac{\|\Delta\mathbf{x}\|}{\|\mathbf{x}\|} \leq \frac{\text{cond}(A)}{1 - \rho} \left( \frac{\|\Delta A\|}{\|A\|} + \frac{\|\Delta\mathbf{b}\|}{\|\mathbf{b}\|} \right). \quad (1)$$

Consider the linear system  $A\mathbf{x} = \mathbf{b}$  where

$$A = \begin{pmatrix} .5055 & .6412 & .8035 \\ .1693 & .0162 & .6978 \\ .5280 & .8369 & .4617 \end{pmatrix}, \quad \mathbf{b} = \begin{bmatrix} .4939 \\ .4175 \\ .2923 \end{bmatrix}$$

- Solve  $A\mathbf{x} = \mathbf{b}$  using the backslash operator.
- Use equation (1) to answer the following question: If each entry in  $A$  and  $\mathbf{b}$  might have an error of  $\pm .00005$ , how reliable is  $\mathbf{x}$ ? Use the  $\infty$ -norm.
- Let

$$\Delta A = .0001 * \text{rand}(3) - .00005 * \text{ones}(3), \quad \Delta \mathbf{b} = .0001 * \text{rand}(3, 1) - .00005 * \text{ones}(3, 1).$$

Solve  $(A + \Delta A)(\mathbf{x} + \Delta\mathbf{x}) = \mathbf{b} + \Delta\mathbf{b}$  to get  $\mathbf{x} + \Delta\mathbf{x}$ . Calculate  $\|\Delta\mathbf{x}\|/\|\mathbf{x}\|$ . Is this consistent with (b)? What is the relative change in each  $x_i$ ?

7. Ex.7, p.303, *Atkinson & Han*.

8.

- Let  $A$  be an  $n \times n$  matrix and  $\mathbf{x} \in \mathbf{R}^n$ . How many *flops* does it take to form the product  $A\mathbf{x}$ ?
- Let  $A$  and  $B$  be  $n \times n$  matrices. How many *flops* does it take to form the product  $AB$ ?
- In light of the results of (a) and (b), from the standpoint of efficiency, how should one compute  $A^k\mathbf{x}$  for  $k$  a positive integer  $k > 1$ ?