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On stochastic perturbations of slowly changing dynamical systems

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Abstract

In this paper we consider a diffusion process obtained as a small random perturbation of a dynamical system attracted to a stable equilibrium point. The drift and the diffusive perturbation are assumed to evolve slowly in time. We describe the asymptotics of the time it takes the process to exit a given domain and the limiting distribution of the exit point.

Keywords: large deviations, exit problem, ageing system Mathematics Subject Classification numbers: 60F10, 35J25, 60J60

(Some figures may appear in colour only in the online journal)

1. Introduction and the formulation of the main result

Suppose that the state of a system is determined by a *d*-dimensional vector. Assume that without any perturbations the system is situated at a point $O \in \mathbb{R}^d$, and that it is pushed back to O when perturbed by noise, so that the evolution of the perturbed system is described by the equation

$$dX_t^{x,\varepsilon} = b(X_t^{x,\varepsilon})dt + \varepsilon\sigma(X_t^{x,\varepsilon})dW_t, \ X_1^{x,\varepsilon} = x \in \mathbb{R}^d.$$

Here *b* is a smooth vector field with an asymptotically stable equilibrium *O* and σ is a diffusion matrix. The vector field provides a repairing mechanism that returns the system close to the equilibrium. Observe that the initial position of the process is prescribed at time t = 1 rather than the usual t = 0 for reasons that will become clear later.

Consider a domain D such that $O \in D$ and all the points of $\overline{D} = D \cup \partial D$ are attracted to O for the unperturbed system (with $\sigma \equiv 0$). Let $\tau^{x,\varepsilon}$ be the first time when $X_t^{x,\varepsilon}$ reaches ∂D . This can be viewed as the life span of our system—the system 'dies' when $X_t^{x,\varepsilon}$ exits

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D. The asymptotics of the life span and the location of the point where $X_t^{x,\varepsilon}$ exits *D* can be explicitly expressed through the action functional corresponding to the diffusion process (see [5]). In particular, $\lim_{\varepsilon \downarrow 0} (\varepsilon^2 \ln E \tau^{x,\varepsilon}) = V > 0$, where *V* depends on the domain *D* and on the coefficients. The system also has the following renewal property: for every $x \in D$ and $t(\varepsilon)$, the distribution of $\tau^{x,\varepsilon} - t(\varepsilon)$ conditioned on survival till time $t(\varepsilon)$ is close to the distribution of $\tau^{x,\varepsilon} - t(\varepsilon)$ by conditioning on survival till time $t(\varepsilon)$ and dividing by $E\tau^{x,\varepsilon}$ converge in distribution to an exponential random variable with parameter one.) This property can be interpreted as the lack of ageing in the system.

In certain applications, it is natural to allow the system to age. For instance, the repairing capabilities may degrade with time. Since in the absence of ageing the life span of the system is of order $\exp(\text{const}/\varepsilon^2)$, it is natural to assume that the degradation occurs slowly, i.e. also at exponential time scales. We allow for two ageing mechanisms—one due to the slow evolution of coefficients in time and the other due to the dependence on a slowly changing random process. This leads us to consider the following stochastic process.

Let ξ_{λ} , $\lambda \ge 0$, be a continuous time Markov chain on the state space $S = \{1, ..., s\}$. We choose the right-continuous modification of ξ_{λ} . Consider the diffusion process

$$dX_t^{x,\varepsilon} = b(X_t^{x,\varepsilon},\varepsilon^2 \ln t, \xi_{\varepsilon^2 \ln t})dt + \varepsilon \sigma(X_t^{x,\varepsilon},\varepsilon^2 \ln t, \xi_{\varepsilon^2 \ln t})dW_t, X_1^{x,\varepsilon} = x \in \mathbb{R}^d$$

Here $\varepsilon > 0$ is a small parameter, W_t is a Wiener process in \mathbb{R}^d , independent of ξ_{λ} . The coefficients $b(\cdot, \cdot, k)$, $1 \le k \le s$, and $\sigma(\cdot, \cdot, k)$ are assumed to be bounded, continuous, and Lipschitz continuous in the spatial variable (with the Lipschitz constant that doesn't depend on λ). The diffusion matrix $a(x, \lambda, k) = (a_{ij}(x, \lambda, k)) = \sigma(x, \lambda, k)\sigma^*(x, \lambda, k)$ is assumed to be uniformly positive definite. This condition is needed to make sure that the process exits a bounded domain in finite time and for calculating the action functional (which is relevant to the questions discussed below). The initial position of the process is prescribed at time t = 1 rather than the usual t = 0 in order to avoid the large negative values of the logarithm inside the coefficients.

Let $D \subset \mathbb{R}^d$ be a bounded domain with smooth boundary. We assume that there is a point $O \in D$ (the equilibrium) and r, c > 0 such that

$$(b(x, \lambda, k), x - O) \leq -c|x - O|^2$$

whenever *x* is in the *r*-neighborhood of *O*, $\lambda \ge 0$, and $k \in S$, and that

 $(b(x, \lambda, k), n(x)) \leq -c, x \in \partial D,$

where n(x) is the outward unit normal vector. Moreover, we assume that for each λ every solution of the equation $x'(t) = b(x(t), \lambda, k)$ that starts in \overline{D} enters the *r*-neighborhood of *O* in time that is shorter than c^{-1} .

Recall that $\tau^{x,\varepsilon}$ is the first time when $X_t^{x,\varepsilon}$ reaches ∂D . We'll be interested in the asymptotics of $\tau^{x,\varepsilon}$ and the limiting distribution of $X_{\tau^{x,\varepsilon}}^{x,\varepsilon}$. First, consider the following family of auxiliary problems. For each $\lambda \ge 0$ and $k \in S$, let $Y_t^{x,\varepsilon,\lambda,k}$ be the solution of

$$\mathrm{d}Y_t^{x,\varepsilon,\lambda,k} = b(Y_t^{x,\varepsilon,\lambda,k},\lambda,k)\mathrm{d}t + \varepsilon\sigma(Y_t^{x,\varepsilon,\lambda,k},\lambda,k)\mathrm{d}W_t, \ Y_0^{x,\varepsilon,\lambda,k} = x \in \mathbb{R}^d.$$

This is a diffusion process with time-independent coefficients, and the usual action functional can be defined:



Figure 1. A trajectory of the process Z_{λ} .

$$S_{0,T}^{\lambda,k}(\varphi) = \frac{1}{2} \int_0^T \sum_{i,j=1}^d a^{ij}(\varphi_t, \lambda, k) (\dot{\varphi}_t^i - b_i(\varphi_t, \lambda, k)) (\dot{\varphi}_t^j - b_j(\varphi_t, \lambda, k)) dt, \ T \ge 0,$$

for absolutely continuous $\varphi \in C([0, T], \mathbb{R}^d)$, while $S_{0,T}^{\lambda,k}(\varphi) = +\infty$ for φ that are not absolutely continuous. Here a^{ij} are the elements of the inverse matrix, that is $a^{ij} = (a^{-1})_{ij}$. The quasipotential is defined as

$$V^{\lambda,k}(x) = \inf_{T,\varphi} \{ S^{\lambda,k}_{0,T}(\varphi) : \varphi \in C([0,T], \mathbb{R}^d), \varphi(0) = O, \varphi(T) = x \}, \ x \in \mathbb{R}^d.$$

Let

$$M^{\lambda,k} = \inf_{x \in \partial D} V^{\lambda,k}(x).$$
⁽¹⁾

Obviously, this is a continuous function of λ with values in $(0, \infty)$.

Assumption 1. We assume that the equation $M^{\lambda,k} = \lambda$ has a unique solution for each $k \in S$. The solution will be denoted by m^k .

Remark. The case when the equation has finitely many solutions could also be considered without major additional difficulties, but would require more complicated notation.

A trivial example where assumption 1 holds is obtained by taking the coefficients *b* and σ that do not depend on λ , since $M^{\lambda,k}$ is a positive constant for each *k* in this case. Similarly, the solution exists and is unique if $|\frac{d}{d\lambda}M^{\lambda,k}| < c < 1$ for all λ and *k*.

Assumption 2. We assume that for each $k \in S$ the infimum in $\inf_{x \in \partial D} V^{m^k,k}(x)$ is achieved in a single point of the boundary.

The point for which the infimum is achieved will be denoted by x^k . Let $I_k = \{k\} \times [0, m^k)$, and $G = \bigcup_{k=1}^{s} I_k$. Thus G can be viewed as a union of k disjoint segments of lengths $m^1, ..., m^s$. It is a subset of the larger space $\widehat{G} = S \times [0, \infty)$ (see figure 1). Define the following Markov process on \widehat{G} :

$$Z_{\!\lambda}=(\xi_{\lambda},\lambda),\ \lambda \!\geqslant\! 0,$$

and let $\theta = \inf \{\lambda : Z_{\lambda} \notin G\}$ be the first time when the process leaves *G*. Now we can formulate the main result.

Theorem 1.1. Under the above assumptions, for each $x \in D$ the distribution of $\varepsilon^2 \ln \tau^{x,\varepsilon}$ converges, as $\varepsilon \downarrow 0$, to the distribution of θ . The distribution of $X^{x,\varepsilon}_{\tau^{x,\varepsilon}}$ converges to the distribution of $x^{\xi_{\theta}}$.

Fix a number $\Lambda > \max(m^1, ..., m^s)$ and a right-continuous function $z_{\lambda}, \lambda \in [0, \Lambda]$, taking values in *S*, with a finite number of jumps. Together with z_{λ} , we can consider the function (z_{λ}, λ) with values in $\widehat{G} = S \times [0, \infty)$. This can be viewed as a trajectory of the process Z_{λ} . Given such a function *z*, we can define the process

$$dX_t^{x,\varepsilon,z} = b(X_t^{x,\varepsilon,z},\varepsilon^2 \ln t, z_{\varepsilon^2 \ln t})dt + \varepsilon \sigma(X_t^{x,\varepsilon,z},\varepsilon^2 \ln t, z_{\varepsilon^2 \ln t})dW_t, X_1^{x,\varepsilon,z} = x \in \mathbb{R}^d.$$
(2)

This is different from the process $X^{x,\varepsilon}$ in that now the trajectory of the underlying Markov process is considered fixed. Let $\tau^{x,\varepsilon,z}$ be the first time when $X_t^{x,\varepsilon,z}$ reaches ∂D . Let θ^z be the first time when (z_λ, λ) leaves G, which corresponds to the stopping time θ for the process Z. Observe that the probability of ξ_λ experiencing a jump at any of the points $m_1, ..., m_s$ is zero and that the number of jumps on $[0, \Lambda]$ is finite with probability one. Therefore, by conditioning on a trajectory of the process ξ_λ , we see that in order to prove theorem 1.1 it suffices to prove the following lemma.

Lemma 1.2. Assume that the function z_{λ} is right-continuous with finitely many jumps at points $\lambda_1, ..., \lambda_k$ and that none of the jumps happens at any of the points $m_1, ..., m_s$. Then for each $x \in D$ the distribution of $\varepsilon^2 \ln \tau^{x,\varepsilon,z}$ converges, as $\varepsilon \downarrow 0$, to θ^z . The distribution of $X_{\tau^{x,\varepsilon,z}}^{x,\varepsilon,z}$ converges to $x^{z_{\theta^{\varepsilon}}}$.

In the next section we gather some facts about processes with time-dependent coefficients that will be needed for the proof of lemma 1.2. The lemma itself will be proved in section 3. Finally, in section 4 we briefly discuss a situation in which the vector field *b* is equal to zero near ∂D .

2. On diffusion processes with time-dependent coefficients

Before we proceed with the proof of lemma 1.2, let us briefly discuss diffusion processes whose coefficients are time-dependent, but are close to functions that do not depend on time. For T > 0 and $\varphi, \psi \in C([0, T], \mathbb{R}^d)$, we define $\rho_T(\varphi, \psi) = \sup_{t \in [0, T]} |\varphi(t) - \psi(t)|$.

Let $\tilde{a}^{\varepsilon}(t, x)$, $\bar{a}(x)$, be uniformly positive definite symmetric $d \times d$ matrices whose elements $\tilde{a}_{ij}^{\varepsilon}$, \bar{a}_{ij} , are continuous in (t, x) (x in case of \bar{a}) and Lipschitz continuous in x with a Lipschitz constant L. Assume that there are positive k and K such that

$$\begin{aligned} k|\xi|^2 &\leqslant \sum_{i,j=1}^d \tilde{a}_{ij}^\varepsilon(t,x)\xi_i\xi_j \leqslant K|\xi|^2, \ t \ge 0, x \in \mathbb{R}^d, \xi \in \mathbb{R}^d \\ k|\xi|^2 &\leqslant \sum_{i,j=1}^d \bar{a}_{ij}^\varepsilon(x)\xi_i\xi_j \leqslant K|\xi|^2, \ x \in \mathbb{R}^d, \xi \in \mathbb{R}^d. \end{aligned}$$

Let $\tilde{\sigma}^{\varepsilon}$, $\bar{\sigma}$ be a square matrices such that $\tilde{a}^{\varepsilon} = \tilde{\sigma}^{\varepsilon} (\tilde{\sigma}^{\varepsilon})^*$, $\bar{a} = \bar{\sigma}(\bar{\sigma})^*$. We choose $\tilde{\sigma}^{\varepsilon}$, $\bar{\sigma}$ in such a way that $\tilde{\sigma}^{\varepsilon}_{ij}$ are continuous in (t, x), while $\tilde{\sigma}^{\varepsilon}_{ij}$ and $\bar{\sigma}_{ij}$ are Lipschitz continuous in x. Let $\tilde{b}^{\varepsilon}(t, x)$, $\bar{b}(x)$, be continuous vector fields, Lipschitz continuous in x with Lipschitz constant L.

Let
$$\widetilde{X}_{t}^{x,\varepsilon}$$
 and $\overline{X}_{t}^{x,\varepsilon}$ satisfy $\widetilde{X}_{0}^{x,\varepsilon} = \overline{X}_{0}^{x,\varepsilon} = x$ and
 $d\widetilde{X}_{t}^{x,\varepsilon} = \widetilde{b}(t,\widetilde{X}_{t}^{x,\varepsilon})dt + \varepsilon \widetilde{\sigma}^{\varepsilon}(t,\widetilde{X}_{t}^{x,\varepsilon})dW_{t}, \ d\overline{X}_{t}^{x,\varepsilon} = \overline{b}(\overline{X}_{t}^{x,\varepsilon})dt + \varepsilon \overline{\sigma}(\overline{X}_{t}^{x,\varepsilon})dW_{t}.$

We will assume that the coefficients of the process $\widetilde{X}_t^{x,\varepsilon}$ are close to those of $\overline{X}_t^{x,\varepsilon}$. Namely, let us assume that

$$\sup_{(t,x)\in\mathbb{R}^+\times\mathbb{R}^d}\left|\widetilde{b}_i^{\varepsilon}(t,x)-\overline{b}_i(x)\right|\leqslant\varkappa, \quad \sup_{(t,x)\in\mathbb{R}^+\times\mathbb{R}^d}\left|\widetilde{a}_{ij}^{\varepsilon}(t,x)-\overline{a}_{ij}(x)\right|\leqslant\varkappa,$$

where \varkappa is small.

The reason to introduce these processes is that we would like to study the behavior of the process $X_t^{x,\varepsilon,z}$ given by (2) on such time intervals where the coefficients do not change much with time. Thus it is convenient to consider a generic process whose coefficients are close to functions that don't depend on time. Let $\overline{S}_{0,T}$ be the action functional for the processes $\overline{X}_t^{x,\varepsilon}$, that is

$$\overline{S}_{0,T}(\varphi) = \frac{1}{2} \int_0^T \sum_{i,j=1}^d \overline{a}^{ij}(\varphi_t) (\dot{\varphi}_t^i - \overline{b}_i(\varphi_t)) (\dot{\varphi}_t^j - \overline{b}_j(\varphi_t)) dt, \ T \ge 0,$$

for absolutely continuous $\varphi \in C([0, T], \mathbb{R}^d)$, while $\overline{S}_{0,T}(\varphi) = +\infty$ for φ that are not absolutely continuous. The next two lemmas show that \overline{S} serves a purpose similar to the action functional for the processes $\widetilde{X}_t^{x,\varepsilon}$, even though the diffusion coefficients for the process are time-dependent.

Lemma 2.1. Suppose that \tilde{a}^{ε} , \bar{a} , \tilde{b}^{ε} , and \bar{b} are as above, and positive constants k, K, and L are fixed. For every δ , γ and C there exist $\varkappa > 0$ and $\varepsilon_0 > 0$ such that

$$\mathbb{P}(\rho_T(\widetilde{X}^{\lambda,\varepsilon},\varphi) < \delta) \ge \exp(-\varepsilon^{-2}[\overline{S}_{0,T}(\varphi) + \gamma])$$

for $\varepsilon < \varepsilon_0$ and T > 0, $\varphi \in C([0, T], \mathbb{R}^d)$ such that $\varphi(0) = x$ and $T + \overline{S}_{0,T}(\varphi) < C$.

Lemma 2.2. Suppose that \tilde{a}^{ε} , \bar{a} , \tilde{b}^{ε} , and \bar{b} are as above, and positive constants k, K, and L are fixed. For $x \in \mathbb{R}^d$, T > 0, and $s \ge 0$, put

$$\Phi(s) = \{ \varphi \in C([0, T], \mathbb{R}^d), \varphi(0) = x, \overline{S}_{0, T}(\varphi) \leq s \}.$$

For every T > 0, $\delta > 0$, $\gamma > 0$, and $s_0 > 0$, there exist $\varkappa > 0$ and $\varepsilon_0 > 0$ such that for $x \in \mathbb{R}^d$, $0 < \varepsilon \leq \varepsilon_0$ and $s \leq s_0$, we have

$$\mathbb{P}(\rho_T(\widetilde{X}^{x,\varepsilon}, \Phi(s)) \ge \delta) \le \exp(-\varepsilon^{-2}[s-\gamma]).$$

Note that the choice of \varkappa and ε_0 in the above lemmas depends on the coefficients only through *k*, *K* and *L*.

A sketch of the proof of these lemmas is provided in [2], so we'll not replicate it here. For the most part, it is similar to the proof of the fact that $\overline{S}_{0,T}(\varphi)$ serves as an action functional for the process $\overline{X}_{t}^{x,\varepsilon}$ (see [1, 4]).

We next state a corollary of the above two lemmas that will be used in the paper. Define $D^{\eta} = \{x \in D : \operatorname{dist}(x, \partial D) \ge \eta\}$ and $T^{\varepsilon}(\lambda) = \exp(\lambda/\varepsilon^2)$. Let

$$v = \inf_{T,\varphi} \{ \overline{S}_{0,T}(\varphi) : \varphi \in C([0,T], \overline{D}), \varphi(0) = O, \varphi(T) \in \partial D \}.$$

Assume that

$$(\overline{b}^{\varepsilon}(t,x), x-O), \ (\overline{b}(x), x-O) \leqslant -c|x-O|^2$$

whenever x is in the r-neighborhood of O and that

$$(\overline{b}(x), n(x)) \leq -c, x \in \partial D.$$

Moreover, we assume that every solution of the equation $x'(t) = \overline{b}(x(t))$ that starts in \overline{D} enters the *r*-neighborhood of *O* in time that is shorter than c^{-1} .

For $x \in D$, let $\tilde{\tau}^{x,\varepsilon}$ be the first time when $\widetilde{X}_t^{x,\varepsilon}$ reaches the boundary of *D*. Thus $\widetilde{X}_{\tilde{\tau}^{x,\varepsilon}}^{x,\varepsilon}$ is the location of the first exit. Let

$$\mathcal{A} = \{ x \in \partial D : v = \inf_{T,\varphi} \{ \overline{S}_{0,T}(\varphi) : \varphi \in C([0,T],\overline{D}), \varphi(0) = O, \varphi(T) = x \} \}$$

Lemma 2.3. Suppose that \tilde{a}^{ε} , \bar{a} , \tilde{b}^{ε} , and \bar{b} are as above. For each δ , $\eta > 0$ there are $\varkappa > 0$ and a function $\rho(\varepsilon)$ (that depend on \tilde{a}^{ε} , \bar{a} , \tilde{b}^{ε} , and \bar{b} through k, K, L, c, and r) such that $\lim_{\varepsilon \mid 0} \rho(\varepsilon) = 0$ and

$$\begin{split} & (A) \ \mathsf{P}(\tilde{\tau}^{x,\varepsilon} \leqslant T^{\varepsilon}(v+\delta)) \geqslant 1 - \rho(\varepsilon) \ for \ x \in D, \\ & (B) \ \mathsf{P}(\tilde{\tau}^{x,\varepsilon} \geqslant T^{\varepsilon}(v-\delta)) \geqslant 1 - \rho(\varepsilon) \ for \ x \in D^{\eta}, \\ & (C) \ \mathsf{P}(\operatorname{dist}(\widetilde{X}^{x,\varepsilon}_{\tilde{\tau}^{x,\varepsilon}},\mathcal{A}) \leqslant \eta) \geqslant 1 - \rho(\varepsilon) \ for \ x \in D^{\eta}. \\ & (D) \ \mathsf{P}(|\widetilde{X}^{x,\varepsilon}_t - O| < \eta) \geqslant 1 - \rho(\varepsilon) \ for \ x \in D^{\eta}, t \in [T^{\varepsilon}(\delta), T^{\varepsilon}(v-\delta)], \end{split}$$

provided that

$$\sup_{(t,x)\in\mathbb{R}^+\times D} |\widetilde{b}_i^{\varepsilon}(t,x) - \overline{b}_i(x)| \leqslant \varkappa, \quad \sup_{(t,x)\in\mathbb{R}^+\times D} |\widetilde{a}_{ij}^{\varepsilon}(t,x) - \overline{a}_{ij}(x)| \leqslant \varkappa. \tag{3}$$

This lemma can be easily proved using a modification of theorems 4.2 and 4.3 from chapter 4 of [5] if we substitute our lemmas 2.1 and 2.2 for the corresponding results concerning the case of time-independent coefficients.

An easy corollary of this lemma is that at an exponential time the process either can be found in a small neighborhood of *O* or has earlier crossed the boundary of the domain.

Lemma 2.4. Suppose that \tilde{a}^{ε} , \bar{a} , \tilde{b}^{ε} , and \bar{b} are as above. For each δ , $\eta > 0$ such that $O \in D^{\eta}$, there is a function $\rho(\varepsilon)$ (that depends on \tilde{a}^{ε} , \bar{a} , \tilde{b}^{ε} , and \bar{b} through k, K, L, c, and r) such that $\lim_{\varepsilon \downarrow 0} \rho(\varepsilon) = 0$ and

$$\mathbb{P}(\widetilde{X}_t^{x,\varepsilon} \in D^{\eta} \text{ or } \widetilde{\tau}^{x,\varepsilon} \leq t) \geq 1 - \rho(\varepsilon) \text{ for } x \in D, t \in [T^{\varepsilon}(\delta), \infty).$$

Proof. Let $\eta_1 > 0$ be sufficiently small so that there is a domain \widetilde{D} with smooth boundary such that $\widetilde{D}^{\eta_1} = D$. Note that if η_1 is sufficiently small, then lemma 2.3 is applicable to the domain \widetilde{D} . If the process does not reach ∂D by the time $t - T^{\varepsilon}(\delta)$, then we can apply part (D) of lemma 2.3 (with sufficiently small δ) to the domain \widetilde{D} and the process starting at $X_{t-T^{\varepsilon}(\delta)}^{x,\varepsilon}$, and the result follows from the Markov property.

3. Proof of the main result

In this section we prove lemma 1.2, which, as we discussed above, implies theorem 1.1. Let us first assume that $z_{\lambda} \equiv k$ (the general case will be considered below). An example of the graph of $M^{\lambda,k}$ is shown in figure 2.



Figure 2. Graph of $M^{\lambda,k}$.

Let $u^{\varepsilon,k}(t,x) = P(\tau^{x,\varepsilon,k} \leq t)$. Take an arbitrary $\eta > 0$ such that $O \in D^{\eta}$. We claim that $\lim_{\varepsilon \downarrow 0} u^{\varepsilon,k}(T^{\varepsilon}(\lambda), x) = 0$ for each $\lambda < m^k$ uniformly in $x \in D^{\eta}$. Assume the contrary. Choose $\delta > 0$ and $0 \leq \lambda_1 < \lambda_2 < m^k$ such that

$$\limsup_{\varepsilon \downarrow 0} \sup_{x \in D^{\eta}} u^{\varepsilon,k}(T^{\varepsilon}(\lambda_{1}), x) < \limsup_{\varepsilon \downarrow 0} \sup_{x \in D^{\eta}} u^{\varepsilon,k}(T^{\varepsilon}(\lambda_{2}), x),$$
(4)

while

$$\lambda_2 < M^{\lambda_1,k} - \delta. \tag{5}$$

Let

$$\overline{a}(x) = a(x, \lambda_{l}, k), \ b(x) = b(x, \lambda_{l}, k), \tag{6}$$

$$\widetilde{a}(t,x) = a(x,\varepsilon^2 \ln(t) - T^{\varepsilon}(\lambda_1), k), \ \widetilde{b}(t,x) = b(x,\varepsilon^2 \ln(t) - T^{\varepsilon}(\lambda_1), k),$$
(7)

 $\widetilde{X}_{t}^{x,\varepsilon}$ be the corresponding process, and $\widetilde{\tau}^{x,\varepsilon}$ be the corresponding stopping time. Choose $\varkappa > 0$ such that the conclusion of lemma 2.3 holds. Due to the continuity assumptions on *a* and *b*, estimate (3) holds if we restrict *t* to the interval $[0, T^{\varepsilon}(\lambda_2) - T^{\varepsilon}(\lambda_1)]$ and choose $\lambda_2 - \lambda_1$ sufficiently small. Note that we can achieve (4), (5) even with the requirement that $\lambda_2 - \lambda_1$ is smaller than any prescribed positive number.

By the definition of $u^{\varepsilon,k}$ and the Markov property of the process,

$$u^{\varepsilon,k}(T^{\varepsilon}(\lambda_2), x) = u^{\varepsilon,k}(T^{\varepsilon}(\lambda_1), x) + \mathbb{P}(\tau^{x,\varepsilon,k} > T^{\varepsilon}(\lambda_1), \tilde{\tau}^{X^{x,\varepsilon,k}_{T^{\varepsilon}(\lambda_1)}, \varepsilon} \leq T^{\varepsilon}(\lambda_2) - T^{\varepsilon}(\lambda_1))$$
(8)

Observe that $T^{\varepsilon}(\lambda_2) - T^{\varepsilon}(\lambda_1) < T^{\varepsilon}(M^{\lambda_1,k} - \delta)$. Therefore, by part (B) of lemmas 2.3 and 2.4, the second term in the right hand side of (8) tends to zero as $\varepsilon \downarrow 0$ uniformly in $x \in D^{\eta}$. This, however, is a contradiction with (4), so we do have $\lim_{\varepsilon \downarrow 0} u^{\varepsilon,k}(T^{\varepsilon}(\lambda), x) = 0$ for each $\lambda < m^k$ uniformly in $x \in D^{\eta}$.

Next, we claim that $\lim_{\varepsilon \downarrow 0} u^{\varepsilon,k}(T^{\varepsilon}(\lambda), x) = 1$ for each $\lambda > m^k$ uniformly in $x \in D^{\eta}$. Since m^k is the unique solution of the equation $M^{\lambda,k} = \lambda$, while $M^{\lambda,k}$ is bounded (as the coefficients are bounded), we have $M^{\lambda,k} < \lambda$ for $\lambda > m^k$. Choose $\delta > 0$ and $m^k < \lambda_1 < \lambda_2$ such that

$$M^{\lambda_{\mathrm{l}},k} + \delta < \lambda_{\mathrm{l}}.$$

We can achieve this while choosing λ_2 arbitrarily close to m^k . With \overline{a} , \overline{b} , \widetilde{a} , \widetilde{b} defined by (6) and (7), choose $\varkappa > 0$ such that the conclusion of lemma 2.3 holds. Due to the continuity assumptions on *a* and *b*, estimate (3) holds if we restrict *t* to the interval $[0, T^{\varepsilon}(\lambda_2) - T^{\varepsilon}(\lambda_1)]$ and choose λ_2 sufficiently close to λ_1 . With these new λ_1 and λ_2 , we again employ (8), writing it as

$$u^{\varepsilon,k}(T^{\varepsilon}(\lambda_2),x) = u^{\varepsilon,k}(T^{\varepsilon}(\lambda_1),x) + \mathbb{P}(\tilde{\tau}^{X_{T^{\varepsilon}(\lambda_1)}^{\lambda_{\varepsilon},k},\varepsilon} \leq T^{\varepsilon}(\lambda_2) - T^{\varepsilon}(\lambda_1) | \tau^{x,\varepsilon,k} > T^{\varepsilon}(\lambda_1))(1 - u^{\varepsilon,k}(T^{\varepsilon}(\lambda_1),x)).$$

The conditional probability in the right hand side tends to one uniformly in $x \in D^{\eta}$ as $\varepsilon \downarrow 0$ by part (A) of lemma 2.3 since $T^{\varepsilon}(\lambda_2) - T^{\varepsilon}(\lambda_1) > T^{\varepsilon}(\lambda_1) > T^{\varepsilon}(M^{\lambda_1,k} + \delta)$ for all sufficiently small ε . Therefore, $\lim_{\varepsilon \downarrow 0} \inf_{x \in D^{\eta}} u^{\varepsilon,k}(T^{\varepsilon}(\lambda_2), x) = 1$. Since λ_2 can be chosen to be arbitrarily close to m^k and since $u^{\varepsilon,k}(t, x)$ increases with t, we conclude that $\lim_{\varepsilon \downarrow 0} u^{\varepsilon,k}(T^{\varepsilon}(\lambda), x) = 1$ uniformly in $x \in D^{\eta}$.

Now let us prove that the distribution of $X_{\tau^{k,\varepsilon,k}}^{x,\varepsilon,k}$ converges to x^k . From our assumptions on the continuity of the coefficients it follows that for each λ that is sufficiently close to m^k the infimum $\inf_{x \in \partial D} V^{\lambda,k}(x)$ is achieved in a single point of the boundary that will be denoted by $x^k(\lambda)$. Moreover, $x^k(\lambda)$ is continuous at m^k . Given $\eta > 0$, choose $\lambda_1 < m^k$ such that dist $(x^k(\lambda), x^k) < \eta$ for $\lambda \in [\lambda_1, m^k]$. With $\overline{a}, \overline{b}, \widetilde{a}, \widetilde{b}$ defined by (6) and (7), choose $\lambda_1 < m^k$ and $\lambda_2 > m_k$ in such a way that (3) holds if we restrict *t* to the interval $[0, T^{\varepsilon}(\lambda_2) - T^{\varepsilon}(\lambda_1)]$, where \varkappa is sufficiently small for the conclusion of lemma 2.3 to hold (this may require modifying the previously selected λ_1 by making it larger).

As we showed above, $X_t^{x,\varepsilon,k}$ does not exit D prior to time $T^{\varepsilon}(\lambda_1)$ with probability that tends to one uniformly in $x \in D^{\eta}$. By lemma 2.4, $X_{T^{\varepsilon}(\lambda_1)}^{x,\varepsilon,k}$ belongs to D^{η} with probability that tends to one. Therefore, by the above construction and part (C) of lemma 2.3, the process $X_t^{x,\varepsilon,k}$ reaches the boundary of D for the first time in an η -neighborhood of $x^k(\lambda_1)$ with probability that tends to one. Since η was arbitrary, this proves that the distribution of $X_{x,\varepsilon,k}^{x,\varepsilon,k}$ converges to x^k .

It remains now to get rid of the assumption that $z_{\lambda} \equiv k$. Assume now that z_{λ} has finitely many jumps at points $\lambda_1, ..., \lambda_k$ and that none of the jumps happens at any of the points $m_1, ..., m_s$. Suppose that $\theta^z \ge \lambda_1$. As we showed above, $P(\tau^{x,\varepsilon,z} > T^{\varepsilon}(\lambda_1)) \rightarrow 1$ as $\varepsilon \downarrow 0$. By lemma 2.4, $X_{T^{\varepsilon}(\lambda_1)}^{x,\varepsilon,z}$ belongs to D^{η} , with sufficiently small η , with probability that tends to one. Using the Markov property of the process, we can now replace the values of z on the interval $[0, \lambda_1)$ by z_{λ_2} , i.e. z now has one fewer jump. At the same time, the coefficients of the process need to be set to be equal to zero on the interval $[0, T^{\varepsilon}(\lambda_1)]$. The earlier arguments still apply in this situation. Continuing by induction on the number of the jump, we obtain the desired result.

4. The case of no repairing mechanism near the boundary

Let us modify some of the assumptions on the coefficients b and σ . Namely, instead of assuming that b is Lipschitz continuous, we assume that it can be continued from \overline{D} to the entire space as a Lipschitz continuous function, yet is equal to zero outside \overline{D} . Inside \overline{D} , the drift is assumed to have the same properties as before. For simplicity, let us assume that σ is an identity matrix and that b does not depend on ξ . Thus the process under consideration is

$$\mathrm{d} X^{x,\varepsilon}_t = b(X^{x,\varepsilon}_t,\varepsilon^2 \ln t) \mathrm{d} t + \varepsilon \mathrm{d} W_t, \ X^{x,\varepsilon}_1 = x \in \mathbb{R}^d.$$

Let D_1 be a domain with smooth boundary such that $\overline{D} \subset D_1$. Let $\tau_1^{x,\varepsilon}$ be the first time when $X_t^{x,\varepsilon}$ reaches ∂D_1 . We'll be interested in the limiting distribution of $X_{x,\varepsilon}^{x,\varepsilon}$. The fact that b = 0 in $D_1 \setminus \overline{D}$ can be viewed as the absence of a repair mechanism in a part of the domain.

As follows from theorem 1.1, there is $x^* \in \partial D$ such that $\lim_{\varepsilon \perp 0} X_{\tau^{x,\varepsilon}}^{x,\varepsilon} = x^*$ in distribution for each $x \in D$. Note that x^* is now non-random. In [3] we considered the behavior of the process in $\mathbb{R}^d \setminus D$ obtained from $X_t^{x,\varepsilon}$ by running the clock only when $X_t^{x,\varepsilon}$ is outside D. (The ageing mechanism was not considered there, which is not a problem since the process in $\mathbb{R}^d \setminus D$ is relevant now only at one time scale associated with the exit of $X_t^{x,\varepsilon}$ from D). An adaptation of the results from [3] gives us the following fact: for $\gamma \subset \partial D_1$ and $x \in D_1 \setminus D$,

$$\lim_{\varepsilon \downarrow 0} \mathsf{P}(X^{x,\varepsilon}_{\tau_1^{x,\varepsilon}} \in \gamma) = u^{\gamma}(x),$$

where u^{γ} is the unique solution of the following non-standard boundary problem

$$\Delta u^{\gamma}(x) = 0, \ x \in D_1 \setminus \overline{D},$$
$$u^{\gamma}(x) = \begin{cases} 1, & x \in \gamma, \\ 0, & x \in \partial D_1 \setminus \gamma, \end{cases}$$

 $u^{\gamma}(x)$ is constant on ∂D ,

$$\langle \nabla u^{\gamma}(x^*), n(x^*) \rangle = 0,$$

where n(x) is the normal to ∂D at x. For $x \in D$, we have $\lim_{\varepsilon \downarrow 0} P(X_{\tau_1}^{x,\varepsilon} \in \gamma) = u^{\gamma}(x^*)$.

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