

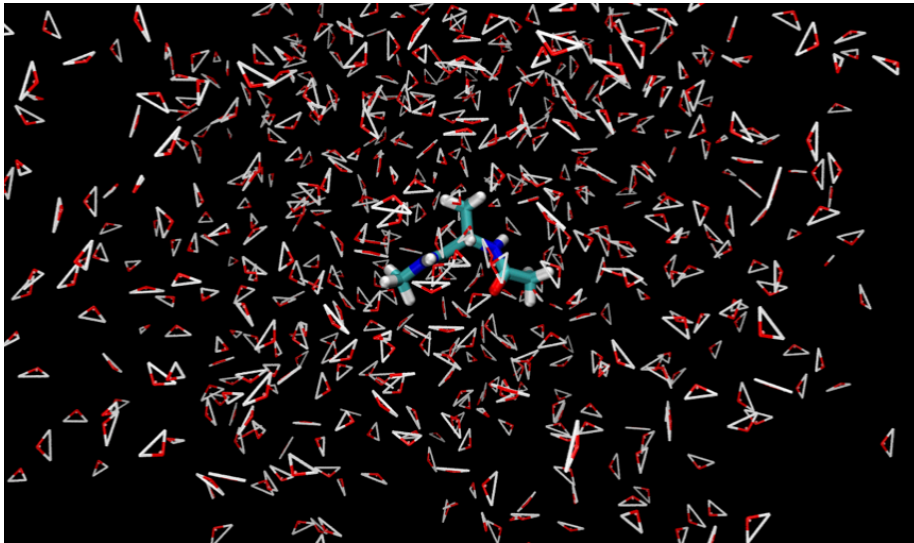
Machine learning methods for the study of rare events in stochastic systems

REU: Modern topics
in pure and applied mathematics

What are rare events?

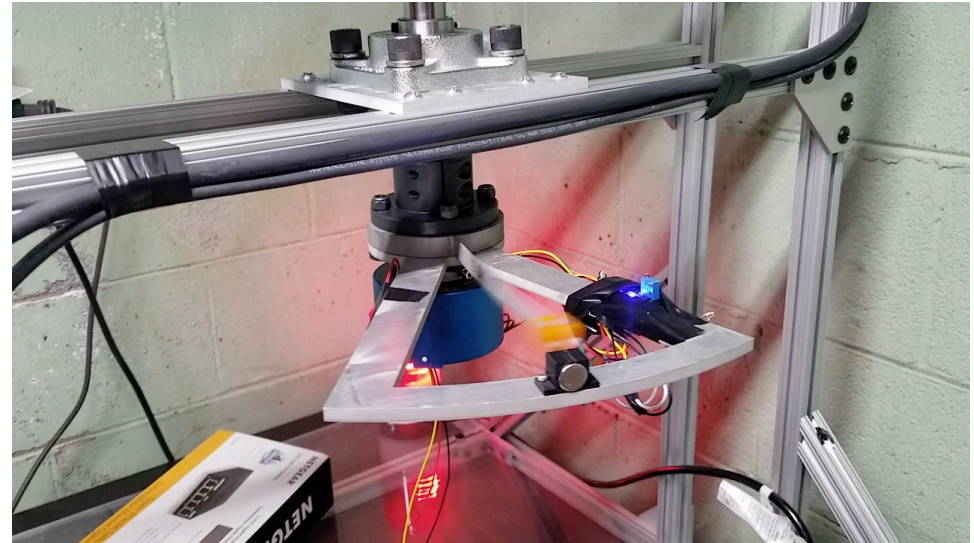
Rare events are those that occur rarely on the timescale of the system

Dynamics of
an alanine-dipeptide molecule
pushed around by water molecules



<https://ambermd.org/tutorials/basic/tutorial0/index.php>

A noise-driven transition from
the high- to the low-amplitude attractor
in an electromechanical
nonlinear oscillator



Lautaro Cilenti, Clark Fellow, Dept. of Mech. Eng. UMD

Stochastic differential equations

Deterministic forcing Stochastic forcing

$$dX_t = \boxed{b(X_t)dt} + \boxed{\sqrt{\epsilon}\sigma(X_t)dW_t}, \quad X_t \in \mathcal{M} \subset \mathbb{R}^d$$

A smooth vector field A small parameter The standard Brownian motion

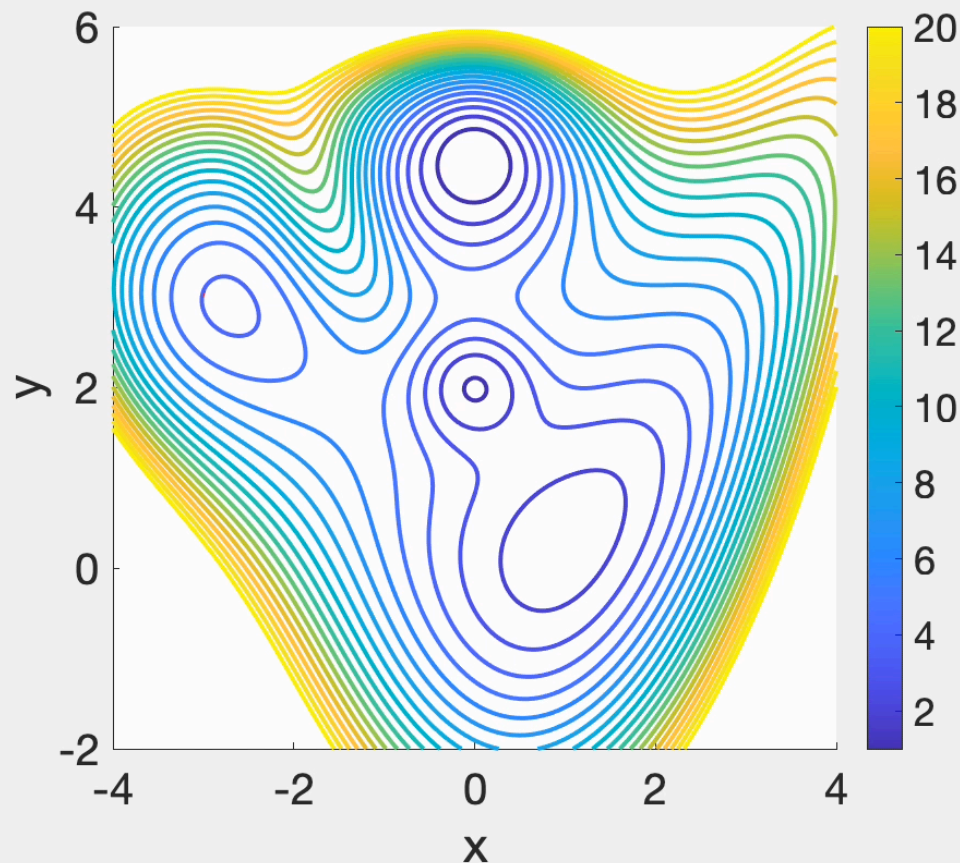
A smooth matrix function

The diagram illustrates the components of a Stochastic Differential Equation (SDE). The equation is $dX_t = b(X_t)dt + \sqrt{\epsilon}\sigma(X_t)dW_t$, where $X_t \in \mathcal{M} \subset \mathbb{R}^d$. The first term, $b(X_t)dt$, is labeled 'Deterministic forcing' and is described as 'A smooth vector field'. The second term, $\sqrt{\epsilon}\sigma(X_t)dW_t$, is labeled 'Stochastic forcing' and is described as 'The standard Brownian motion'. The parameter ϵ is labeled 'A small parameter'. The function $\sigma(X_t)$ is labeled 'A smooth matrix function'. Arrows point from these labels to their respective parts in the equation. The terms $b(X_t)dt$ and $\sqrt{\epsilon}\sigma(X_t)dW_t$ are enclosed in blue rounded rectangles.

The overdamped Langevin dynamics

A simple and important model

$$dX_t = -\nabla V(X_t)dt + \sqrt{2\beta^{-1}}dW_t$$



Invariant pdf is
the Gibbs density:

$$\mu(x) = Z^{-1} e^{-\beta V(x)}$$

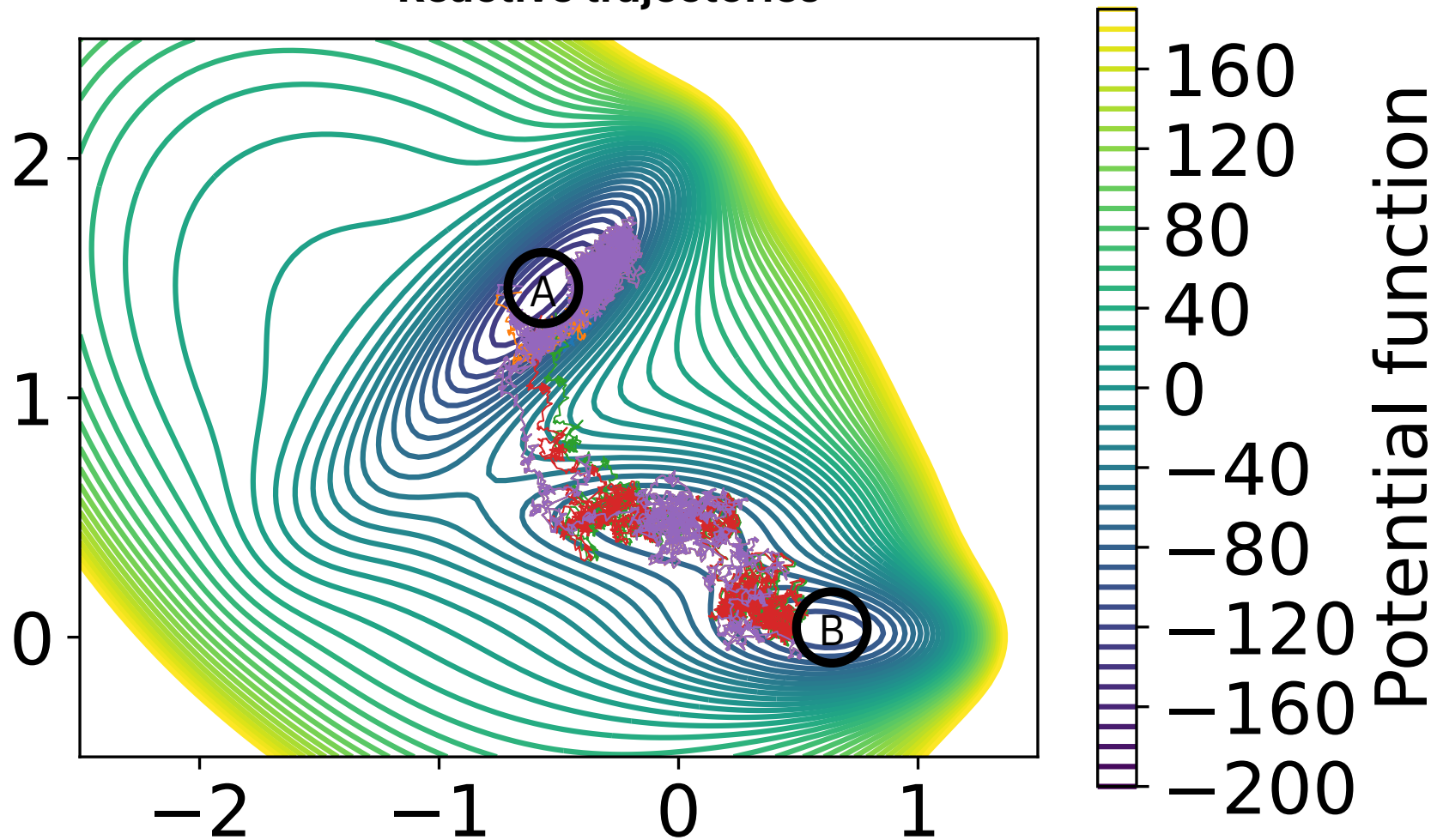
Expected exit time
from the basin of x_{\min} :

$$\mathbb{E}[\tau_{\partial B_{x_{\min}}}] \\ \approx C e^{\beta(V(x_{\text{saddle}}) - V(x_{\min}))}$$

Transition path theory

W. E and E. Vanden-Eijnden, 2006

Reactive trajectories



The **committor** is the probability that the process starting at x will reach region B prior to reaching region A

$$q(x) := \text{Prob}_x(\tau_B < \tau_A)$$

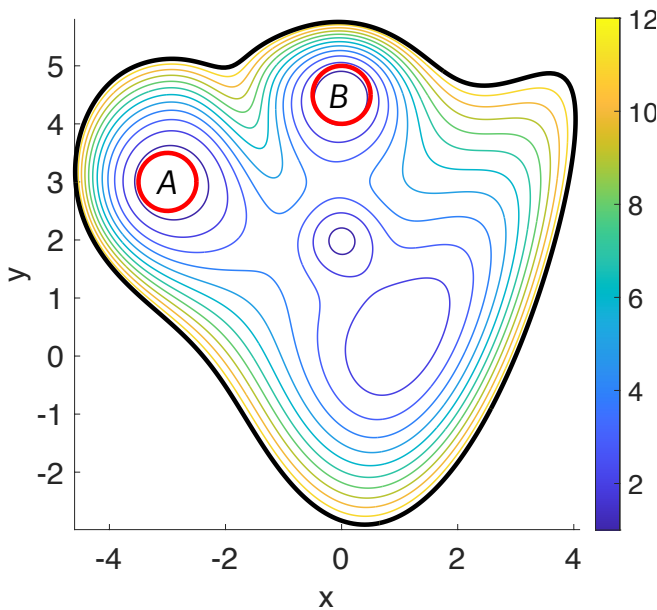
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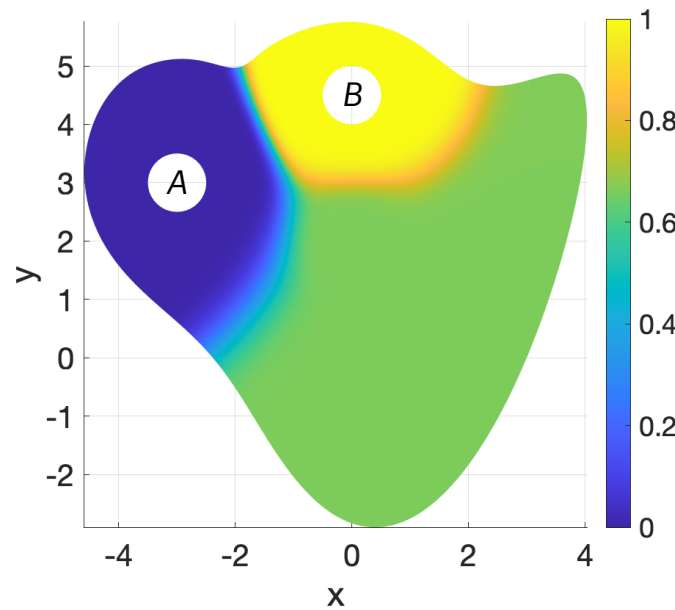
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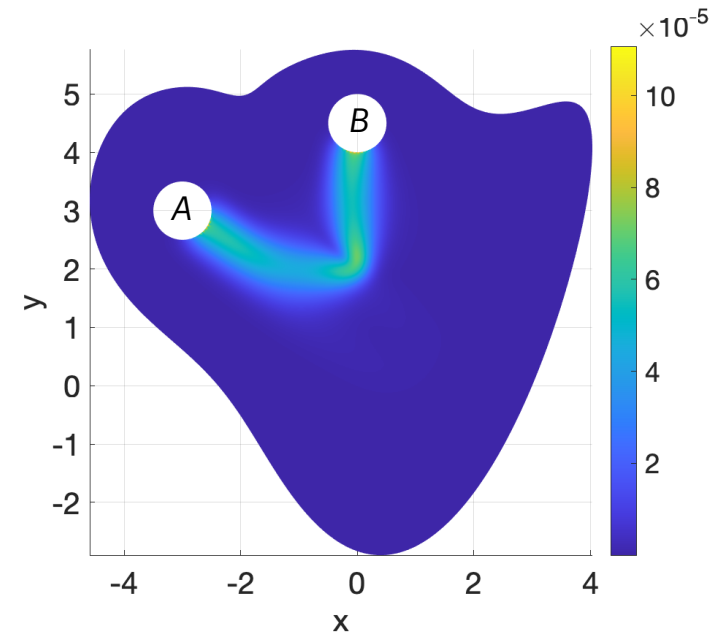
The potential function



The committor



The reactive current



$$\mu(x) = Z^{-1} e^{-\beta V(x)}$$

$$J(x) = \beta^{-1} \mu \nabla q(x)$$

The reaction rate:

$$\nu_{AB} = \beta^{-1} \int_{\Omega_{AB}} \|\nabla q\|^2 \mu dx$$

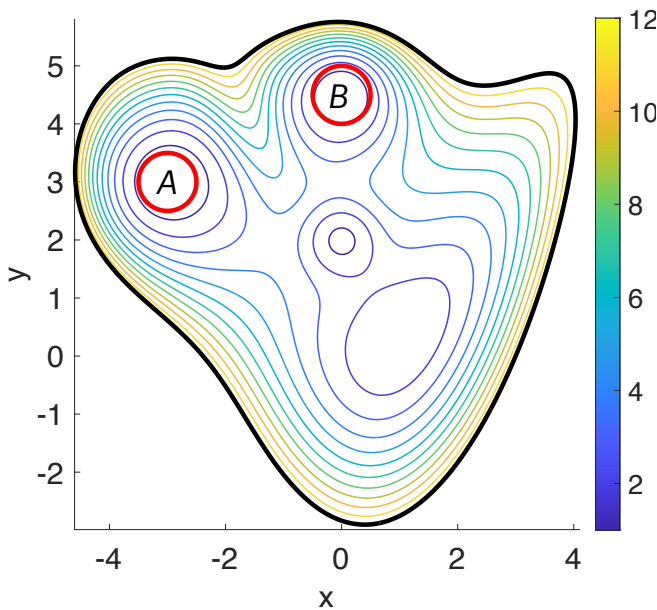
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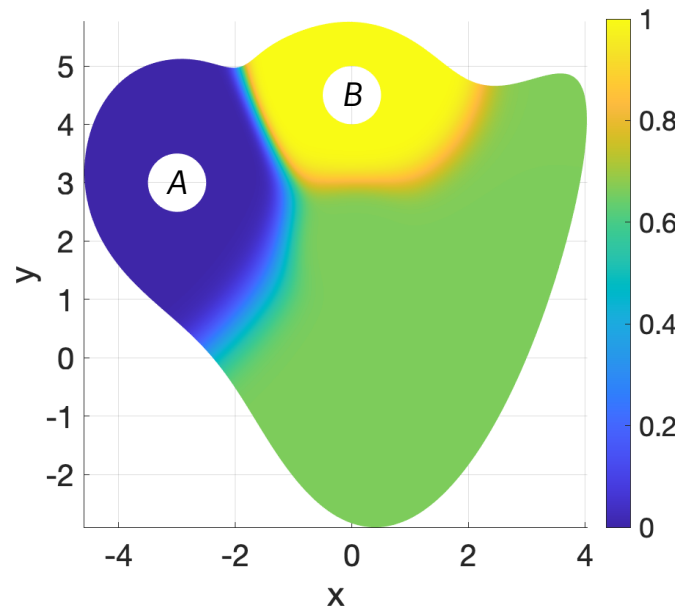
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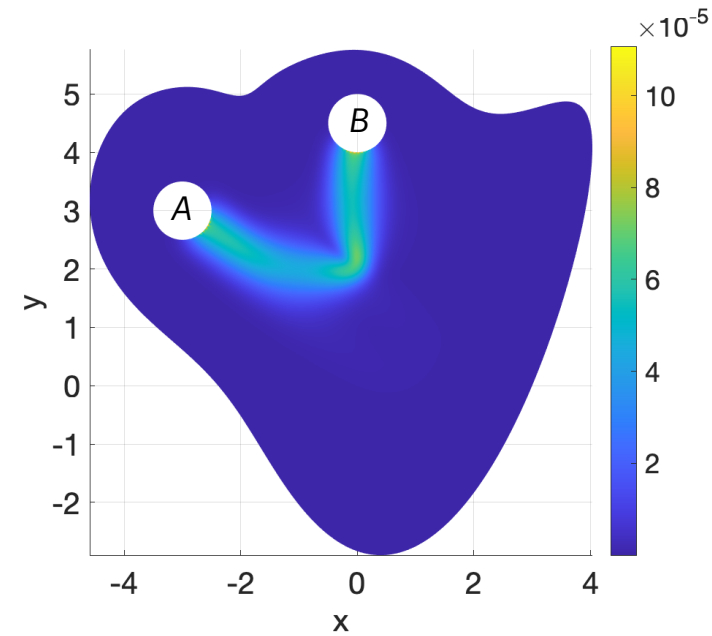
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Computing the committor

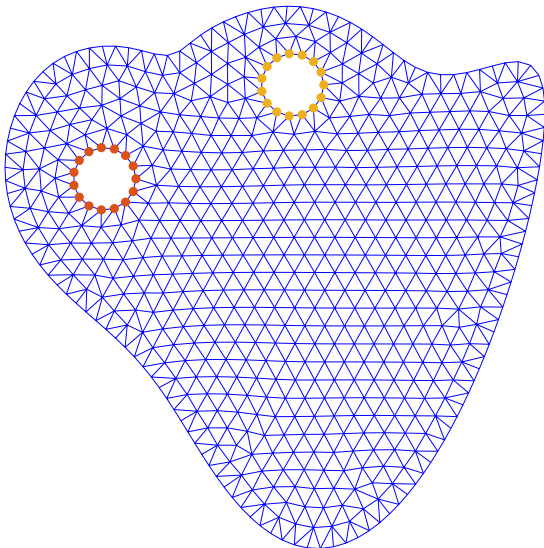
To find the committor, we need to solve:

$$\mathcal{L}q = \beta^{-1} e^{\beta V} \nabla \cdot (e^{-\beta V} \nabla q) = 0$$

$$q(\partial A) = 0$$

$$q(\partial B) = 1$$

- Approach 1: *finite element method*



Good only for low dimensions

$d = 2$: easy to use

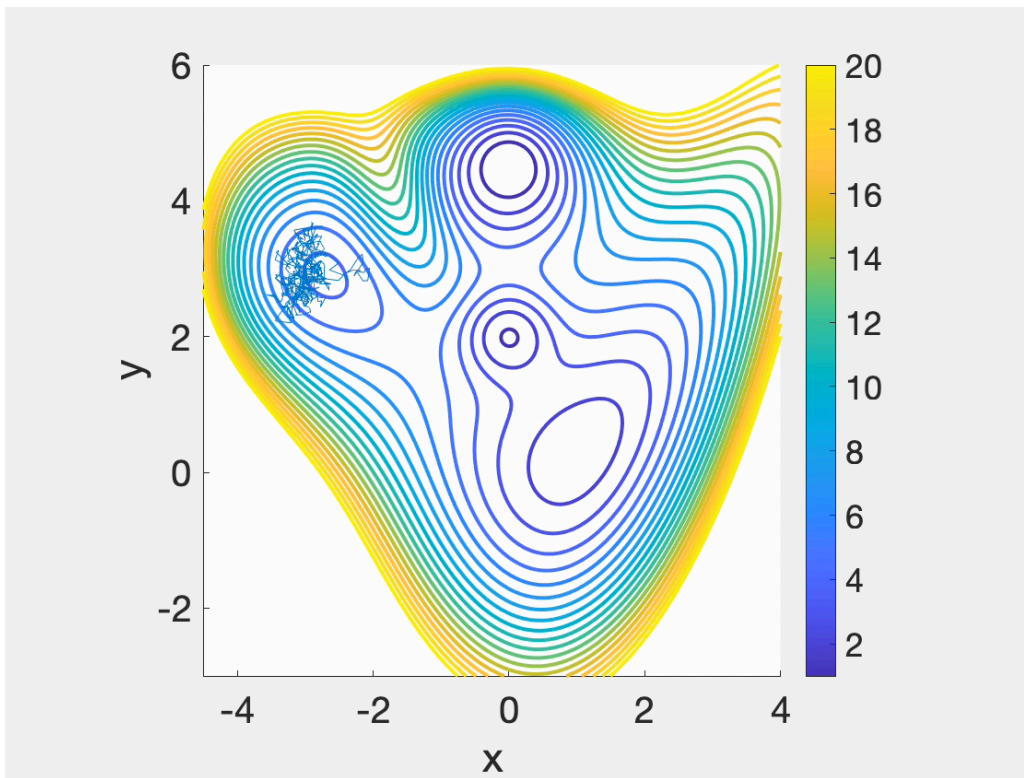
$d = 3$: possible but harder

Computing the committor

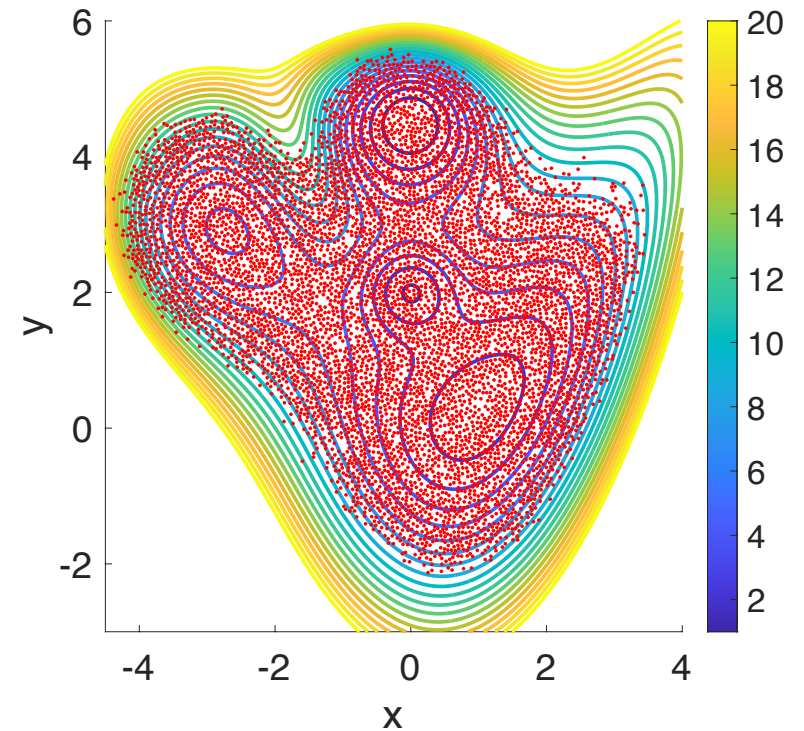
$$\mathcal{L}q = \beta^{-1} e^{\beta V} \nabla \cdot (e^{-\beta V} \nabla q) = 0, \quad q(\partial A) = 0, \quad q(\partial B) = 1$$

- **Meshless approaches:** diffusion maps, neural networks

Enhanced sampling: *metadynamics*



Subsample data set: *delta-net*



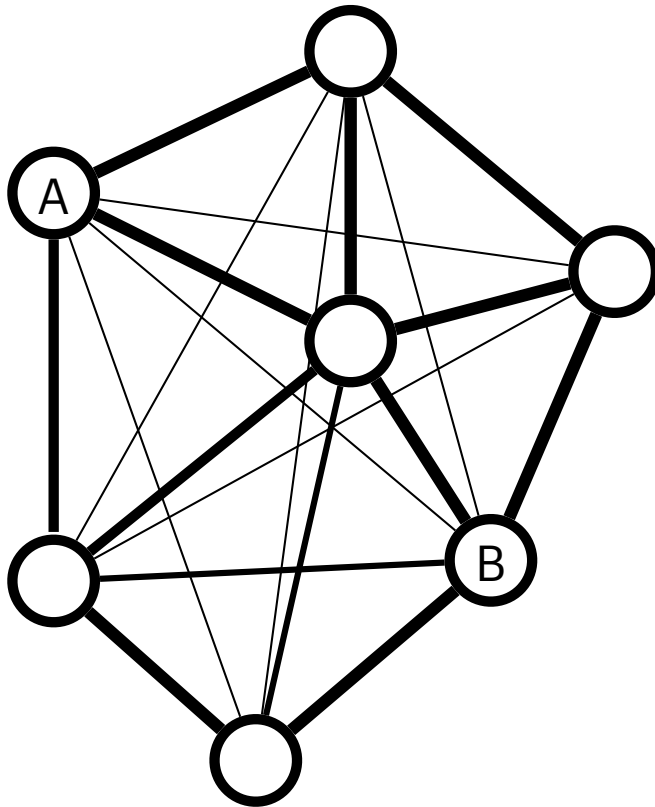
$$\delta = 0.05$$

Computing the committor

- Approach 2: *diffusion map*

Ref: Coifman and Lafon (2006)

Idea: we construct a Markov chain whose dynamics approximate the dynamics of the original SDE



$P = \{P_{ij}\}$ Stochastic matrix

$L = P - I$ Generator matrix

The committor equation

$$\sum_j L_{ij} q_j = 0, \quad i \in (A \cup B)^c$$

$$q_i = 0, \quad i \in A$$

$$q_i = 1, \quad i \in B$$

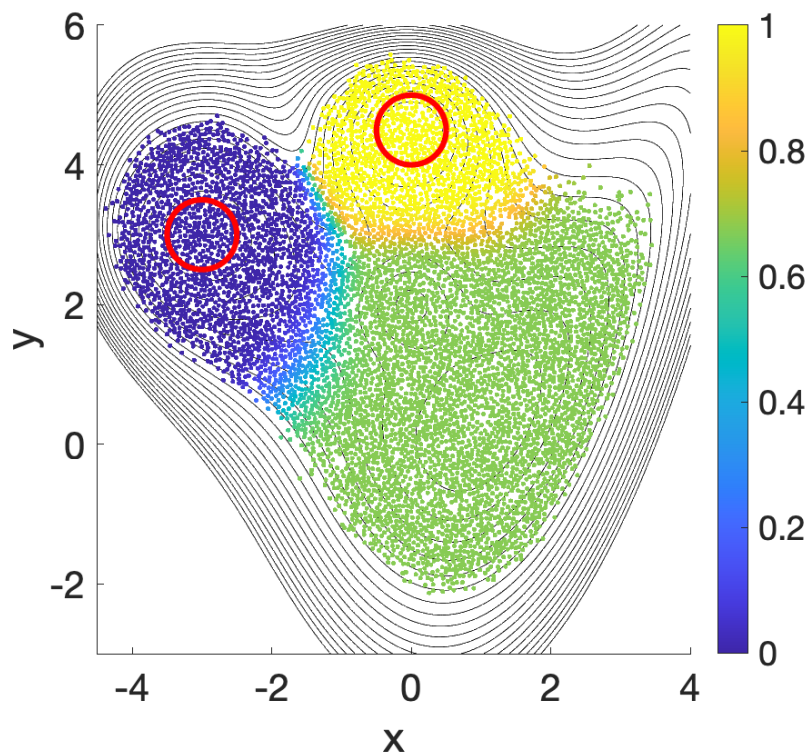
Computing the committor

- Approach 2: *diffusion map*

Key refs: Coifman and Lafon (2006), Banisch, Trstanova, Bittracker, Klus, Koltai (2020)

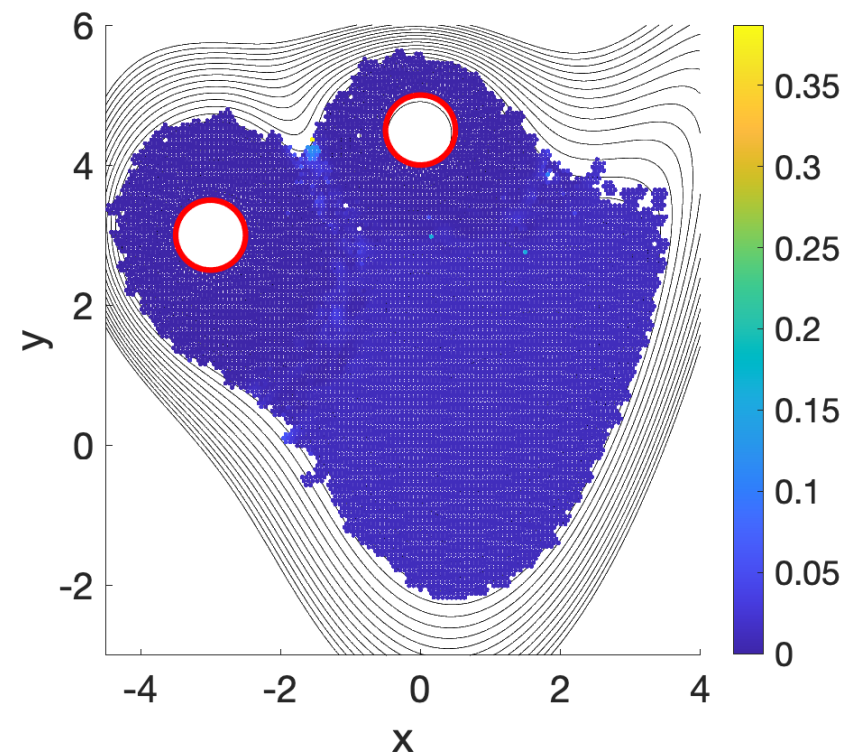
Idea: we construct a Markov chain whose dynamics approximate the dynamics of the reactive trajectories

The committor found using
target measure diffusion map



$\epsilon = 0.01$

Error relative to the FEM solution



$$\sum_j \mu_R(x_j) [q_{FEM}(x_j) - q_{TMDmap}(x_j)] = 1.03 \cdot 10^{-2}$$

Computing the committor

- Approach 3: *neural network*

Key refs: Khoo, Lu, Ying (2018), Li, Lin, Ren (2019)

Idea: setup up an optimization problem for the committor, represent its solution as a neural network, and train the neural network

$$\mathcal{N}(x, \theta) = \sigma_1 (A_1 (\sigma_0 (A_0 x + b_0) + b_1)) \quad \text{A neural network}$$

$$\theta = \{A_0, b_0, A_1, b_1\} \quad \text{The parameters to be found}$$

$$q(x) = f(\mathcal{N}(x, \theta), x)$$

We represent the committor as a function of the neural network

The committor is the solution to:

$$\mathcal{L}q = \beta^{-1} e^{\beta V} \nabla \cdot (e^{-\beta V} \nabla q) = 0$$

$$q(\partial A) = 0$$

$$q(\partial B) = 1$$



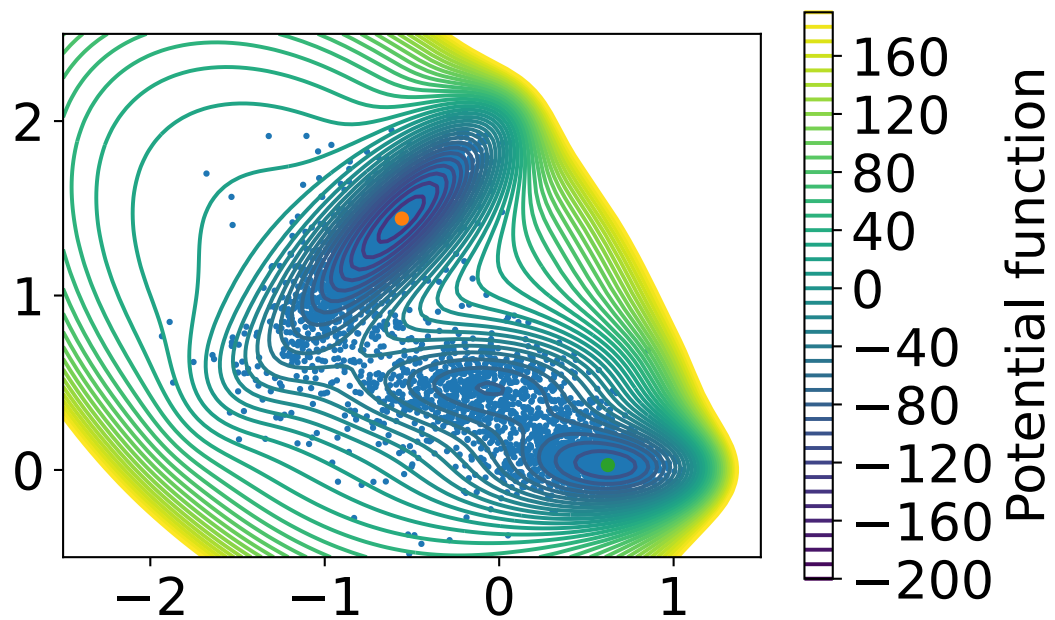
$$\int_{(A \cup B)^c} \|\nabla q\|^2 \mu(x) dx \rightarrow \min$$

subject to

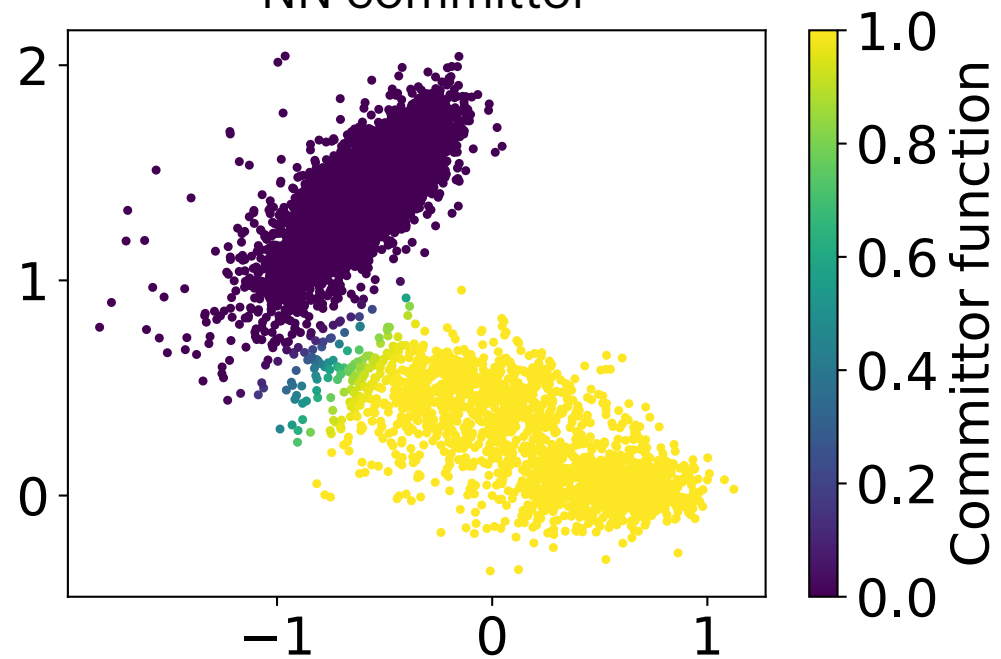
$$q(\partial A) = 0$$

$$q(\partial B) = 1$$

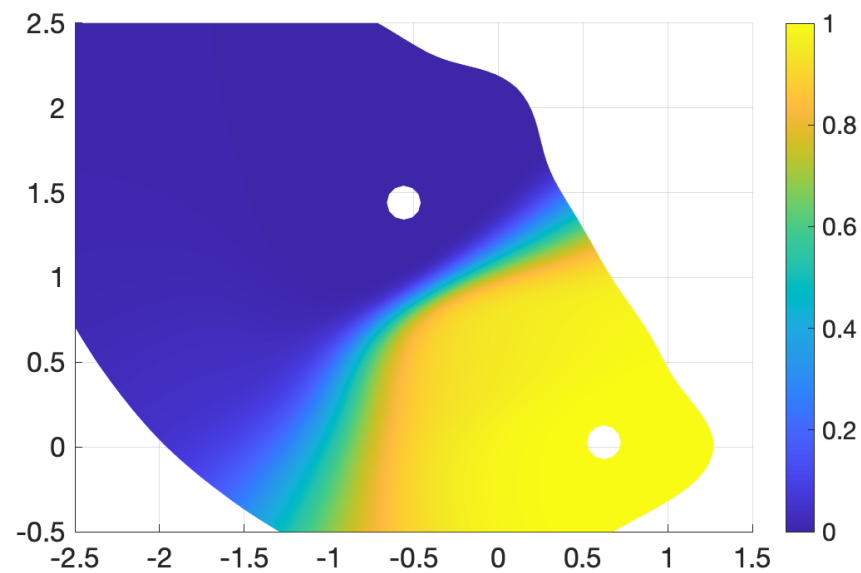
10,000 training points



NN committor



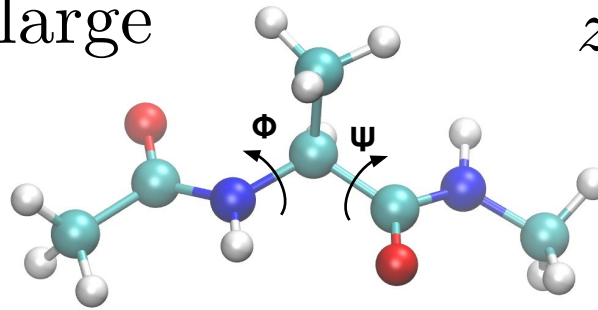
FEM committor



The committor as an optimal controller for sampling reactive trajectories

$x \in \mathbb{R}^n$, n is very large

Full-space data



$z \in \mathbb{R}^d$, d is 2,3,4

Collective variables

- We can approximate the committor $q(z)$ in collective variables via solving the backward Kolmogorov equation via: (1) Diffusion maps, (2) neural networks, (3) tensor trains, (4) FEM (if $d = 2$).
- Use the committor $q(z(x))$ as the **controller** for the stochastic process: Zhang, Sahai, Marzouk <https://arxiv.org/abs/2101.07330>, Gao, Li, Li, Liu <https://arxiv.org/abs/2010.09988>
- Sample rare events in higher-dimensional space. A good test: Alanine dipeptide: go from **two** to **four** dihedral angles.

The committor as an optimal controller for sampling reactive trajectories

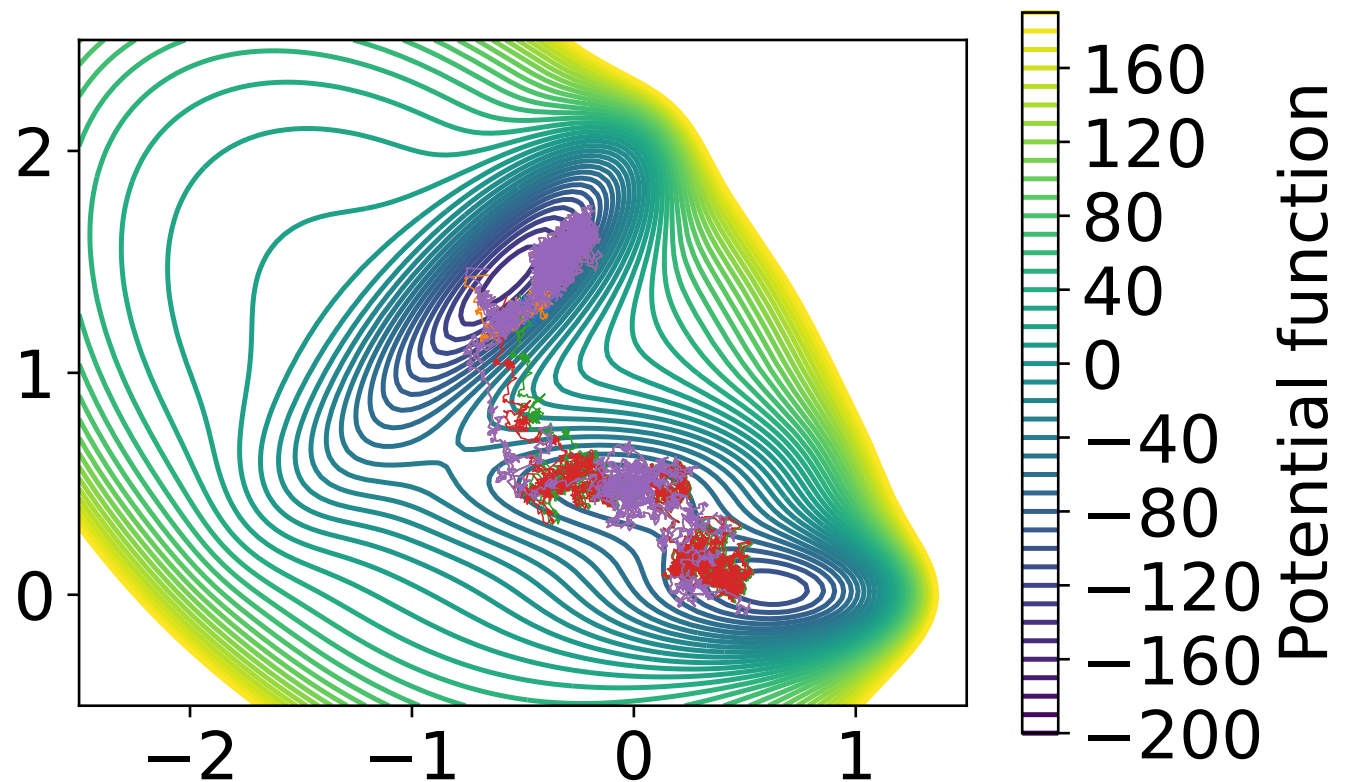
Key ref: Gao, Li, Li, Liu (2020)

The original governing SDE:
$$dX_t = -\nabla V(X_t)dt + \sqrt{2\beta^{-1}}dW_t$$

Modify the drift:
$$dX_t = -\left(\nabla V(X_t) - \frac{2\nabla q(X_t)}{\beta q(X_t)}\right)dt + \sqrt{2\beta^{-1}}dW_t$$

Sample reactive trajectories:

Restore the transition rate
(e.g. B. Keller et al.)



Tutorials

June 14 — June 24

- Stochastic differential equations
- Markov Chains
- Transition Path Theory
- FEM
- Diffusion Maps
- Neural Networks
- Sampling reactive trajectories with the aid of an optimal controller

Tentative projects

- How does the architecture of the neural network affect the accuracy of the solution to the committor problem?
- How should we choose a training set for the neural network?
- Can a low-dimensional approximation to the committor be used to design a controller for a high-dimensional process?
- How can we restore the true transition rate if we are using an SDE with a controller for sampling transition paths?
- How does the training set affect the accuracy of the diffusion map-based solution to the committor problem?
- How can we adapt the diffusion map algorithm to compute committors for more complicated SDEs?
- A case study: alanine-dipeptide molecule described via two or four dihedral angles.
- Extension to systems with inertia: oscillators.