Al Pictures at a Mathematical Exhibition: How Applied Harmonic Analysis meets Machine Learning

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Acknowledgments



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Papers available online at:

https://www.math.umd.edu/ rvbalan/



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Oay 2: Permutation invariant representations and Euclidean embeddings

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- 2. Permutation Invariant Representations for $V = R^{n \times d}$
- 3. Polynomial Embeddings
- 4. Sorting based Embeddings
- 4 Day 2: G-invariant representations and Euclidean embeddings
 - 1. Invariant Coorbit Representations
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 - 3. Bi-Lipschitz Property

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High-Level Overview

In this series of lectures, we discuss a few harmonic analysis techniques and problems applied to machine learning.

1. NN: Neural networks (NN) and their universal approximation property. 2. Lipschitz analysis: we provide rationals for studying Lipschitz properties of NNs, and then we perform a Lipschitz analysis of these networks. We focus on two aspects of this analysis: stochastic modeling of local vs. global analysis, and a scattering network inspired Lipschitz analysis of convolutive networks.

3. Invariance and Equivariance: We highlight the duality between invariance and covariance/equivariance, with focus on G-invariant representations.

4. Applications to data analysis and modeling: We present applications on a variety of problems: classification and regression on graphs; generative models for data sets; neural network based modeling of time-evolution of dynamical systems; discrete optimizatons.

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Joint works with:

Naveed Haghani (UMD,APL-JHU)Daniel Levy (UMD)Maneesh Singh (Verisk, Comcast)Efstratos Tsoukanis (UMD)

R. Balan, N. Haghani, M. Singh, "Permutation Invariant Representations with Applications to Graph Deep Learning", arXiv preprint: 2203.07546 [math.FA], [cs.LG]

R. Balan, E. Tsoukanis, "Relationships between the Phase Retrieval Problem and Permutation Invariant Embeddings", arXiv preprint: 2306.13111 [math.FA]

High-Level View

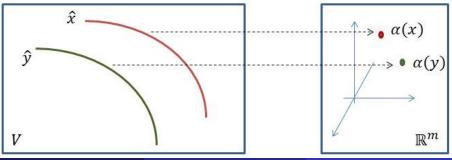
Two related problems with many variations:

Given a (discrete) group G acting on a normed space V:

Construct a (bi)Lipschitz Euclidean embedding of the quotient space V/G, α : V̂ → ℝ^m. Classification of cosets.

Construct the projection onto cosets,

$$\pi: V \to [y] = \hat{y} = \{g.y \ , \ g \in G\}.$$



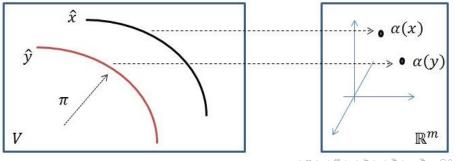
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Overview

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- Q Construct projections onto cosets, *π* : *V* → [*y*] = ŷ = {*g*.*y*, *g* ∈ *G*}. Optimizations within cosets.





2 Day 1: Neural Networks and Lipschitz Analysis

Oay 2: Permutation invariant representations and Euclidean embeddings

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1. Motivat	ion			

A. Similarity of Matrices

Consider two symmetric matrices $A, B \in \text{Sym}(n)$. When are they equivalent modulo an orthonormal change of coordinates? Specifically, is there an orthogonal matrix $U \in O(n)$ so that $B = UAU^T$?

An elementary derivation in linear algebra shows that $A \stackrel{O(n)}{\sim} B$ if and only if A and B have the same set of eigenvalues with exactly same multiplicities.

But what about other groups G? For instance what about the group of permutation matrices S_n ?

Find necessary and sufficient conditions so that $A \stackrel{S_n}{\sim} B$. Recall:

 $S_n = \{P \in O(n) : P_{i,j} \in \{0,1\}\} = O(n) \cap \{W \in [0,1]^{n \times n} : W1 = 1, W^T = 1\}$

1. Motivation

A. The Graph Isomorphism Problem

Consider two graphs $G = (\mathcal{V}, \mathcal{E})$ and $\tilde{G} = (\tilde{\mathcal{V}}, \tilde{\mathcal{E}})$ with *n* nodes. The graph isomorphism problem is the computational problem of determining whether these graphs are identical after a relabeling of nodes.

If A and \tilde{A} denote their adjacency matrices, these graphs are isomorphic if and only if $\tilde{A} = \Pi A \Pi^T$ for some permutation matrix $\Pi \in S_n$.

Current state-of-the-art (Wikipedia): Babai (2015,2017) presented a quasi-polynomial algorithm with running time $2^{O((\log n)^c)}$, for some fixed c > 0. Helfgott (2017) claims that one can take c = 3.

Similar problem can be stated for weighted graphs: $A, \tilde{A} \in \text{Sym}(n)$ with nonnegative entries, isomorphic if and only if $\tilde{A} = \Pi A \Pi^T$ for some $\Pi \in S_n$.

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B. Graph Alignment Problems

Motivation

Consider two $n \times n$ symmetric matrices A, B. In the alignment problem for quadratic forms one seeks an orthogonal matrix $U \in O(n)$ that minimizes

$$\|UAU^{\mathsf{T}} - B\|_{F}^{2} := trace((UAU^{\mathsf{T}} - B)^{2}) = \|A\|_{F}^{2} + \|B\|_{F}^{2} - 2trace(UAU^{\mathsf{T}}B).$$

The solution is well-known and depends on the eigendecomposition of matrices A, B: if $A = U_1 D_1 U_1^T$, $B = U_2 D_2 U_2^T$ then

$$U_{opt} = U_2 U_1^T$$
, $||U_{opt} A U_{opt}^T - B||_F^2 = \sum_{k=1}^n |\lambda_k - \mu_k|^2$,

where $D_1 = diag(\lambda_k)$ and $D_2 = diag(\mu_k)$ are diagonal matrices with eigenvalues ordered monotonically.

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B. Quadratic Assignment Problem

The challenging case is when U is constrained to the permutation group as is the case in the graph matching problem. In this case, the optimization problem becomes

$$\min_{U\in\mathcal{S}_n} \|UAU^T - B\|_F$$

turns into a QAP:

 $\max_{U\in\mathcal{S}_n} trace(UAU^TB).$

This is equivalent to computing the natural distance $\mathbf{d}(\hat{A}, \hat{B}) = \min_{P,Q \in S_n} \|PAP^T - QBQ^T\|_F$ between the equivalence classes $\hat{A}, \hat{B} \in \widehat{\text{Sym}(n)}$ induced by the group action $S_n \times \text{Sym}(n) \to \text{Sym}(n)$, $(\Pi, A) \mapsto \Pi A \Pi^T$.

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C. Graph Learning Problems

Given a data graph (e.g., social network, transportation network, citation network, chemical network, protein network, biological networks):

- Graph adjacency or weight matrix, $A \in \mathbb{R}^{n \times n}$;
- Data matrix, $X \in \mathbb{R}^{n \times r}$, where each row corresponds to a feature vector per node.
- Contruct a map $f: (A, X) \rightarrow f(A, X)$ that performs:
 - classification: $f(A, X) \in \{1, 2, \cdots, c\}$
 - **2** regression/prediction: $f(A, X) \in \mathbb{R}$.

Key observation: The outcome should be invariant to vertex permutation: $f(PAP^T, PX) = f(A, X)$, for every $P \in S_n$.

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1. Motivation				

Invariance vs. Equivariance

Graph learning problems are prime examples of the difference between *invariant* vs. *equivariant* representations.

If the machine learning task is **node** classification or regression:

$$f:(A,X)\mapsto f(A,X)\ \in\ \{1,2,\cdots,c\}^n \ ext{or}\ \mathbb{R}^n$$

where f(A, X) is a graph signal, i.e., $f(A, X)_i$ is signal at node *i*, then the nonlinear map *f* is *equivariant* and must satisfy $f(PAP^T, PX) = Pf(A, X)$, for all $P \in S_n$.

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On the other hand, if the machine learning task is **graph** classification or regression,

$$f:(A,X)\mapsto f(A,X)\ \in\ \{1,2,\cdots,c\}$$
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where f(A, X) is assigned for the entire graph, then the nonlinear map f is *invariant* and must satisfy $f(PAP^T, PX) = f(A, X)$, for all $P \in S_n$.

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C. Graph Convolution Networks (GCN), Graph Neural

Networks (GNN)

General architecture of a $\mathsf{GCN}/\mathsf{GNN}$

$$\begin{array}{c} A \\ \hline X \end{array} Y_1 = \sigma(\tilde{A} X W_1 + B_1) \end{array} \xrightarrow{} Y_2 = \sigma(\tilde{A} Y_1 W_2 + B_2) \qquad \dots \qquad Y_L = \sigma(\tilde{A} Y_{L-1} W_L + B_L) \xrightarrow{Y} \end{array}$$

GCN (Kipf and Welling ('16)) choses $\tilde{A} = I + A$; GNN (Scarselli et.al. ('08), Bronstein et.al. ('16)) choses $\tilde{A} = p_I(A)$, a polynomial in adjacency matrix. L-layer GNN has parameters $(p_1, W_1, B_1, \dots, p_L, W_L, B_L)$.

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C. Graph Convolution Networks (GCN), Graph Neural Networks (GNN)

General architecture of a GCN/GNN

$$\begin{array}{c} A \\ \hline X \\ \end{array} Y_1 = \sigma(\tilde{A} X W_1 + B_1) \\ \end{array} Y_2 = \sigma(\tilde{A} Y_1 W_2 + B_2) \\ \cdots \\ Y_L = \sigma(\tilde{A} Y_{L-1} W_L + B_L) \\ \end{array} Y_2$$

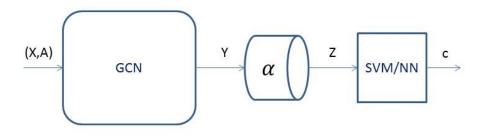
GCN (Kipf and Welling ('16)) choses $\tilde{A} = I + A$; GNN (Scarselli et.al. ('08), Bronstein et.al. ('16)) choses $\tilde{A} = p_l(A)$, a polynomial in adjacency matrix. *L*-layer GNN has parameters $(p_1, W_1, B_1, \dots, p_L, W_L, B_L)$.

Note the *covariance* (or, equivariance) property: for any $P \in O(n)$ (including S_n), if $(A, X) \mapsto (PAP^T, PX)$ and $B_i \mapsto PB_i$ then $Y \mapsto PY$.



C. Deep Learning with GCN/GNN

The approach for the two learning tasks (classification or regression) is based on the following scheme (see also Maron et.al. ('19)):



where α is a permutation invariant map (embedding), and SVM/NN is a single-layer or a deep neural network (Support Vector Machine or a Fully Connected Neural Network) trained on invariant representations. The purpose of this talk is to analyze the α component.

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HA - ML Day 2

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2. Permutation Invariant Representations for $V = R^{n \times d}$

The metric space \hat{V} when $V = \mathbb{R}^{n \times d}$

Recall the equivalence relation \sim on $V = \mathbb{R}^{n \times d}$ induced by the group of permutation matrices S_n acting on V by left multiplication: for any $X, X' \in \mathbb{R}^{n \times d}$,

$$X \sim X' \;\; \Leftrightarrow \;\; X' = PX \;, \; \mathrm{for \; some} \; P \in \mathcal{S}_n$$

Let $\mathbb{R}^{n \times d} = \mathbb{R}^{n \times d} / \sim$ be the quotient space endowed with the natural distance induced by Frobenius norm $\| \cdot \|_F$

$$\mathbf{d}(\hat{X}_{1},\hat{X}_{2}) = \min_{P \in S_{n}} \|X_{1} - PX_{2}\|_{F} , \quad \hat{X}_{1},\hat{X}_{2} \in \widehat{\mathbb{R}^{n \times d}}.$$

2. Permutation Invariant Representations for $V = R^{n \times d}$

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$$\mathbf{d}(\hat{X}_{1}, \hat{X}_{2}) = \min_{P \in S_{n}} \|X_{1} - PX_{2}\|_{F} , \quad \hat{X}_{1}, \hat{X}_{2} \in \widehat{\mathbb{R}^{n \times d}}.$$

The computation of the minimum distance is performed by solving the Linear Assignment Problem (LAP) whose convex relaxation is exact:

$$\max_{P \in \mathcal{S}_n} trace(PX_2X_1^T) = \max_{W \in DS(n)} trace(WX_2X_1^T)$$

where $DS(n) = \{ W \in [0, 1]^{n \times n} : W1 = 1, W^T = 1 \}$ is the convex set of doubly stochastic matrices.

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The embedding problem

Problem: Construct a bi-Lipschitz embedding $\hat{\alpha} : \mathbb{R}^{n \times d} \to \mathbb{R}^m$, i.e., an integer m = m(n, d), a map $\alpha : \mathbb{R}^{n \times d} \to \mathbb{R}^m$ with constants $0 < a \le b < \infty$ so that for any $X, X' \in \mathbb{R}^{n \times d}$, 1 If $X \sim X'$ then $\alpha(X) = \alpha(X')$. 2 If $\alpha(X) = \alpha(X')$ then $X \sim X'$. 3 $a \cdot \mathbf{d}(\hat{X}, \hat{X}') \le \|\alpha(X) - \alpha(X')\|_2 \le b \cdot \mathbf{d}(\hat{X}, \hat{X}')$. where $\mathbf{d}(\hat{X}, \hat{X}') = \min_{P \in S_n} \|X - PX'\|_F$.
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2. Permutation Invariant Representations for $V = R^{n \times d}$

A Universal Embedding

Consider the map

$$\mu: \widehat{\mathbb{R}^{n \times d}} \to \mathcal{P}(\mathbb{R}^d) \ , \ \mu(X)(x) = \frac{1}{n} \sum_{k=1}^n \delta(x - x_k)$$

where $\mathcal{P}(\mathbb{R}^d)$ denotes the convex set of probability measures over \mathbb{R}^d , and δ denotes the Dirac measure. x_k is the k^{th} row of X. Clearly $\mu(X') = \mu(X)$ iff X' = PX for some $P \in S_n$. The Wasserstein-2 distance is isometrically equivalent to **d**:

$$W_2(\mu(X),\mu(Y))^2 := \inf_{q \in J(\mu(X),\mu(Y))} \mathbb{E}_q[\|x-y\|_2^2] = \min_{P \in S_n} \|Y-PX\|^2$$

By Kantorovich-Rubinstein theorem, the Wasserstein-1 distance (the Earth moving distance) extends to a norm on the space of signed Borel measures.

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By Kantorovich-Rubinstein theorem, the Wasserstein-1 distance (the Earth moving distance) extends to a norm on the space of signed Borel measures. Main drawback: $\mathcal{P}(\mathbb{R}^d)$ is infinite dimensional!

Finite Dimensional Embeddings

Idea: "Project" the measure onto a finite dimensional space. This is accomplished by *kernel methods*:

Fix a family of functions f_1, \dots, f_m and consider:

$$\mu(X)\mapsto \int_{\mathbb{R}^d}f_j(x)d\mu(X)=rac{1}{n}\sum_{k=1}^nf_j(x_k)\ ,\ j\in[m]$$

2. Permutation Invariant Representations for $V = R^{n \times d}$

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Possible choices:

 Polynomial embeddings: ℝ[X]^{S_n}, ring of invariant polynomials; [Lipman&al.],[Peyré&al.],[Sanay&al.],[Kemper book] ...

2 Gaussian kernels: $f_j(x) = exp(-||x - a_j||^2/\sigma_j^2)$; [Gilmer&al.],[Zaheer&al.], [Vinyals&al.],...

• Fourier kernels (cmplx embd): $f_j(x) = exp(2\pi i \langle x, \omega_j \rangle)$; related to Prony method; [Li&Liao] for bi-Lipschitz estimates.

Main drawback: No global bi-Lipschitz embeddings [Cahill&al.'19]. Ok on (some) compacts.

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3. Polynomial Embeddings

Polynomial Expansions - Quadratics

In the case d = 1 recall Vieta's formulas, Newton-Girard identities

$$P(X) = \prod_{k=1}^{N} (X - x_k) \leftrightarrow \left(\sum_k x_k, \sum_k x_k^2, ..., \sum_k x_k^n\right)$$

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$$P(X) = \prod_{k=1}^{N} (X - x_k) \leftrightarrow \left(\sum_k x_k, \sum_k x_k^2, ..., \sum_k x_k^n\right)$$

For d > 1, consider the quadratic *d*-variate polynomial:

$$P(Z_1, \dots, Z_d) = \prod_{k=1}^n \left((Z_1 - x_{k,1})^2 + \dots + (Z_d - x_{k,d})^2 \right)$$
$$= \sum_{p_1, \dots, p_d=0}^{2n} a_{p_1, \dots, p_d} Z_1^{p_1} \cdots Z_d^{p_d}$$

Encoding complexity:

$$m=\left(egin{array}{c} 2n+d\ d\end{array}
ight)\sim (2n)^d.$$

Polynomial Expansions - Quadratics (2)

A more careful analysis of $P(Z_1, ..., Z_d)$ reveals a form:

$$P(Z_1, ..., Z_d) = t^n + Q_1(Z_1, ..., Z_d)t^{n-1} + \dots + Q_{n-1}(Z_1, ..., Z_d)t + Q_n(Z_1, ..., Z_d)$$

where $t = Z_1^2 + \dots + Z_d^2$ and each $Q_k(Z_1, ..., Z_d) \in \mathbb{R}_k[Z_1, ..., Z_d]$ is a (non-homogeneous) polynomial of degree k. Hence one needs to encode:

$$m = \begin{pmatrix} d+1\\1 \end{pmatrix} + \begin{pmatrix} d+2\\2 \end{pmatrix} + \dots + \begin{pmatrix} d+n\\n \end{pmatrix} = \begin{pmatrix} d+n+1\\n \end{pmatrix} - 1$$

number of coefficients.

A significant drawback: Inversion is numerically unstable and embedding is not Lipschitz.

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Readout Mapping Approach

Polynomial Expansion - Linear Forms

A stable (Lipschitz, not bi-Lipschitz!) embedding can be constructed as follows (see also Gobels' algorithm (1996) or [Derksen, Kemper '02]). Consider the *n* linear forms $\lambda_k(Z_1, ..., Z_d) = x_{k,1}Z_1 + \cdots \times x_{k,d}Z_d$. Construct the polynomial in variable *t* with coefficients in $\mathbb{R}[Z_1, ..., Z_d]$:

$$P(t) = \prod_{k=1}^{n} (t - \lambda_k(Z_1, ..., Z_d)) = t^n - e_1(Z_1, ..., Z_d) t^{n-1} + \dots (-1)^n e_n(Z_1, ..., Z_d)$$
$$= t^n + \sum_{\substack{p_0, p_1, \cdots, p_d \ge 0\\ p_0 + p_1 + \dots + p_d = n}} c_{p_0, p_1, \cdots, p_d} t^{p_0} Z_1^{p_1} \cdots Z_d^{p_d}$$

The elementary symmetric polynomials $(e_1, ..., e_n)$ are in 1-1 correspondence (Newton-Girard theorem) with the moments: $\mu_p = \sum_{k=1}^n \lambda_k^p (Z_1, ..., Z_d), \ 1 \le p \le n.$

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Polynomial Expansions - Linear Forms (2)

Each μ_p is a homogeneous polynomial of degree p in d variables. Hence to encode each of them one needs $\begin{pmatrix} d+p-1\\p \end{pmatrix}$ coefficients. Hence the embedding dimension is

$$m_0 = \begin{pmatrix} d \\ 1 \end{pmatrix} + \begin{pmatrix} d+1 \\ 2 \end{pmatrix} + \dots + \begin{pmatrix} d+n-1 \\ n \end{pmatrix} = \begin{pmatrix} d+n \\ n \end{pmatrix} - 1$$

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The map $\alpha_0 : \mathbb{R}^{n \times d} \to \mathbb{R}^{m_0}$, $X \mapsto (c_{p_0,p_1,\cdots,p_d})_{p_0,p_1,\cdots,p_d}$ is injective modulo S_n but it is not Lipschitz. However a simple modification as suggested by [Cahill et.al.'19] makes it Lipschitz.

Polynomial Lipschitz embedding

Denote by L_0 the Lipschitz constant of α_0 when restricted to the closed unit ball $B_1(\mathbb{R}^{n \times d}) : \{X \in \mathbb{R}^{n \times d}, \|X\| \leq 1\}$ of $\mathbb{R}^{n \times d}$, i.e. $\|\alpha_0(X) - \alpha_0(Y)\| \leq L_0 \|X - Y\|$ for any $X, Y \in \mathbb{R}^{n \times d}$ with $\|X\|, \|Y\| \leq 1$. Let $\varphi_0 : \mathbb{R} \to [0, 1], \varphi_0(x) = \min(1, \frac{1}{x})$ be a Lipschitz monotone decreasing function with Lipschitz constant 1.

Theorem

The map:

$$\alpha_1: \mathbb{R}^{n \times d} \to \mathbb{R}^m \ , \ \alpha_1(X) = \begin{pmatrix} \alpha_0 \left(\varphi_0(\|X\|) X \right) \\ \|X\| \end{pmatrix},$$

with $m = \begin{pmatrix} n+d \\ d \end{pmatrix} = m_0 + 1$ lifts to an injective and globally Lipschitz map $\hat{\alpha}_1 : \mathbb{R}^{n \times d} \to \mathbb{R}^m$ with Lipschitz constant $Lip(\hat{\alpha}_1) \le \sqrt{1 + L_0^2}$.

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3. Polynomial Embeddings								
Minir	nalit	у						

For
$$d = 1$$
, $m = n$ which is minimal.

For
$$d = 2$$
, $m = \frac{n^2 + 3n}{2}$. Is this minimal?

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3. Polynon	nial Embe	eddings		
Algeb	oraic	Embedding		

Encoding using Complex Roots

Idea: Consider the case d = 2. Then each $x_1, \dots, x_n \in \mathbb{R}^2$ can be replaced by *n* complex numbers $z_1, \dots, z_n \in \mathbb{C}$, $z_k = x_{k,1} + ix_{k,2}$. Consider the complex polynomial:

$$Q(z) = \prod_{k=1}^{n} (z - z_k) = z^n + \sum_{k=1}^{n} \sigma_k z^{n-k}$$

which requires n complex numbers, or 2n real numbers.

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3. Polynon	nial Embe	ddings		
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Algebraic Embedding Encoding using Complex Roots

Idea: Consider the case d = 2. Then each $x_1, \dots, x_n \in \mathbb{R}^2$ can be replaced by *n* complex numbers $z_1, \dots, z_n \in \mathbb{C}$, $z_k = x_{k,1} + ix_{k,2}$. Consider the complex polynomial:

$$Q(z) = \prod_{k=1}^{n} (z - z_k) = z^n + \sum_{k=1}^{n} \sigma_k z^{n-k}$$

which requires n complex numbers, or 2n real numbers.

Open problem: Can this construction be extended to $d \ge 3$? Remark: A drawback of polynomial (algebraic) embeddings: [Cahill'19] showed that polynomial embeddings of translation invariant spaces cannot be bi-Lipschitz.

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4. Sorting	based En	nbeddings		
The	Max	Pool approach		

The idea is provided by the following observation.

Let $\downarrow: \mathbb{R}^n \to \mathbb{R}^n$ denote the *sorting map* $x \mapsto \downarrow x = \prod x$, $\prod \in S_n$, so that

 $(\Pi x)_1 \geq (\Pi x)_2 \geq \cdots \geq (\Pi x)_n.$

Overview	Day 1 ○	Day 2: Permutation invariant representations	Day 2: G-invariant representations	Day 3
4. Sorting	based En	nbeddings		
The	Max	Pool approach		

The idea is provided by the following observation.

Let $\downarrow: \mathbb{R}^n \to \mathbb{R}^n$ denote the sorting map $x \mapsto \downarrow x = \Pi x$, $\Pi \in S_n$, so that

 $(\Pi x)_1 \geq (\Pi x)_2 \geq \cdots \geq (\Pi x)_n.$

Lemma

 $\downarrow: \widehat{\mathbb{R}^n} \to \mathbb{R}^n$ is an isometry (hence bi-Lipschitz):

$$\|\downarrow(x)-\downarrow(y)\|=\min_{P\in\mathcal{S}_n}\|x-Py\|\;,\;\; ext{for all }\;x,y\in\mathbb{R}^n.$$

Proof is based on the rearrangement inequality (see Wikipedia, or Hardy-Littlewood-Pólya "Inequalities" §10.2).

Our main goal is to extend this construction from \mathbb{R}^n to $\mathbb{R}^{n \times d}$

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 4. Sorting based Embeddings
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Recall the equivalence relation, for $X, Y \in \mathbb{R}^{n \times d}$,

$$X \sim Y \quad \Leftrightarrow \quad \exists \Pi \in \mathcal{S}_n \ , \ Y = \Pi X$$

that induces a quotient space $\widehat{\mathbb{R}^{n \times d}} = \mathbb{R}^{n \times d} / \sim$ and the natural distance

$$\mathbf{d}:\widehat{\mathbb{R}^{n\times d}}\times\widehat{\mathbb{R}^{n\times d}}\to\mathbb{R} \ , \ \mathbf{d}([X],[Y])=\min_{\Pi\in\mathcal{S}_n}\|X-\Pi Y\|_F$$

In the following we construct an Euclidean embedding of the form

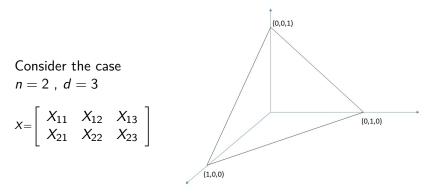
$$\beta_A : \mathbb{R}^{n \times d} \to \mathbb{R}^{n \times D} , \quad \beta_A(X) = \downarrow (XA)$$

where \downarrow (·) sorts decreasingly each column of \cdot , independently. The matrix $A \in \mathbb{R}^{d \times D}$ is called the *key* of encoder β_A . The key is called *universal* if $\widehat{\beta_A} : \widehat{\mathbb{R}^{n \times d}} \to \mathbb{R}^{n \times D}$ is injective.

Radu Balan (UMD)

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Intuition behind universality of keys

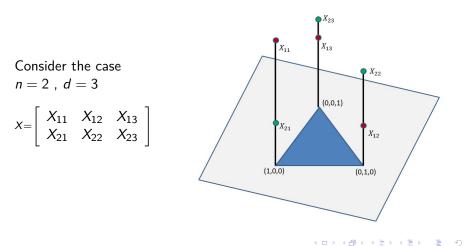


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4. Sorting based Embeddings

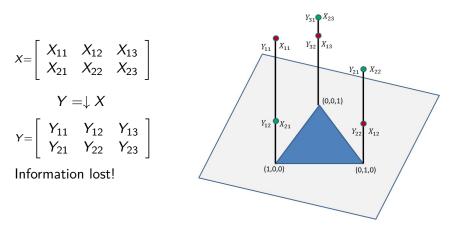
Intuition behind universality of keys



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 Day 3: G-invariant representations

4. Sorting based Embeddings

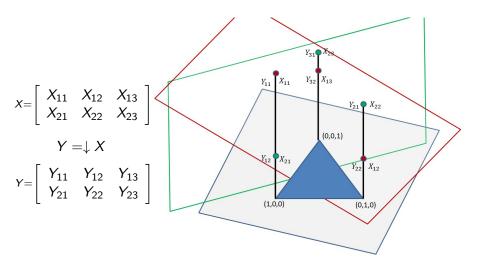
Intuition behind universality of keys



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4. Sorting based Embeddings

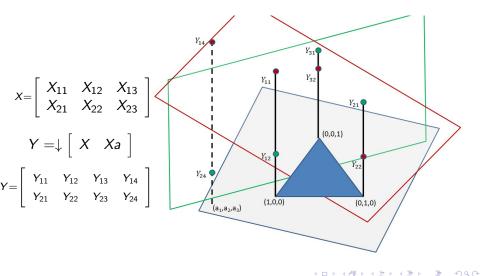
Intuition behind universality of keys



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Intuition for this encoder



Three results (1)

Existence of Universal Keys

Theorem

Consider the metric space $(\mathbb{R}^{n \times d}, \mathbf{d})$. Set D = 1 + (d - 1)n! and let $A \in \mathbb{R}^{d \times D}$ be a matrix whose columns form a full spark frame. Then the key A is universal and the induced map $\hat{\beta}_A : \mathbb{R}^{n \times d} \to \mathbb{R}^{n \times D}$, $\hat{\beta}_A([X]) = \downarrow (XA)$ is injective. Furthermore, $\hat{\beta}_A$ is bi-Lipschitz with constants $a_0 = \min_{J \subset [D], |J| = d} s_d(A[J])$ and $b_0 = s_1(A)$, where $s_1(A)$ denotes the largest singular value of A, A[J] denotes the submatrix of A formed by columns indexed by J, and $s_d(A[J])$ denotes the d^{th} singular value (in this case, the smallest) of A[J]. Specifically, for any $X, Y \in \mathbb{R}^{n \times d}$,

$$a_0 \mathbf{d}([X], [Y]) \le \|\beta_A(X) - \beta_A(Y)\| \le b_0 \mathbf{d}([X], [Y])$$
 (3.1)

where all norms are Frobenius norms.

Three results (2)

Bi-Lipschitz Property of Universal Keys

Theorem

Assume the key $A \in \mathbb{R}^{d \times D}$ is universal, i.e., the induced map $\hat{\beta}_A : \widehat{\mathbb{R}^{n \times d}} \to \mathbb{R}^{n \times D}$, $[X] \mapsto \beta_A(X) = \downarrow (XA)$ is injective. Then $\hat{\beta}_A$ is bi-Lipschitz, that is, there are constants $a_0 > 0$ and $b_0 > 0$ so that for all $X, Y \in \mathbb{R}^{n \times d}$,

$$a_0 \mathbf{d}([X], [Y]) \le \|\beta_A(X) - \beta_A(Y)\| \le b_0 \mathbf{d}([X], [Y])$$
 (3.2)

where all are Frobenius norms. Furthermore, an estimate for b_0 is provided by the largest singular value of A, $b_0 = s_1(A)$.

Dimension Reduction

Theorem

Assume $A \in \mathbb{R}^{d \times D}$ is a universal key for $\mathbb{R}^{n \times d}$ with $D \ge 2d$. Then, for $m \ge 2nd$, a generic linear operator $B : \mathbb{R}^{n \times D} \to \mathbb{R}^m$ with respect to Zariski topology on $\mathbb{R}^{n \times D \times m}$, the map

$$\hat{\beta}_{A,B}: \widehat{\mathbb{R}^{n \times d}} \to \mathbb{R}^{2nd} , \ \hat{\beta}_{A,B}(\hat{X}) = B\left(\hat{\beta}_A(\hat{X})\right)$$
(3.3)

is bi-Lipschitz. In particular, almost every full-rank linear operator $B : \mathbb{R}^{n \times D} \to \mathbb{R}^{2nd}$ produces such a bi-Lipschitz map.

This result is compatible with a Whitney embedding theorem with the important caveat that the Whitney embedding result applies to smooth manifolds, whereas $\widehat{\mathbb{R}^{n \times d}}$ is not a manifold.

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Highlights of proofs

First result: Universal keys

The upper bound is imediate. For lower bound, fix $X, Y \in \mathbb{R}^{n \times d}$:

$$\|\beta_A(X) - \beta_A(Y)\|_2^2 = \sum_{k=1}^D \|\downarrow (Xa_k) - \downarrow (Ya_k)\|_2^2 = \sum_{k=1}^D \|P_k Xa_k - Q_k Ya_k\|_2^2$$

$$\stackrel{\prod_{k:=Q_{k}^{T}P_{k}}{=} \sum_{k=1}^{D} \|(\prod_{k}X - Y)a_{k}\|_{2}^{2}$$

Highlights of proofs

First result: Universal keys

The upper bound is imediate. For lower bound, fix $X, Y \in \mathbb{R}^{n \times d}$:

$$\|\beta_A(X) - \beta_A(Y)\|_2^2 = \sum_{k=1}^D \|\downarrow (Xa_k) - \downarrow (Ya_k)\|_2^2 = \sum_{k=1}^D \|P_k Xa_k - Q_k Ya_k\|_2^2$$

$$\stackrel{\Pi_k:=Q_k^T P_k}{=} \sum_{k=1}^D \|(\Pi_k X - Y)a_k\|_2^2 \ge \sum_{j=1}^d \|(\Pi_{k_j} X - Y)a_{k_j}\|_2^2$$

so that $\Pi_{k_1} = \cdots = \Pi_{k_d} = \Pi_0$ (pigeonhole principle: needs D > (d-1)n!).

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Highlights of proofs

First result: Universal keys

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$$\stackrel{\Pi_k:=Q_k^T P_k}{=} \sum_{k=1}^D \|(\Pi_k X - Y)a_k\|_2^2 \ge \sum_{j=1}^d \|(\Pi_{k_j} X - Y)a_{k_j}\|_2^2$$

so that $\Pi_{k_1} = \cdots = \Pi_{k_d} = \Pi_0$ (pigeonhole principle: needs D > (d-1)n!). Then:

$$\|\beta_{A}(X) - \beta_{A}(Y)\|_{2}^{2} \ge \sum_{j=1}^{d} \|(\Pi_{0}X - Y)a_{k_{j}}\|_{2}^{2} \stackrel{_{full} \ spark}{\ge} s_{d}(A[J])^{2} \|\Pi_{0}X - Y\|^{2}$$
$$\ge s_{d}(A[J])^{2} \min_{\Pi \in \mathcal{S}_{n}} \|\Pi X - Y\|^{2} = s_{d}(A[J])^{2} \mathbf{d}([X], [Y])^{2}$$

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Second	result:	Bi-Lipschitz Property	

The proof resembles the treatment of phase retrieval problem:

- **1** Homogeneity and compactness reduce the problem to local analysis.
- The encoder is "locally" linearized. The failure of local lower Lipschitz bound implies a certain behavior for a Quadratically Constrained Ratio of Quadratics (QCRQ).
- OCRQ has a minimizer: inf ⇒ min. [Teboulle&al.] This step took most of time and lots of (self)convincing !
- Ontradiction to injectivity assumption.

More detailed proof of the bi-Lipschitz result (1)

1. Reduction to local lower Lipschitz bound. Assume $\inf_{X \not\sim Y} \|\beta_A(X) - \beta_A(Y)\|_2 / \mathbf{d}([X], [Y]) = 0$. By homogeneity and compactness, extract/construct sequences $(X_j)_j$ and $(Y_j)_j$ so that: (i) $X_j \rightarrow Z$; (ii) $Y_j \rightarrow Z$; (iii) $\|Y_j\| \le \|X_j\| = \|Z\| = 1$; (iv) $\mathbf{d}([X_j], [Z]) = \|X_j - Z\|$; (v) $\mathbf{d}([X_j], [Y_j]) = \|X_j - Y_j\|$; (vi) $\mathbf{d}([Y_j], [Z]) = \|Y_j - z\|$.

2. Local linearization. Let $H = \{P \in S_n ; PZ = Z\}$ denote the stabilizer of Z. Let $U_j = X_j - Z$ and $V_j = Y_j - Z$. Then:

$$\lim_{j \to \infty} \frac{\sum_{k=1}^{D} \min_{Q \in H} \|QU_j a_k - V_j a_k\|^2}{\|U_j - V_j\|^2} = 0, \ \|U_j - V_j\| \le \|U_j - PV_j\|, \ \forall P \in H.$$

More detailed proof of the bi-Lipschitz result (2)

3. QCQP Last limit implies:

$$\inf_{\substack{(u,v) \in \mathbb{R}^{n \times d} \\ U \neq QV, \forall V \in H}} \max_{\substack{P \in H}} \frac{\sum_{k=1}^{D} \| (U - \Pi_k V) a_k \|_2^2}{\| U - PV \|^2} = 0$$

where Π_k achieves alignment between $U_j a_k$ and $V_j a_k$.

Since these groups are finite, we obtain that the infimum is achieved! Hence:

4. Injectivity no-go

There are $U, V \in \mathbb{R}^{n \times d}$ so that $Z + U \not\sim Z + V$ and yet $(Z + U)a_k = \prod_k (Z + V)a_k$ for all $k \in [D]$. This shows $\beta_A(Z + U) = \beta_A(Z + V)$ which contradicts injectivity! Q.E.D.

Highlights of proofs

The proof follows the approach in [Cahill&al.], [Dufresne]:

$$0 = B(\beta_A(X)) - B(\beta_A(Y)) \Rightarrow \beta_A(X) - \beta_A(Y) \in \ker(B)$$

Need to show: $\beta_A(X) - \beta_A(Y) = 0$, or, $Ran(\Delta) \cap ker(B) = \{0\}$, where

$$\Delta: \mathbb{R}^{n \times d} \times \mathbb{R}^{n \times d} \to \mathbb{R}^{n \times D} , \ \Delta(X, Y) = \beta_A(X) - \beta_A(Y).$$

In the polynomial case, [Cahill&al.] exploit arguments from algebraic geometry. Here the problem is simpler since $Ran(\Delta)$ is included in a finite union of linear subspaces of dimension at most 2nd.

By a dimension argument it follows that the target space for B must be of dimension at least 2nd to obtain an injective embedding. In this case, generically, $Ran(\Delta)$ and ker(B) intersect transversally.

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Towards universal keys

The arXiv preprint provides necessary and sufficient conditions for a key to be universal.

Open Problem: Given (n, d) find the smallest dimension D so that there exists a universal key $A \in \mathbb{R}^{d \times D}$ for $\mathbb{R}^{n \times d}$.

So far we obtained (joint with Daniel Levy (UMD)):

n	d	D-d
2	2	1
3	2	2
4	2	2
5	2	3
6	2	<u>></u> 4

Open Problem: If a universal key exists for a triple (n, d, D) then is it true that universal keys are generic in $\mathbb{R}^{d \times D}$?



A sequence of preprints came out almost simultaneously:

- R. Balan, N. Haghani, M.Singh, Permutation Invariant Representations with Applications to Graph Deep Learning, arXiv:2203.07546 (2022)
- N. Dym, S. J. Gortler, Low Dimensional Invariant Embeddings for Universal Geometric Learning, arXiv:2205.02956 (2022)
- J. Cahill, J. W. Iverson, D. G. Mixon, D. Packer, Group-invariant max filtering, arXiv:2205.14039 (2022)

all of them based on sorting in one way or another. [Dym and Gortler] shows that the key size should be significantly smaller than n!. [Cahill et.al.'22] introduced the concept of max filter which is a special case of a more general G-invariant representation discussed next.

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- 1. Invariant Coorbit Representations
- 2. Injective Invariant Representations
- 3. Bi-Lipschitz Property

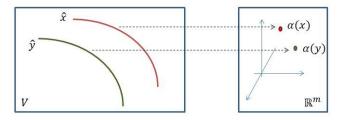
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High-Level View

Recall the framework for Euclidean embeddings of metric spaces induced by orthogonal representations of (finite) groups G acting on a linear space V.

Metric space (\hat{V}, \mathbf{d}) where: $\hat{V} = V/G$ is the set of orbits, $[x] = \{U_g, g \in Gx\}$, for $x \in V$; and $\mathbf{d}(\hat{x}, \hat{y}) = \min_{u \in \hat{x}, v \in \hat{y}} ||u - v||_V$.



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The Program

Given a (discrete) group G acting unitarly on a normed space V, we formulate four general problems

- Construct injective embeddings of the quotient space V/G, *α* : *V* → ℝ^m. The injectivity problem.
- **2** Construct/Obtain bi-Lipschitz properties for the Euclidean embedding $\alpha: \hat{V} \to \mathbb{R}^m$. The stability problem.
- **3** Develop algorithms for inversion $\alpha^{-1} : \mathbb{R}^m \to \hat{V}$. The recovery problem.
- Analyze specific cases. Applications.

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The Program

Given a discrete group G acting unitarly on a normed space V, we formulate four general problems

- Construct injective embeddings of the quotient space V/G, α : V̂ → ℝ^m. The injectivity problem.
- Construct/Obtain bi-Lipschitz properties for the Euclidean embedding $\alpha: \hat{V} \to \mathbb{R}^m$. The stability problem.
- Oevelop algorithms for inversion α⁻¹ : ℝ^m → V̂. The recovery problem.
- Analyze specific cases. Applications.

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The Program

Given a discrete group G acting unitarly on a normed space V, we formulate four general problems

- Construct injective embeddings of the quotient space V/G, α : V̂ → ℝ^m. The injectivity problem.
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- Oevelop algorithms for inversion α⁻¹ : ℝ^m → V̂. The recovery problem.
- Analyze specific cases. Applications.

Today we focus on the first two problems: injectivity and bi-Lipschitz

stability.

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1. Invariant Coorbit Representations

Invariant Representations

Let V be a d-dimensional Hilbert space and G a finite group of size N = |G| acting unitarily on V, $\{U_g, g \in G\}$. The quotient space $\hat{V} = V/G$ is the set of orbits $[x] = \{U_g x, g \in G\}$ induced by the group action, where for $x, y \in V, x \sim y$ iff $y = U_g x$ for some $g \in G$. (\hat{V}, \mathbf{d}) becomes a metric space with the natural distance

$$\mathbf{d}([x],[y]) = \min_{g \in G} \|x - U_g y\|$$

How to construct an invariant representation?

The standard method in the computational invariant theory: Find generators of the ring of invariant polynomials in d variables. This method goes back to Cayley, Hilbert, Noether However this approach has a drawback: it cannot produce bi-Lipschitz embeddings ¹, unless special

cases.

¹J. Cahill, A. Contreras, A.C. Hip, Complete Set of translation Invariant Measurements with Lipschitz Bounds, ACHA 2020

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1. Invariant	1. Invariant Coorbit Representations						
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Sorting based Representations

Different approaches were considered recently ²,³,⁴ based on sorting. A unified framework for these approaches is presented here.

Fix a generator $w \in V$ (call it, window or template) and consider the nonlinear map induced by sorting its coorbit:

$$\phi_{\mathsf{w}}: \mathsf{V} \to \mathbb{R}^{\mathsf{N}} \ , \ \phi_{\mathsf{w}}(\mathsf{x}) = \downarrow ((\langle \mathsf{x}, \mathsf{U}_{\mathsf{g}} \mathsf{w} \rangle)_{\mathsf{g} \in \mathsf{G}}).$$

where $\downarrow (y) = (y_{\pi(i)})_{i \in [N]}$ is the non-increasing sorting operator: $y_{\pi(1)} \ge \cdots \ge y_{\pi(N)}$.

²R. Balan, N. Haghani, M.Singh, Permutation Invariant Representations with Applications to Graph Deep Learning, arXiv:2203.07546 (2022)

³N. Dym, S. J. Gortler, Low Dimensional Invariant Embeddings for Universal Geometric Learning, arXiv:2205.02956 (2022)

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1. Invariant Coorbit Representations

Representations based on sorting (2)

$$\phi_{w}: V \to \mathbb{R}^{N} , \phi_{w}(x) = \downarrow ((\langle x, U_{g}w \rangle)_{g \in G}).$$

Remarks:

- $\phi_w(U_g x) = \phi_w(x)$ for every $g \in G$ and $x \in V$. Thus ϕ_w lifts to the quotient space \widehat{V} .
- Invariant polynomials, and more generally, invariant functions obtained by the averaging operator (the Reynolds operator), can be obtained as:

$$K \mapsto F_K(x) = \frac{1}{|G|} \sum_{g \in G} K(\langle U_g x, w \rangle) = \frac{1}{|G|} \sum_{g \in G} K(\phi_w(x))$$

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1. Invariant Coorbit Representations

Invariant Coorbit Representations

For a collection
$$\mathbf{w} = (w_1, \cdots, w_p) \in V^p$$
 let

$$\Phi_{\mathbf{w}}: V \to \mathbb{R}^{N \times p} \quad , \quad \Phi_{\mathbf{w}}(x) = \left[\phi_{w_1}(x) | \cdots | \phi_{w_p}(x)\right].$$

For a subset $S \subset [N] \times [p]$ of cardinal m = |S|, let

$$\Phi_{\mathbf{w},S}: V o I^2(S) \sim \mathbb{R}^m \ , \ \Phi_{\mathbf{w},S}(x) = (\Phi_{\mathbf{w}}(x))|_S$$

be the restriction of $\Phi_{\mathbf{w}}$ to S. For a linear operator $\mathcal{L}: l^2(S) \to \mathbb{R}^m$, let

$$\Psi_{\mathbf{w},S,\mathcal{L}}: V \to \mathbb{R}^m$$
, $\Psi_{\mathbf{w},\mathcal{L}}(x) = \mathcal{L}(\Phi_{\mathbf{w},S}(x))$

be the "projection" of $\Phi_{\mathbf{w},S}$ through \mathcal{L} into \mathbb{R}^m . **Problems:** Construct (\mathbf{w}, S) so that $\Phi_{\mathbf{w},S}$ is a bi-Lipschitz embedding of \widehat{V} . Construct $(\mathbf{w}, S, \mathcal{L})$ so that $\Psi_{\mathbf{w},S,\mathcal{L}}$ is bi-Lipschitz.

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1. Invariant Coorbit Representations

Invariant Coorbit Representations

Special cases:

1. If $G = S_n$ and $V = \mathbb{R}^{n \times d}$ with action $(P, X) \mapsto PX$, then ⁵ introduced the embedding $\beta_A(X) = \downarrow (XA)$, for key $A \in \mathbb{R}^{d \times D}$ and sorting operator acting independently in each column.

Equivalent recasting: Let $w_1 = \delta_1 \cdot a_1^T, ..., w_D = \delta_1 \cdot a_D^T$, where $\delta_1 = (1, 0, \dots, 0)^T$ and $A = [a_1 | \dots | a_D]$. Then note $\phi_{w_1}(X) = \downarrow (Xa_1) \otimes 1_{(n-1)!}$. Thus $\Phi_{\mathbf{w}}(X) = \beta_A(X) \otimes 1_{(n-1)!}$. Thus $\beta_A(X) = \Phi_{\mathbf{w},S}(X)$ for an appropriate subset $S \subset [n!] \times [D]$ of size nD. 2. The max filter introduced in ⁶ for some template $w \in V$ is defined by $\langle \langle \cdot, w \rangle \rangle : V \to \mathbb{R}, \langle \langle x, w \rangle \rangle = \max_{g \in G} \langle x, U_g w \rangle$. Equivalent recasting: $\langle \langle x, w \rangle \rangle = \Phi_{w,S}(X)$, for $S = \{1\}$.

⁵R. Balan, N. Haghani, M.Singh, Permutation Invariant Representations with Applications to Graph Deep Learning, arXiv:2203.07546 (2022)

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⁶J. Cahill, J. W. Iverson, D. G. Mixon, D. Packer, Group-invariant max filtering, arXiv:2205.14039 (2022)

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2. Injective Invariant Representations

Sufficient conditions for an injective embedding

Theorem

Consider G finite group of size N acting unitarily on the d-dimensional V. Let $\mathbf{w} \in V^p$, $S \subset [N] \times [p]$, S_k the k^{th} slice, and linear map $\mathcal{L} : l^2(S) \to \mathbb{R}^m$. Denote $\gamma_2 = \min_{g \in G, g \neq 1} \min_{\lambda \in \mathbb{R}} \operatorname{rank}(\lambda I_d - U_g), \gamma_3 = \max_{g \in G, g \neq 1} \min_{\lambda \in \mathbb{R}} \operatorname{rank}(\lambda I_d - U_g)$. Then for almost every \mathbf{w} and \mathcal{L} the maps $\Phi_{\mathbf{w},S}$ or $\Psi_{\mathbf{w},S,\mathcal{L}}$ are injective on \widehat{V} in any of the following cases:

- (Max filter, Cahill et.al. 2022) If $p \ge 2d$ and $S_{max} = \{(1,1), \dots, (1,p)\}$ then the max filterbank $\Phi_{\mathbf{w},S_{max}}$ is injective for a.e. $\mathbf{w} \in V^p$.
- (variation of previous result) If p ≥ 2d and |S_k| ≥ 1 for all k ∈ [p] then Φ_{w,S} is injective for a.e. w ∈ V^p.
- If G is a reflection group and p ≥ d then the max filterbank Φ_{w,Smax} is injective for a.e. w ∈ V^p.

 $^{\rm a}\text{D}.$ Mixon, Y. Qaddura, Injectivity, stability, and positive definiteness of max filtering, arXiv:2212.11156

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2. Injective Invariant Representations

Sufficient conditions for injective embedding (cont)

Theorem

- If p ≥ 2d − γ₂, |S| ≥ 2d, and for each k, |S_k| ∈ {1,2} then Φ_{w,S} is injective for a.e. w ∈ V^p.
- If $2d \gamma_3 \leq p \leq 2d$, $|S_1| = \cdots = |S_{2d-p}| = N$, and $|S_{2d-p+1}| = \cdots = |S_p| = 1$ then $\Phi_{\mathbf{w},S}$ is injective for a.e. $\mathbf{w} \in V^p$.
- If Φ_{w,S} is injective and m ≥ 2d then the map Ψ_{w,S,L} is injective for a.e. linear map L : l²(S) → ℝ^m.

Remark:

This result can be extended to the case when S has an irregular structure. However this requires some involved spectral conditions.

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2. Injective Invariant Representations

Injectivity – sketch of proof

The proof provides a semi-algebraic characterization of the set of "bad" windows, i.e., windows w that fail to separate, say \mathcal{F} .

$$\mathcal{F} \subset \bigcup_{\mathbf{g},\mathbf{h} \in \mathcal{G}^{p*}} \mathcal{F}_{\mathbf{g},\mathbf{h}} \ , \ \ \mathcal{G}^{p*} = \{(g_i^k)_{(i,k) \in S} \ , \ \forall k, (g_i^k)_{i \in S_k} \in \mathcal{G}^{|S_k|} \text{are distinct} \}$$

$$\mathcal{F}_{\mathbf{g},\mathbf{h}} = \bigcup_{(x,y)\in\Gamma} \otimes_{k=1}^{p} \{U_{g_{1}^{k}}x - U_{h_{1}^{k}}y, ..., U_{g_{m_{k}}^{k}}x - U_{h_{m_{k}}^{k}}y\}^{\perp}$$

where $\Gamma = \{(x, y) \in V^2 : x \not\sim y, ||x||^2 + ||y||^2 = 1\}, m_k = |S_k|$. Using the "lift-and-project" technique, we realize each $\mathcal{F}_{g,h}$ as finite unions of projection onto second term of total manifolds of certain real-analytic vector bundles. The vector bundles have as base manifolds subsets of Γ where dimension of the orthogonal complement of constant. In turn those subsets are controled by spectral properties of U_g 's.

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Injectivity - sketch of proof

The base manifolds of these vector bundles are themselves total spaces of a different vector bundles living over Grassmanian manifolds. For instance, for $|S_k| = m_k = 2$, First construct the bundle $(Gr(1, \mathbb{R}^2), \pi, E)$ over $Gr(1, \mathbb{R}^2) = \mathbb{RP}^1 \sim [0, \pi)$ with total space

$$E = \{(\theta, x, y) \in [0, \pi) \times V^2 ; \ cos(\theta)(U_{g_1}x - U_{h_1}y) + sin(\theta)(U_{g_2}x - U_{h_2}y) = 0\}$$

Most of fibers are *d*-dimensional except what $tan(\theta)$ is an eigenvalue of some unitary U_g . Those two cases induce a disjoint partition $\Gamma = (\Gamma \setminus \Pi_2(E)) \cup (\Gamma \cap \Pi_2(E))$ so that

$$(x,y) \in \Gamma_1 := \Gamma \setminus \Pi_2(E) \quad \to \quad \dim\{U_{g_1}x - U_{h_1}y\}, (U_{g_2}x - U_{h_2}y\}^{\perp} = d-2 \\ (x,y) \in \Gamma_2 := \Gamma \cap \Pi_2(E) \quad \to \quad \dim\{U_{g_1}x - U_{h_1}y\}, (U_{g_2}x - U_{h_2}y\}^{\perp} = d-1$$

from where the dimension estimates arise.

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3. Bi-Lipschitz Property					

Main Result

Theorem

Consider G finite group of size N acting unitarily on the d-dimensional V. Let $\mathbf{w} \in V^p$, $S \subset [N] \times [p]$ and $\mathcal{L} : l^2(S) \to \mathbb{R}^m$. Let

$$\begin{array}{c} {}^{B=\max} \\ \sigma_1, \cdots, \sigma_p \subset \mathcal{G}, \\ |\sigma_k| = |\mathcal{S}_k|, \forall k \end{array} \xrightarrow{\lambda_{max} \left(\sum_{k=1}^p \sum_{g \in \sigma_k} U_g w_k w_k^T U_g^T \right)} \end{array}$$

where
$$S_k = \{i \in [N], (i, k) \in S\}$$
 for each $k \in [p]$.
• $\Phi_{w,S} : (\widehat{V}, \mathbf{d}) \to l^2(S)$ is Lipschitz with constant upper bounded by \sqrt{B} .

- If S = [N] × [p] and Φ_{w,S} : (V, d) → (ℝ^m, || · ||₂) is injective then it is also bi-Lipschitz;
- If S = [N] × [p] and Φ_{w,S} : (V̂, d) → (ℝ^m, || · ||₂) is injective then for a generic L with m ≥ 2d, the map Ψ_{w,S,L} : (V̂, d) → (ℝ^m, || · ||₂) is injective and bi-Lipschitz.

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Sketch of Proof

1. The upper Lipschitz bound is not too hard. A quick way to obtain it is by the Fundamental Theorem of Calculus: Fix $x, y \in V$ and choose them so that $\mathbf{d}([x], [y]) = ||x - y||$. The function $f : [0, 1] \rightarrow l^2(S)$, $f(t) = \Phi_{\mathbf{w},S}((1 - t)x + ty)$ is Lipschitz because the sorting operator \downarrow is Lipschitz. The upper Lipschitz constant is computable from FTC and Lebesgue's differentiation theorem:

$$\|f(1)-f(0)\|_2 = \|\int_0^1 (Jf)|_{(1-t)x+ty}(y-x)dt\| \le \sup_z \|J\Phi_{\mathbf{w},S}(z)\|_\infty \mathbf{d}([x],[y])$$

But wherever Φ is differentiable, $J\Phi_{\mathbf{w},S}(z) = \left[(U_{g(\pi_k(i)}w_k)^T \right]_{(i,k)\in S}$ where π_k is the permutation that sorts $\phi_{w_k}(z)$. From here one obtains the upper bound.

The same goes for $\Psi_{\mathbf{w},S,\mathcal{L}}$.

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Sketch of Proof (2)

2. The lower Lipschitz bound is more challanging. The proof follows the recipe from (Balan et.al. 2022) and is by contradiction. Assume the lower bound is A = 0.

Step 1. A compactness argument together with the homogeneity of map Φ implies the local lower Lipschitz constant must vanish: there is $z \in S_1(V)$:

$$\lim_{r \downarrow 0} \inf_{\substack{x \not\sim y \\ \mathbf{d}([x], [z]) < r, \mathbf{d}([y], [z]) < r}} \frac{\|\Phi_{\mathbf{w}, S}(x) - \Phi_{\mathbf{w}, S}(y)\|_2}{\mathbf{d}([x], [y])} = 0$$

Step 2. Construct sequences $(x_n)_n$ and $(y_n)_n$ so that: (i) $||x_n|| = 1$, (ii) $||y_n|| \le 1$; (iii) $\mathbf{d}([x_n], [y_n]) = ||x_n - y_n||$; (iv) $\mathbf{d}([x_n], [z]) = ||x_n - z||$; and $x_n \to z$, $[y_n] \to [z]$, and $y_n \to y_\infty$. Step 3. Let $H = \{g \in G : U_g z = z\}$ denote the stabilizer of z. Let $\Delta_0 = \min_{g \in G \setminus H} ||z - U_g z|| > 0$. Assume n large enough so that $u_n = x_n - z$, $v_n = y_n - z$ satisfy $||u_n||, ||v_n|| < \frac{1}{4}\Delta_{0:n}$. This forces $y_\infty = z_{n-2} > \infty$

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Step 4. By finiteness of *G*, we extract subsequences so that $(\Phi_{\mathbf{w},S}(x_n))_{i,k} = \langle x_n, U_{g(1,i,k)}w_k \rangle$ and $(\Phi_{\mathbf{w},S}(y_n))_{i,k} = \langle y_n, U_{g(2,i,k)}w_k \rangle$ (note the group elements are independent on n !). It follows:

$$\lim_{n \to \infty} \frac{1}{\|u_n - v_n\|^2} \sum_{(i,k) \in S} |\langle w_k, U_{g(1,i,k)}^T u_n - U_{g(2,i,k)}^T v_n \rangle|^2 = 0$$

Step 5. Using an argument about ratios of quadratics, it follows that one is able to produce u, v so that $u \not\sim v$ and $\langle w_k, U_{g(1,i,k)}^T u - U_{g(2,i,k)}^T v \rangle = 0$ for all $(i, k) \in S$. Then for s > 0 small enough, x = z + su and y = z + sv we have $\mathbf{d}([x], [y]) > 0$ and yet $\Phi_{\mathbf{w}, S}(x) = \Phi_{\mathbf{w}, S}(y)$. Contradiction!

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Thank you!

Questions?

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