



Center for Scientific Computation And Mathematical Modeling

University of Maryland, College Park



PDEs in Image Processing

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Image processing: two-scale decompositions

- Observed images: $\Omega \subset \mathbb{R}^2$

(grayscale) $f : \Omega \mapsto \mathbb{R}_+$, (colored) $\mathbf{f} = (f_1, f_2, f_3) : \Omega \mapsto \mathbb{R}_+^3$

measuring “pixel intensity units”: 0 (dark) \mapsto 255 (bright)

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- Inverse problems (ill-posed) – from an observed $f \mapsto U$:



Two-scale representation — variational decompositions of noisy images

- $f = u_\lambda + v_\lambda$: $[u_\lambda, v_\lambda] := \arg \inf_{u+v=f} \left\{ \|u\|_X + \lambda \|v\|_Y^2 \right\}$
 - u_λ extracts large scale features: edges, ... $\mapsto U$ (observed)
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 - ⊙ Garnett, T. Le & Vese: $\arg \inf_{u+v=f} \left\{ \|u\|_{BV} + \lambda \|v\|_{L^p}^q \right\}$

Two-scale representations — PDE-based decompositions

- ROF model: $\operatorname{arginf}_u \left\{ \|u\|_{BV} + \lambda \|f - u\|_{L^2}^2 \right\},$

$$v_\lambda := f - u_\lambda$$

- Minimizer u depends on BV^* -size of f : $\|f\|_* = \sup_{\varphi \neq 0} \frac{(f, \varphi)}{\|\varphi\|_{BV}}:$

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- Euler-Lagrange:
$$\begin{cases} u_\lambda - \frac{1}{2\lambda} \operatorname{div}_x \left(\frac{\nabla u_\lambda}{|\nabla u_\lambda|} \right) = f, & \lambda \geq 1/(2\|f\|_*) \\ u_\lambda \equiv 0, & \lambda < 1/(2\|f\|_*) \end{cases}$$

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- Steepest-descent: $\{U(\cdot, 0) = 0\} \mapsto u_\lambda := \lim_{t \uparrow \infty} U(\cdot, t):$

$$\frac{\partial U}{\partial t} = f - U + \frac{1}{2\lambda} \operatorname{div}_x \left(\frac{\nabla U}{|\nabla U|} \right), \quad \frac{\partial U}{\partial \mathbf{n}}|_{\partial\Omega} = 0$$

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- Perona-Malik: Nordström, Catté, P.L. Lions, J. M. Morel, ...

$$\frac{\partial U}{\partial t} = f - U + \operatorname{div}_x \left(g(|G_\lambda * \nabla U|) \nabla U \right), \quad g(s) := \frac{1}{2\lambda s}$$

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- Wavelet shrinkage (DeVore-Lucier): $f = \overbrace{\sum_{|\hat{f}_{jk}| \geq 1/\lambda} \hat{f}_{jk} \psi_{jk}}^{u_\lambda} + v_\lambda$

Multiscale representation — (T.-Nezzar-Vese)

- $f = u_\lambda + v_\lambda : \quad u_\lambda := \arg \inf_{u+v=f} \left\{ \|u\|_{BV} + 2\lambda \|f - v\|_{L^2}^2 \right\}$
- $\begin{cases} u_\lambda : \text{essential features} \\ v_\lambda : \text{noise, texture, ...} \end{cases}$

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- **Distinction is scale dependent** – ‘texture’ at a λ -scale consists of significant features when viewed under a refined 2λ -scale

$$v_\lambda = u_{2\lambda} + v_{2\lambda}, \quad u_{2\lambda} := \arg \inf_{u+v=v_\lambda} \left\{ \|u\|_{BV} + 2\lambda \|v_\lambda - v\|_{L^2}^2 \right\}$$

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- A better 2-scale representation: $f = u_\lambda + v_\lambda \approx u_\lambda + u_{2\lambda} + v_{2\lambda}$

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- This process can be continued...

$$v_{2\lambda} = u_{4\lambda} + v_{4\lambda}, \quad u_{4\lambda} := \arg \inf_{u+v=v_{2\lambda}} \left\{ \|u\|_{BV} + 4\lambda \|v_{2\lambda} - v\|_{L^2}^2 \right\},$$

⋮

$$v_{2^j\lambda} = u_{2^{j+1}\lambda} + v_{2^{j+1}\lambda}, \quad \text{scale} = 2^{j+1}\lambda, \dots$$

Hierarchical decompositions — (T.-Nezzar-Vese)

- $u_{2^j \lambda} \mapsto u_j$:

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- After N hierarchical steps:

$$\begin{aligned} f &= u_0 + v_0 = \\ &= u_0 + u_1 + v_1 = \\ &= \dots\dots\dots = \\ &= u_0 + u_1 + \dots + u_N + v_N \end{aligned}$$

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- Set $\lambda_j = 2^j \lambda_0$, $\lambda_0 \geq \frac{1}{2\|f\|_*}$: $v_j = -\frac{1}{2\lambda_j} \operatorname{div} \left(\frac{\nabla u_j}{|\nabla u_j|} \right)$:

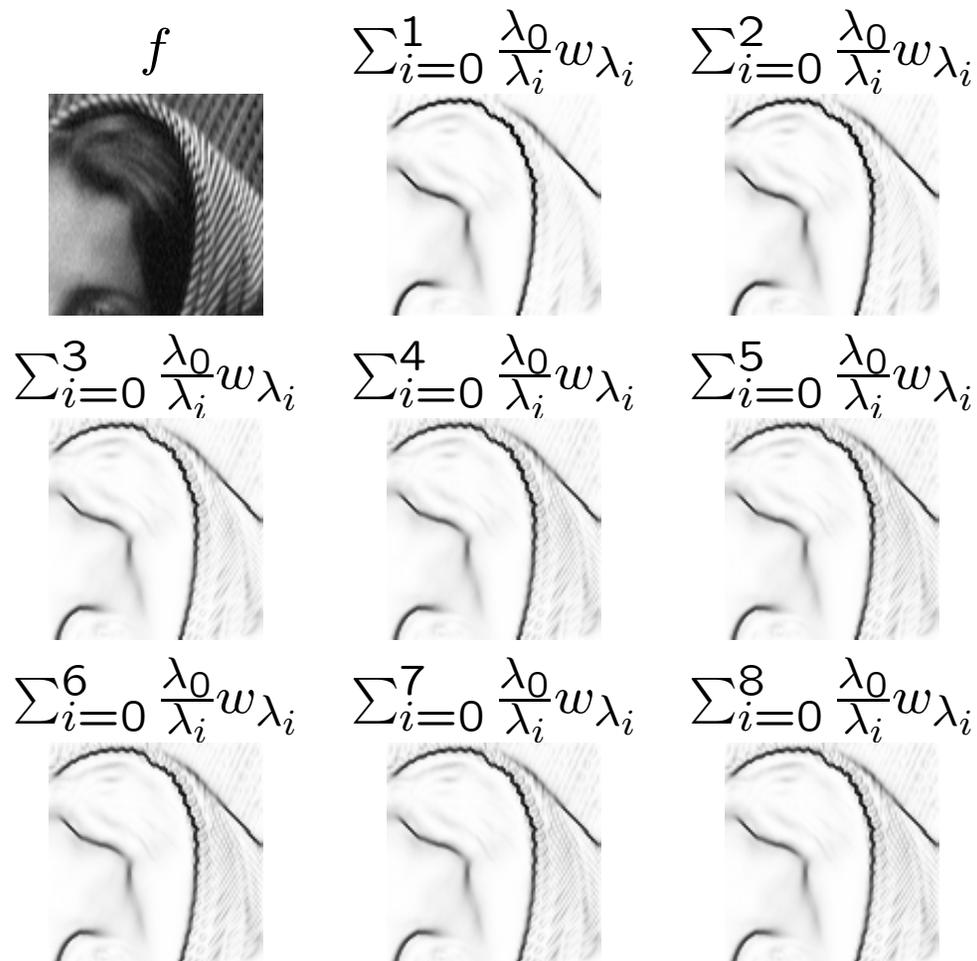
$$u_{j+1} - \frac{1}{2\lambda_{j+1}} \operatorname{div}_x \left(\frac{\nabla u_{j+1}}{|\nabla u_{j+1}|} \right) = -\frac{1}{2\lambda_j} \operatorname{div}_x \left(\frac{\nabla u_j}{|\nabla u_j|} \right)$$

Multiscale representation of Barbara



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Multiscale representation using MS edge detectors



Mumford-Shah: Ambrosio-Tortorelli $[SBV, L^2](f, \lambda) := \inf_{\{u,v,w \mid u+v=f\}} \{\dots\}$

$$w_j(x, y) \approx \begin{cases} 0, & \text{in regions of smoothness} \\ 1, & \text{near edges} \end{cases}$$

Multiscale representation of colored images

f



$$\sum_{i=0}^2 u_{\lambda_i}$$



$$\sum_{i=0}^3 u_{\lambda_i}$$



$$\sum_{i=0}^4 u_{\lambda_i}$$



$$\sum_{i=0}^5 u_{\lambda_i}$$



$$\sum_{i=0}^6 u_{\lambda_i}$$



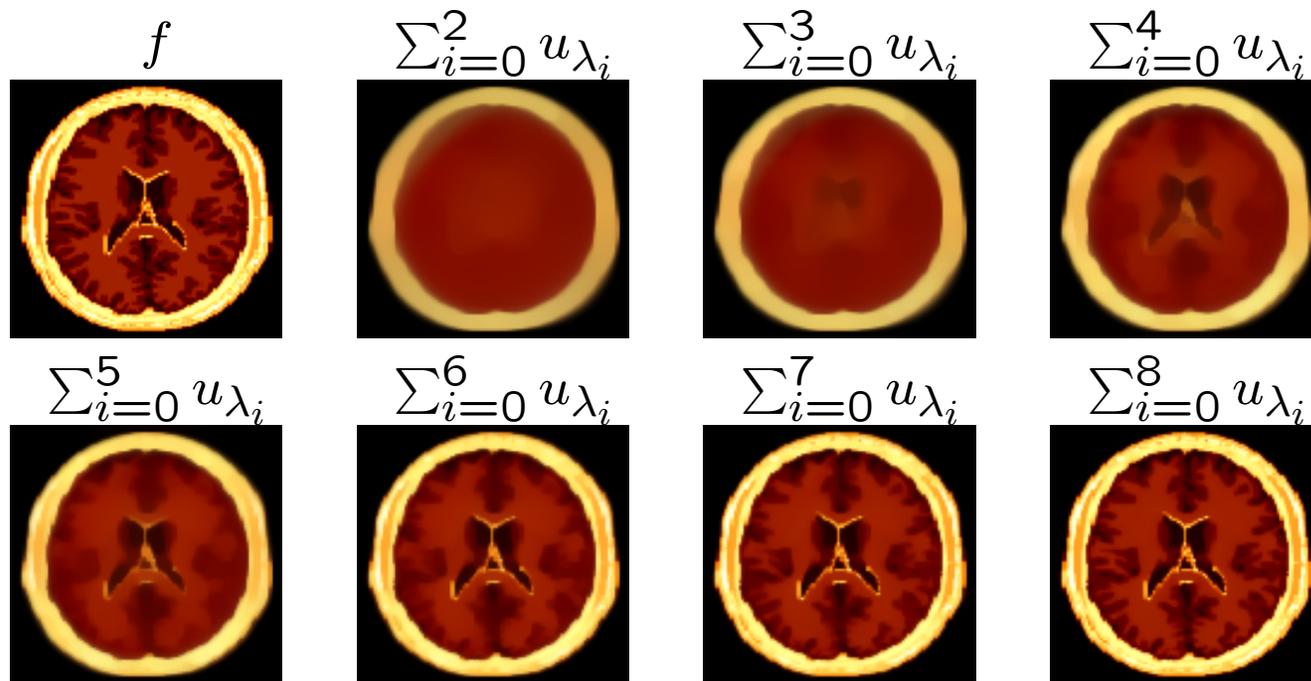
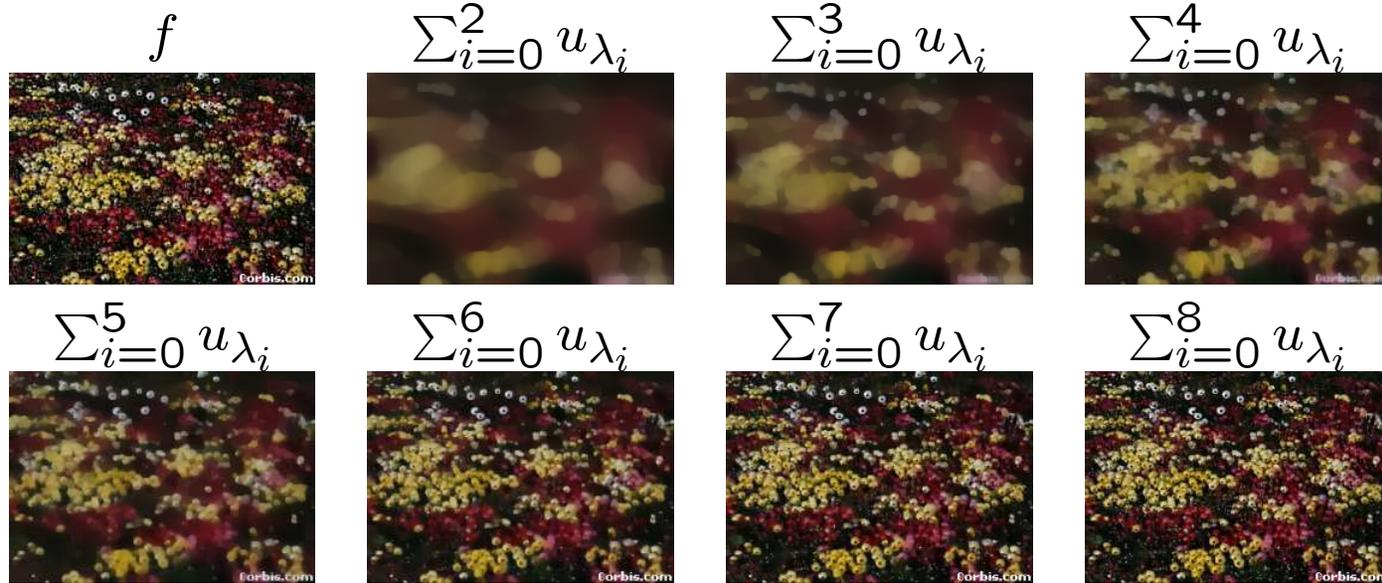
$$\sum_{i=0}^7 u_{\lambda_i}$$



$$\sum_{i=0}^8 u_{\lambda_i}$$



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- Integro-Differential Equation (IDE):

$$\int_{s=0}^t u(s) ds - f = \frac{1}{\lambda(t)} \operatorname{div}_x \left(\frac{\nabla_x u(t)}{|\nabla_x u(t)|} \right), \quad \frac{\partial u}{\partial \mathbf{n}} \Big|_{\partial \Omega} = 0$$

Numerical results of IDE

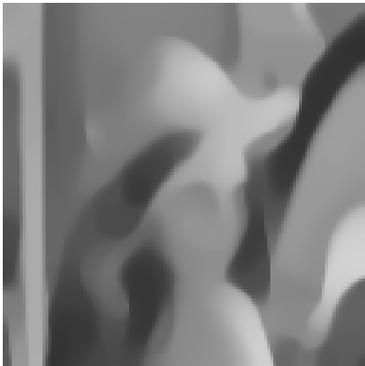
- IDE:
$$\int_{s=t_0}^t u(s)ds - f = \frac{1}{\lambda(t)} \operatorname{div}_x \left(\frac{\nabla_x u(t)}{|\nabla_x u(t)|} \right)$$
 - inverse scale : $u(t_0) \mapsto U(t) := \int_{s=t_0}^t u(s)ds$ (observed)
- Perona-Malik:
$$u_t = \frac{1}{\lambda(t)} \operatorname{div}_x \left(\frac{\nabla_x u(t)}{|\nabla_x u(t)|} \right)$$
 - forward scale : $u(0) = f \mapsto u(\infty) \equiv 0$ (diffused)

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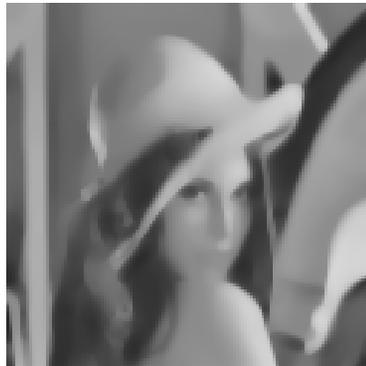
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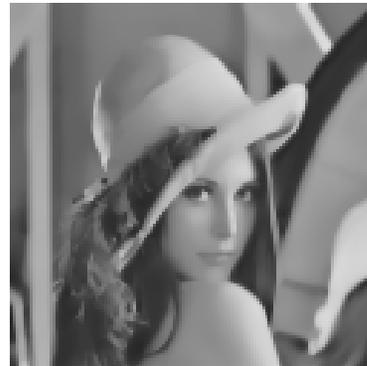
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$t = 1$



$t = 4$



$t = 6$



$t = 10$

The IDE images, $U(t) := \int_0^t u(\cdot, s) ds$ at $t = 1, 4, 6, 10$;

Scaling function: $\lambda(t) := 0.002 \times 2^t$

Parameters: where to start? how to scale?

#1. Where to start $\int_{s=t_0}^t u(s)ds - f = \frac{1}{\lambda(t)} \operatorname{div}_x \left(\frac{\nabla_x u(t)}{|\nabla_x u(t)|} \right)$?

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$$\text{At } t = 0 : u(0)\tau = f + \frac{1}{2\lambda(0)} \operatorname{div}_x \left(\frac{\nabla_x u(0)}{|\nabla_x u(0)|} \right) : \lambda(0) < \frac{1}{2\|f\|_*} \mapsto u(0) \equiv 0$$

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- $\frac{1}{\lambda(t)}$ dictates the size of texture: $\|U(\cdot, t) - f\|_{BV^*} = \frac{1}{2\lambda(t)}$

Extended IDE model for image restoration

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- Filtered diffusion — restricted diffusion near edges:

$$\int_0^t u(x, s) ds = f(x) + \frac{g(|G_\sigma \star \nabla u(x, t)|)}{2\lambda(t)} \operatorname{div}_x \left(\frac{\nabla u(x, t)}{|\nabla u(x, t)|} \right); \quad \frac{\partial u}{\partial \mathbf{n}} \Big|_{\partial \Omega} = 0,$$

subject to $u_0(x) \equiv u(\cdot, 0)$ such that

$$u_0 = f + \frac{1}{2\lambda_0} g(|G_\sigma \star \nabla u_0|) \operatorname{div}_x \left(\frac{\nabla u_0}{|\nabla u_0|} \right), \quad \lambda_0 > \frac{g(|G_\sigma \star \nabla u_0|)}{2\|f\|_*}.$$

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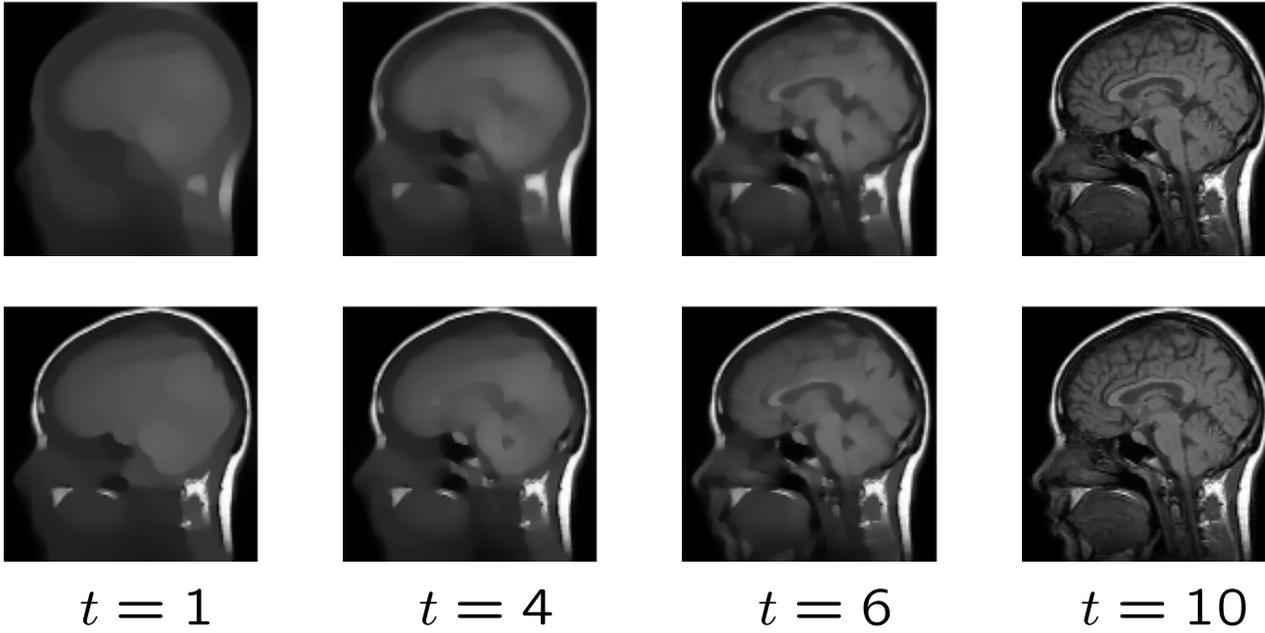
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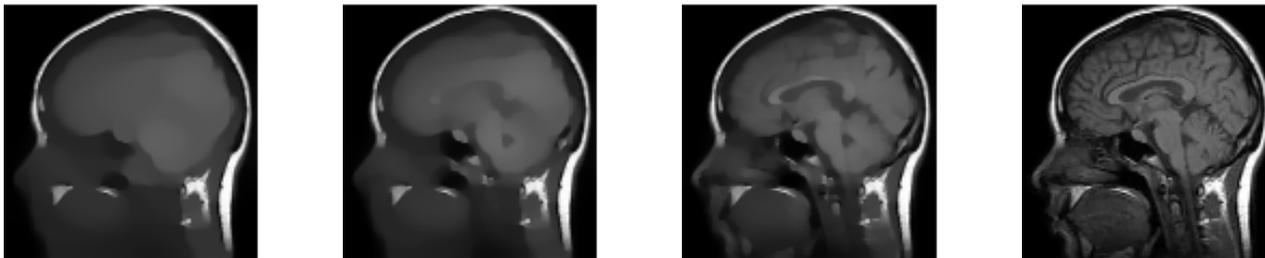
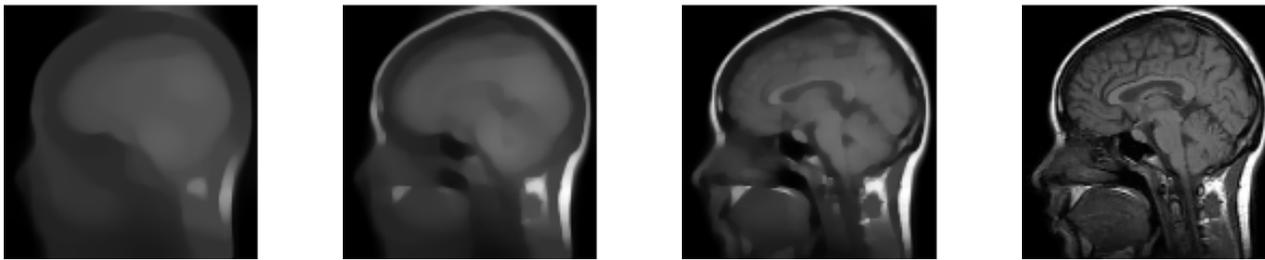
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- Tangential smoothing — $u_{\mathbf{t}\mathbf{t}} = \Delta u - u_{\mathbf{n}\mathbf{n}} = |\nabla u| \operatorname{div}_x \left(\frac{\nabla u}{|\nabla u|} \right)$:

$$\int_{s=0}^t u(x, s) ds - f(x) = \frac{1}{\lambda(t)} |\nabla u(x, t)| \cdot \operatorname{div}_x \left(\frac{\nabla u(x, t)}{|\nabla u(x, t)|} \right)$$



MRI images, $U(t) = \int_0^t u(\cdot, s) ds$ at $t = 1, 4, 6, 10$. Top: unfiltered. Bottom: filtered



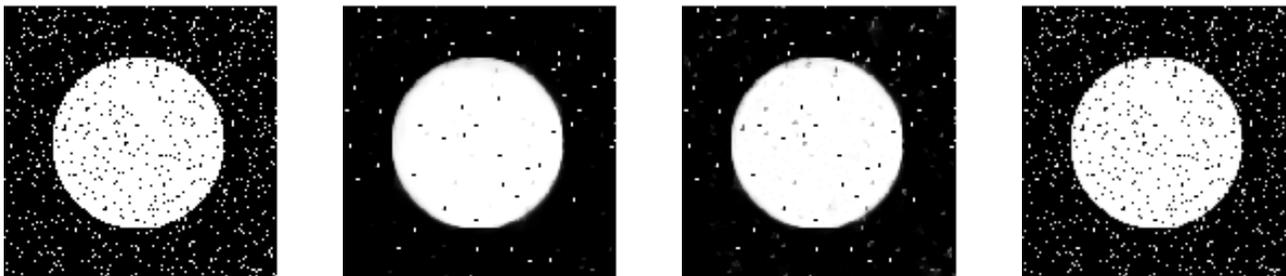
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f at $t = 0$

$t = 1$

$t = 4$

$t = 7$

Restoring a noisy image. Top: vanilla IDE. Bottom: IDE with tangential smoothing

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Deblurring Lena using IDE with $G_\sigma, \sigma = 1$



Center for Scientific Computation And Mathematical Modeling

University of Maryland, College Park



THANK YOU