







# Conservation laws and kinetic formulations rough fluxes and stochastic averaging lemma

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#### Introduction

We want to find u(x,t) solution of

$$\begin{cases} du + \sum_{i=1}^{N} \frac{\partial}{\partial x_i} A_i(u) \circ dW^i(t) = 0 & x \in \mathbb{R}^N, \ t \ge 0 \\ u(t = 0) = u^0(x) & \\ \mathbf{A} = (A_1, ..., A_N) \in C^2(\mathbb{R}; \mathbb{R}^N), \end{cases}$$
 (Flux)

$$\mathbf{W} = (W^1, ..., W^N) \in C([0, \infty); \mathbb{R}^N),$$

two special cases being

$$\mathbf{W} = (B^1, ..., B^N)$$
 (N-dimensional Brownian motion)  $\mathbf{W}(\mathbf{t}) = (t, ..., t)$  (Standard SCL, Kruzkov)

#### Introduction

Theorem (Pathwise entropy solutions) There is a unique 'kinetic pathwise solution'

• for a given W

$$||u_2(\cdot,t)-u_1(\cdot,t)||_{L^1(\mathbb{R}^N)} \le ||u_2^0-u_1^0||_{L^1(\mathbb{R}^N)}.$$

ullet for two paths  $\mathbf{W_i}$  and  $u_i^0 \in BV(\mathbb{R}^N)$ , then  $u_1$  and  $u_2$  satisfy

$$||u_{2}(\cdot,t)-u_{1}(\cdot,t)||_{L^{1}(\mathbb{R}^{N})} \leq ||u_{2}^{0}-u_{1}^{0}||_{L^{1}(\mathbb{R}^{N})}$$
$$+C|(\mathbf{W}_{1}-\mathbf{W}_{2})(t)|+C\sup_{s\in(0,t)}\left|(\mathbf{W}_{1}-\mathbf{W}_{2})(s)\right|$$

#### **Motivation**

One motivation:

For i = 1, ..., L, the system of stochastic interacting agents

$$dX_t^i = \sigma(X_t^i, \frac{1}{L-1} \sum_{j \neq i} \delta_{X_t^j}) \circ d\mathbf{W}_t,$$

Uncertainty in drivers behaviour Randomness in an oil well extension Variability in nephrons arrangements

Our problem is the formal limit  $L \to \infty$ 

#### **Related works**

#### Related works:

Flandoli Stochastic perturbations

$$du + \operatorname{div}(bu) + dB(t) \circ \nabla u = 0$$
 (Stratonovich)  $\iff$   $du + \operatorname{div}(bu) + dB(t) \cdot \nabla u = \Delta u$  (Itō)

Extensions to perturbations of Vlasov/Navier-Stokes style equations

• Feng & Nualart, Debussche, Vovelle, Hofmanova

$$du + \operatorname{div} A(u) = F(u).dB(t)$$

#### **Related works**

Lions & Souganidis: Topological point of view

$$du = F(D^2u; Du)dt + \sum_{i=1}^m H_i(Du) \circ dW_i$$

$$du = F(D^2u; Du)dt + \sum_{i=1}^{m} \Phi_i(u) \circ dW_i$$

## Principles:

- Pathwise
- Use characteristics for short times (iterate-Trotter)
- Lyons, Fritz...
  - Rough paths..  $\frac{d}{dt}X(t) = \sigma(X(t))\dot{W}(t)$

## **Outlines**

- 1. Hyperbolic equations and shocks
- 2. Difficulties related to dW(t)
- 3. How do we define a solution?
- 4. Can one prove existence, uniqueness?
- 5. The x-dependant case
- 6. Stochastic averaging lemmas

$$\begin{cases} \frac{\partial}{\partial t}\overline{u} + \sum_{i=1}^{N} \frac{\partial}{\partial x_i} A_i(\overline{u}) = 0 & x \in \mathbb{R}^N, \ t \ge 0 \\ \overline{u}(t, t = 0) = u^0(x) \end{cases}$$

- Generates shocks (discontinuities): low regularity
- Entropy inequality selects a type of solution (unique)

$$\frac{\partial}{\partial t}S(\overline{u}) + \sum_{i=1}^{N} \frac{\partial}{\partial x_i} \eta_i(\overline{u}) \le 0$$

for all  $S: \mathbb{R} \to \mathbb{R}$  convex. Example (Kruzkov)

$$S(u) = |u - k|, \qquad k \in \mathbb{R},$$

Non reversible in time!

$$\begin{cases} \frac{\partial}{\partial t}\overline{u} + \sum_{i=1}^{N} \frac{\partial}{\partial x_i} A_i(\overline{u}) = 0 & x \in \mathbb{R}^N, \ t \ge 0 \\ \overline{u}(x, t = 0) = u^0(x) \end{cases}$$

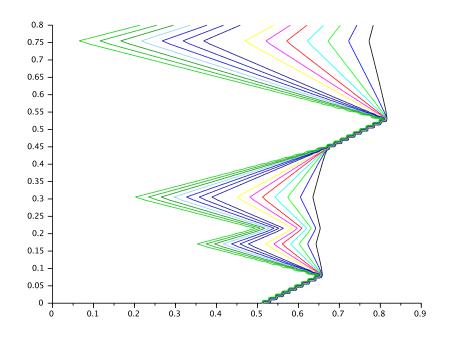
- For  $A(\cdot)$  convex (1 dimension)
  - Decreasing discontinuities are propagated as shocks
  - Increasing discontinuities are regularized
- ullet We want to alternate  $A(\cdot)$  convex and  $A(\cdot)$  concave

$$\begin{cases} du + \sum_{i=1}^{N} \frac{\partial}{\partial x_i} A_i(u) \circ dW^i(t) = 0 & x \in \mathbb{R}^N, \ t \ge 0 \\ u(t = 0) = u^0(t) \end{cases}$$

$$\frac{\partial}{\partial t}S(u) + \sum_{i=1}^{N} \frac{\partial}{\partial x_i} \eta_i(u) \circ dW^i(t) \le 0, \qquad \forall S(\cdot) \quad \text{convex.}$$

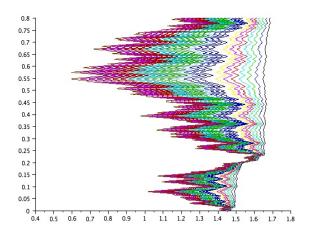
- Motivates the notation 'o' as in Stratonowich form
- Irreversible in time. We cannot write in 1 dimension,

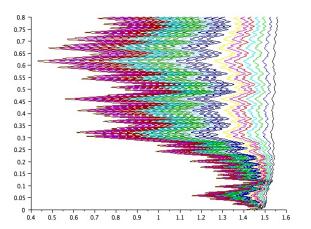
$$u(x,t) = \overline{u}(x,W(t))$$
$$d\overline{u}(x,W(t)) = -\frac{\partial}{\partial x} A(\overline{u}(x,W(t))) \circ dW^{i}(t)$$

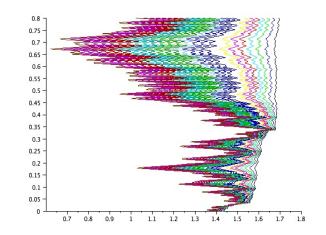


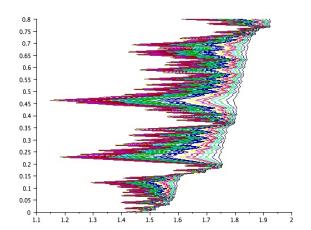
• Usual method : BV estimates (might be correct in x, not in t)

- Compensated compactness (Murat-Tartar)
- Kinetic formulation (Lions, BP, Tadmor)









#### What do we want?

$$\begin{cases} du + \sum_{i=1}^{N} \frac{\partial}{\partial x_i} A_i(u) \circ dW^i(t) = 0 & \text{in} \quad \mathbb{R}^N \times (0, \infty), \\ u = u^0 & \text{on} \quad \mathbb{R}^N \times \{0\}. \end{cases}$$

$$\mathbf{W} = (W^1, ..., W^N) \in C([0, \infty); \mathbb{R}^N), \qquad \mathbf{A} = (A_1, ..., A_N) \in C^2(\mathbb{R}; \mathbb{R}^N),$$
$$\mathbf{a}(\mathbf{u}) = A' = (A'_1(u), ..., A'_N(u)), \qquad \text{(Velocity)}$$

• Entropy dissipation : For S convex

$$\begin{cases} dS(u) + \sum_{i=1}^{N} \frac{\partial}{\partial x_i} \eta_i(u) \circ dW^i \leq 0, \\ \eta_i(u)' = a_i(u)S'(u) \qquad a_i = A'_i \end{cases}$$

(Stratonovich, no additional entropy dissipation)

#### What do we want?

• If we use Itō formula we loose the entropy! We take expectations

$$\frac{d}{dt}\mathbb{E}(u^2) = \mathbb{E}\left(ua(u)^2(u_x)^2\right)$$

No possible control of the RHS (shocks)

ullet For W continuous and  $u(t) \in BV_x$ , we cannot obtain BV in time

$$\frac{du}{dt} = \dot{W}(t) \frac{\partial}{\partial x} u(x, t)$$

No control.

What does it mean to be a solution?

#### How do we define a solution?

As in Debussche & Vovelle, we use the kinetic formulation

$$\chi(x,\xi,t) = \chi(u(x,t),\xi) = \begin{cases} +1 & \text{if} \quad 0 \le \xi \le u(x,t), \\ -1 & \text{if} \quad u(x,t) \le \xi \le 0, \\ 0 & \text{otherwise.} \end{cases}$$

$$S(u(x,t)) = \int_{\mathbb{R}} S'(\xi)\chi(x,\xi,t)d\xi$$

$$\begin{cases} d\chi + \sum_{i=1}^{N} a_i(\xi) \frac{\partial}{\partial x_i} \chi \circ dW^i = \frac{\partial}{\partial \xi} m dt & \text{in} \quad (x, \xi, t) \in \mathbb{R}^N \times \mathbb{R} \times (0, \infty), \\ m(x, \xi, t) \le 0 \end{cases}$$

Equivalent to the **Entropy dissipation** 

#### How do we define a solution?

We can define solutions along the characteristics

$$\dot{X}(t) = a(\xi)\dot{\mathbf{W}}, \qquad \dot{\xi} = 0,$$

$$\frac{d}{dt}\chi(x - a(\xi)\mathbf{W}(t), \xi, t) = \frac{\partial}{\partial \xi}m(x - a(\xi)\mathbf{W}(t), \xi, t)$$

These are globally defined (at variance with the case of H.-J. eq.)

- We show regularization/unique limit usi, g only on this formulation.
- The uniqueness proof based on kinetic formulation
- ullet Continuity with respect to  ${f W}$  in  $C^0$

#### How do we define a solution?

Definition. We 'regularize along the characteristics. Consider

$$\begin{cases} \rho^0 \in \mathcal{D}(\mathbb{R}^N) & \text{such that } \rho^0 \geq 0 \quad \text{and} \quad \int_{\mathbb{R}^N} \rho^0(x) dx = 1, \\ \rho(y, x, \xi, t) = \rho^0 \Big( y - x + \mathbf{a}(\xi) \mathbf{W}(t) \Big), \end{cases}$$

solves formally the linear transport equation

$$d\rho + \sum_{i=1}^{N} a_i(\xi) \frac{\partial}{\partial x_i} \rho \circ dW^i = 0$$
 in  $\mathbb{R}^N \times \mathbb{R} \times (0, \infty)$ , and, hence,

$$d(\rho(y,x,\xi,t)\chi(x,\xi,t)) + \sum_{i=1}^{N} a_i(\xi) \frac{\partial}{\partial x_i} \rho \chi \circ dW^i = \rho(y,x,\xi,t) \frac{\partial}{\partial \xi} m(x,\xi,t) dt.$$

$$\frac{d}{dt} \int_{\mathbb{R}^N} \chi(x,\xi,t) \rho(y,x,\xi,t) dx = -\int_{\mathbb{R}^N} \frac{\partial}{\partial \xi} \rho(y,x,\xi,t) m(x,\xi,t) dx.$$

#### Can one prove existence, uniqueness?

**Theorem (Pathwise entropy solutions)** There is a unique 'kinetic pathwise solution'

• for a given W

$$||u_2(\cdot,t)-u_1(\cdot,t)||_{L^1(\mathbb{R}^N)} \le ||u_2^0-u_1^0||_{L^1(\mathbb{R}^N)}.$$

ullet for two paths  $\mathbf{W_i}$  and  $u_i^0 \in BV(\mathbb{R}^N)$ , then  $u_1$  and  $u_2$  satisfy

$$\begin{aligned} \|u_{2}(\cdot,t) - u_{1}(\cdot,t)\|_{L^{1}(\mathbb{R}^{N})} &\leq \|u_{2}^{0} - u_{1}^{0}\|_{L^{1}(\mathbb{R}^{N})} \\ &+ |(\mathbf{W}_{1} - \mathbf{W}_{2})(t)| \|\mathbf{a}\|(|u_{1}^{0}|_{BV(\mathbb{R}^{N})} + |u_{2}^{0}|_{BV(\mathbb{R}^{N})}) \\ &+ \left(\sup_{s \in (0,t)} \left| (\mathbf{W}_{1} - \mathbf{W}_{2})(s) \right| \|\mathbf{a}'\|[\|u_{1}^{0}\|_{L^{2}(\mathbb{R}^{N})}^{2} + \|u_{2}^{0}\|_{L^{2}(\mathbb{R}^{N})}^{2}] \right)^{1/2}. \end{aligned}$$

Conclude...

# Space dependent case

$$\begin{cases} du + \sum_{i=1}^{N} \frac{\partial}{\partial x_i} A_i(x, u) \circ dW(t) = 0 & \text{in} \quad \mathbb{R}^N \times (0, \infty), \\ u = u^0 & \text{on} \quad \mathbb{R}^N \times \{0\}. \end{cases}$$

One W(t) only!

Kinetic formulation A.-L. Dalibard

$$d\chi + \sum_{i=1}^{N} a_i(x,\xi) \frac{\partial}{\partial x_i} \chi \circ dW(t) - b(x,\xi) \frac{\partial}{\partial \xi} \chi \circ dW(t) = \frac{\partial}{\partial \xi} m dt$$
$$a_i(x,\xi) = \frac{\partial}{\partial x_i} A_i(x,\xi), \qquad b(x,\xi) = \sum_i \frac{\partial}{\partial \xi} A_i(x,\xi).$$

#### **Space dependent case**

We test against smooth 'generalized convolution kernels'

$$d\rho + \sum_{i=1}^{N} a_i(x,\xi) \frac{\partial}{\partial x_i} \rho \circ dW(t) - b(x,\xi) \frac{\partial}{\partial \xi} \rho \circ dW(t) = 0.$$

And these are given by

$$\rho(x,\xi,t) = \widehat{\rho}(x,\xi,W(t)),$$

with

$$\frac{\partial}{\partial t}\widehat{\rho} + \sum_{i=1}^{N} a_i(x,\xi) \frac{\partial}{\partial x_i} \widehat{\rho} - b(x,\xi) \frac{\partial}{\partial \xi} \widehat{\rho} = 0.$$

**Definition** A stochastic kinetic solution is defined by

$$\frac{d}{dt}\int \rho(x,\xi,t) \ \chi(x,\xi,t) dx d\xi = -\int m(x,\xi,t) \frac{\partial}{\partial \xi} \rho(x,\xi,t).$$

#### Space dependent case

**Theorem** There is a unique stochastic kinetic solution and for a given  $\mathbf{W}$ 

$$||u_2(\cdot,t)-u_1(\cdot,t)||_{L^1(\mathbb{R}^N)} \le ||u_2^0-u_1^0||_{L^1(\mathbb{R}^N)}.$$

- Existence is through weak limits
- ullet Continuous dependency on W(t) is not proved
- ullet Extension to multiple  $W^i(t)$  by B. Guess. Characteristics

$$dX_i = a_i(x,\xi)dW^i(t), \qquad d\Xi(t) = -b(x,\xi)d\mathbf{W}(t)$$

It is difficult to resist the idea to consider simply

$$\begin{cases} \frac{\partial}{\partial t} f(x,\xi,t) + \dot{B}(t) \circ \xi . \nabla_x f = g(x,\xi,t) & \text{in } \mathbb{R}^{2d} \times (0,\infty), \\ f(0) = f^0 & \text{on } \mathbb{R}^{2N}. \end{cases}$$

The notation for the flux means

$$\dot{B}(t) \circ \xi . \nabla_x f = \dot{B}(t) \sum_{i=1}^N \xi_i \frac{\partial f}{\partial x_i}.$$

And the Stratonovich solution

$$\frac{d}{dt}f(x-B(t)\xi,\xi,t) = g(x-B(t)\xi,\xi,t).$$

$$\begin{cases} \frac{\partial}{\partial t} f(x,\xi,t) + \dot{B}(t) \circ \xi . \nabla_x f = g(x,\xi,t) & \text{in } \mathbb{R}^{2N} \times (0,\infty), \\ f(0) = f^0 & \text{on } \mathbb{R}^{2N}. \end{cases}$$

Kinetic averaging lemma aim to prove regularity for

$$\rho_{\psi}(x,t) = \int_{\mathbb{R}^N} \psi(\xi) f(x,\xi,t) d\xi$$

with  $\psi$  a smooth function with compact support.

$$\begin{cases} \frac{\partial}{\partial t} f(x, \xi, t) + \xi . \nabla_x f = g(x, \xi, t) & \text{in} \quad \mathbb{R}^{2N} \times (0, \infty), \\ f(0) = f^0 & \text{on} \quad \mathbb{R}^{2N}. \end{cases}$$

**Theorems** (Deterministic averaging). Take B(t) = t.

For g = 0 and  $\lambda \ge 0$ 

$$\|e^{-\lambda t}\rho_{\psi}\|_{L^{2}\left(R^{+};\dot{H}^{1/2}(\mathbb{R}^{N})\right)}^{2} \leq C(\psi) \|f^{0}\|_{L^{2}(\mathbb{R}^{N}\times\mathbb{R}^{N})}^{2}$$

For  $f^0 = 0$ 

$$\|\rho_{\psi}\|_{L^{2}\left(R^{+};\dot{H}^{1/2}(\mathbb{R}^{N})\right)}^{2} \leq C \|g\|_{L^{2}(\mathbb{R}^{+}\times\mathbb{R}^{N}\times\mathbb{R}^{N})} \|f\|_{L^{2}(\mathbb{R}^{+}\times\mathbb{R}^{N}\times\mathbb{R}^{N})}$$

For  $f^0 = 0$  and  $g = \operatorname{div}_{\xi} h$ , we have

$$\|\rho_{\psi}\|_{L^{2}\left(R^{+};\dot{H}^{1/4}(\mathbb{R}^{N})\right)}^{2} \leq C \|h\|_{L^{2}(\mathbb{R}^{+}\times\mathbb{R}^{N}\times\mathbb{R}^{N})}^{1/2} \|f\|_{L^{2}(\mathbb{R}^{+}\times\mathbb{R}^{N}\times\mathbb{R}^{N})}^{3/2}$$

Long story behind that : F. Golse, BP, R. Sentis (CRAS 1985), P.-L. Lions, Meyer, Gérard, Souganidis... Tadmor and Tao

The proof is based is inspired by the version in F. Bouchut and L. Desvillettes (no Fourier in time)

**Theorem** (Comparison deterministic/stochastic).

1. For g = 0 and  $\lambda \ge 0$  we have

$$\|e^{-\lambda t}\rho_{\psi}\|_{L^{2}\left(R^{+};\dot{H}^{1/2}(\mathbb{R}^{N})\right)}^{2} \leq C(\psi) \|f^{0}\|_{L^{2}(\mathbb{R}^{N}\times\mathbb{R}^{N})}^{2}.$$

$$\mathbb{E}\|e^{-\lambda t}\rho_{\psi}\|_{L^{2}\left(R^{+};\dot{H}^{1/2}(\mathbb{R}^{N})\right)}^{2} \leq \frac{C(\sup p \psi)}{\lambda^{1/2}}\|f^{0}\|_{L^{2}(\mathbb{R}^{N}\times\mathbb{R}^{N})}^{2}.$$

**Theorem** (Comparison deterministic/stochastic).

2. For  $f^0 = 0$  we have

$$\|\rho_{\psi}\|_{L^{2}(\mathbb{R}^{+};\dot{H}^{1/2}(\mathbb{R}^{N}))}^{2} \leq C\|g\|_{L^{2}(\mathbb{R}^{+}\times\mathbb{R}^{N}\times\mathbb{R}^{N})}\|f\|_{L^{2}(\mathbb{R}^{+}\times\mathbb{R}^{N}\times\mathbb{R}^{N})}.$$

$$\mathbb{E}\|\rho_{\psi}\|_{L^{2}\left(R^{+};\dot{H}^{1/2}(\mathbb{R}^{N})\right)}^{2} \leq C\|g\|_{L^{2}(\mathbb{R}^{+}\times\mathbb{R}^{N}\times\mathbb{R}^{N})}^{1/2}\|f\|_{L^{2}(\mathbb{R}^{+}\times\mathbb{R}^{N}\times\mathbb{R}^{N})}^{3/2}.$$

**Theorem** (Comparison deterministic/stochastic).

3. For  $f^0 = 0$  and  $g = \text{div}_{\xi}h$ , we have

$$\|\rho_{\psi}\|_{L^{2}\left(R^{+};\dot{H}^{1/4}(\mathbb{R}^{N})\right)}^{2} \leq C\|h\|_{L^{2}(\mathbb{R}^{+}\times\mathbb{R}^{N}\times\mathbb{R}^{N})}^{1/2}\|f\|_{L^{2}(\mathbb{R}^{+}\times\mathbb{R}^{N}\times\mathbb{R}^{N})}^{3/2}.$$

$$\mathbb{E}\|\rho_{\psi}\|_{L^{2}\left(R^{+};\dot{H}^{1/3}(\mathbb{R}^{N})\right)}^{2} \leq C\|h\|_{L^{2}(\mathbb{R}^{+}\times\mathbb{R}^{N}\times\mathbb{R}^{N})}^{2/3}\|f\|_{L^{2}(\mathbb{R}^{+}\times\mathbb{R}^{N}\times\mathbb{R}^{N})}^{4/3}.$$

Idea of the proof.

$$\frac{\partial}{\partial t}\widehat{f}(k,\xi,t) + i\dot{B}(t) \circ k.\xi \widehat{f} = \widehat{g}.$$

$$\frac{\partial}{\partial t}\widehat{f}(k,\xi,t) + i\dot{B}(t) \circ k.\xi \widehat{f} + \lambda \widehat{f} = \widehat{g} + \lambda \widehat{f}.$$

$$\widehat{f}(k,\xi,t) = \widehat{f}^{0}(k,\xi)e^{-\lambda t - iB(t)k.\xi}$$

$$+ \int_{0}^{t} e^{-\lambda s} \left[\widehat{g} + \lambda \widehat{f}\right](k,\xi,t-s) \left[e^{ik.\xi \left(B(t-s) - B(t)\right)} ds\right]$$

$$|\widehat{\rho_{\psi}}(k,t)|^2 \le 2 \left| \int \psi \widehat{f^0}(k,\xi) e^{-\lambda t - iB(t)k.\xi} d\xi \right|^2$$

$$+2\left|\int_0^t \int e^{-\lambda s} \left[\psi \widehat{g} + \lambda \psi \widehat{f}\right](k,\xi,t-s) e^{ik.\xi \left(B(t-s)-B(t)\right)} ds d\xi\right|^2.$$

For g = 0

$$\leq \mathbb{E} \int_{t=0}^{\infty} \int \psi \widehat{f^0}(k,\xi_1) \ \overline{\psi \widehat{f^0}(k,\xi_2)} e^{-2\lambda t - iB(t)k.(\xi_1 - \xi_2)} d\xi_2 d\xi_1 dt$$

## **Conclusion**

In the non-degenerate case :  $\xi \mapsto a(\xi)$  not locally contained in an hyperplane

we know regularizing effects based on the kinetic formulation.

For random conservation laws, they are certainly very different

# HAPPY BIRTHDAY EITAN