

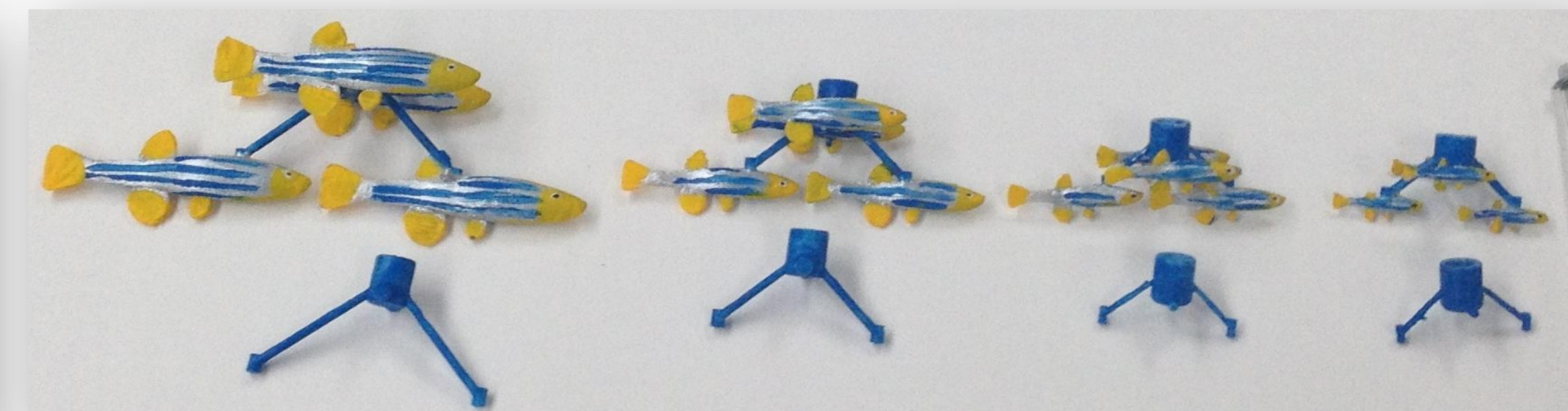
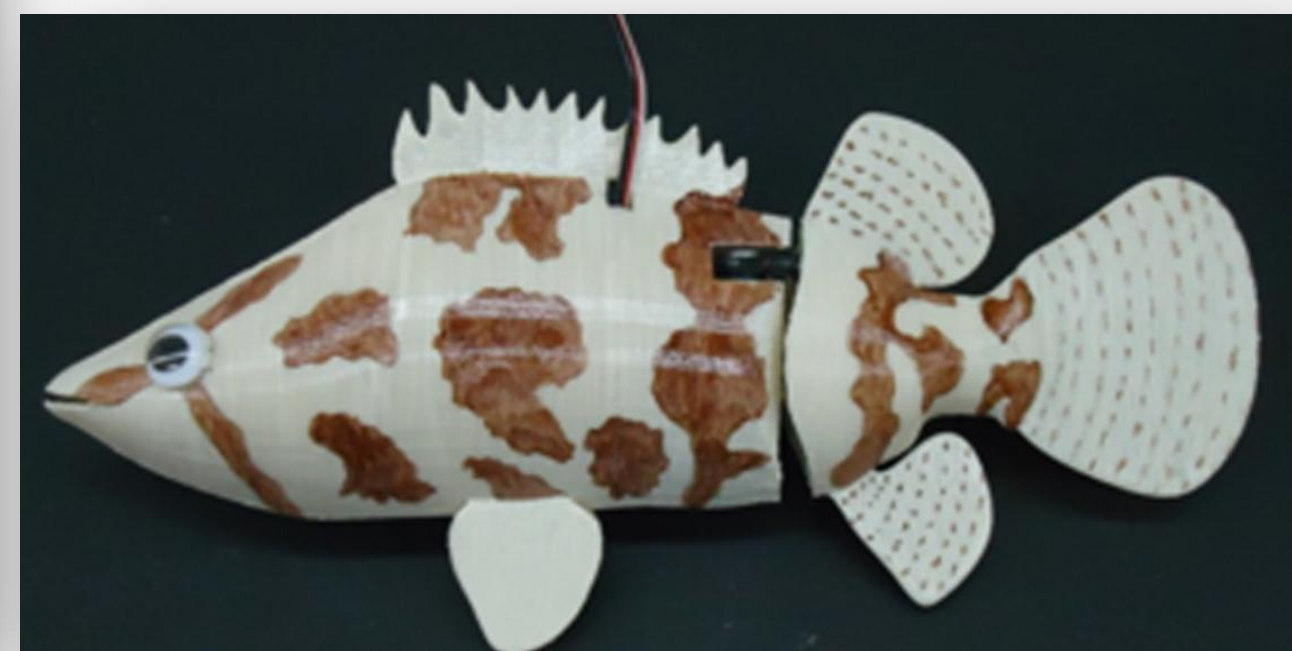
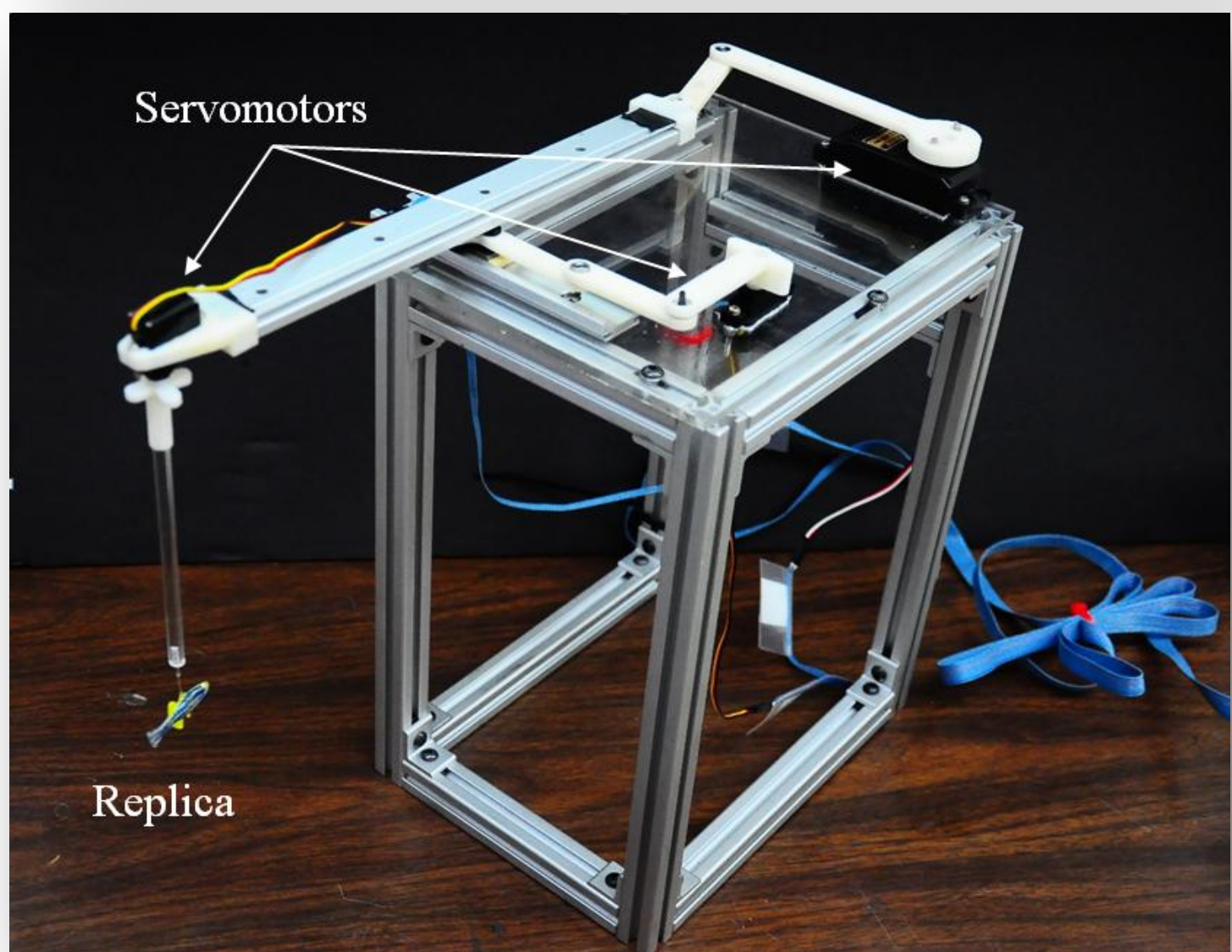
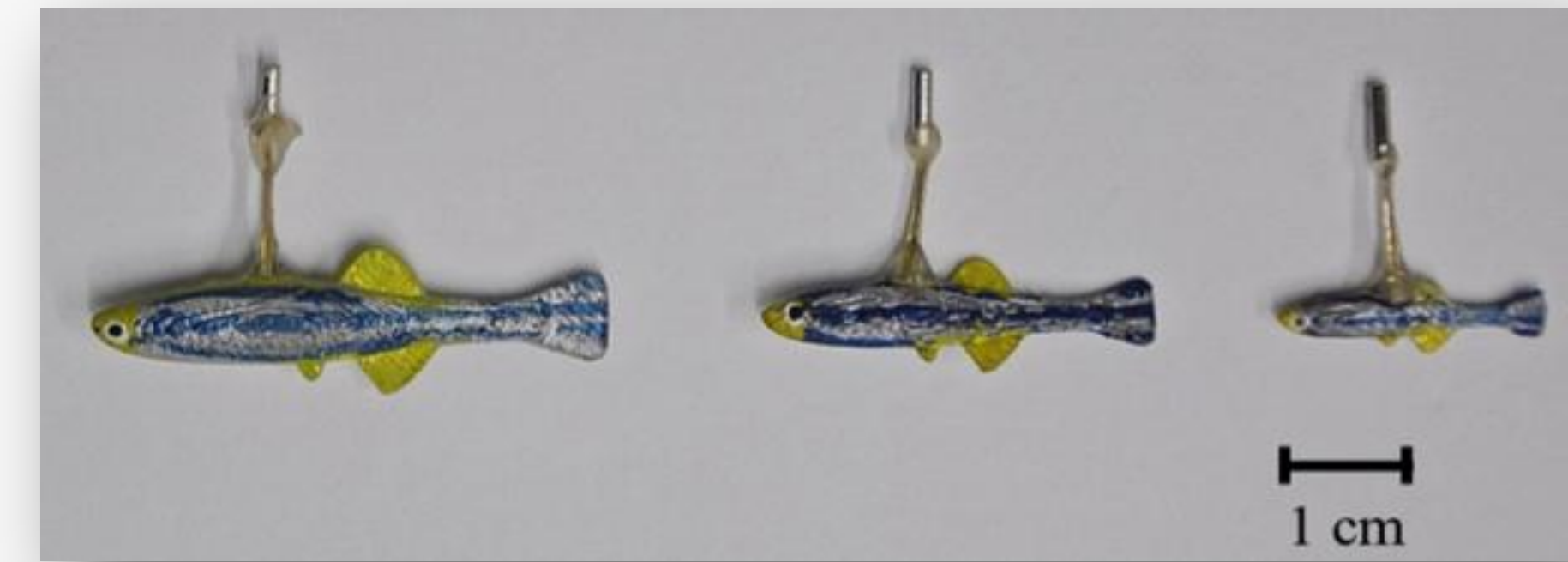
# Fish 'n' robots: not a take-out food

Tiziana Bartolini



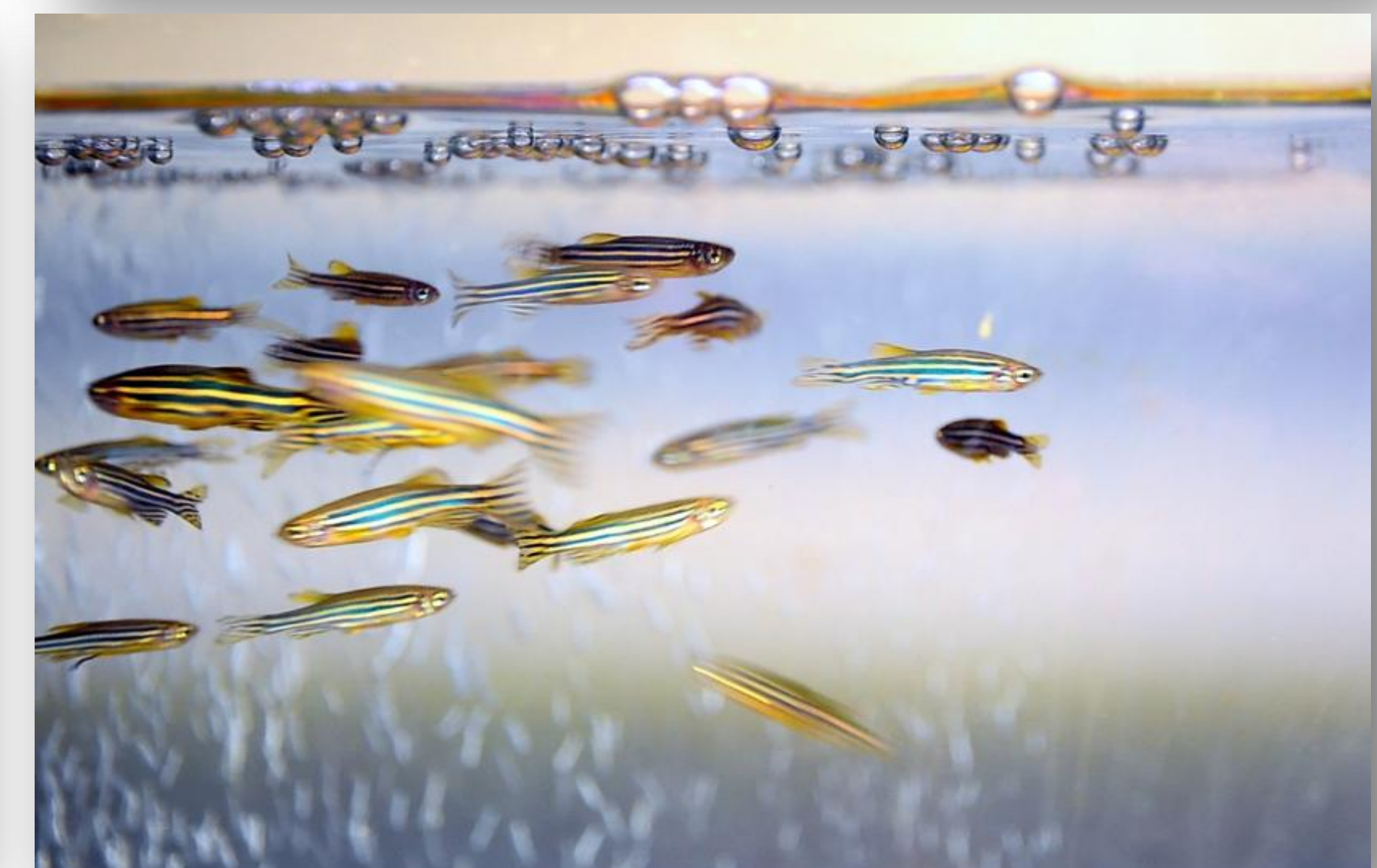
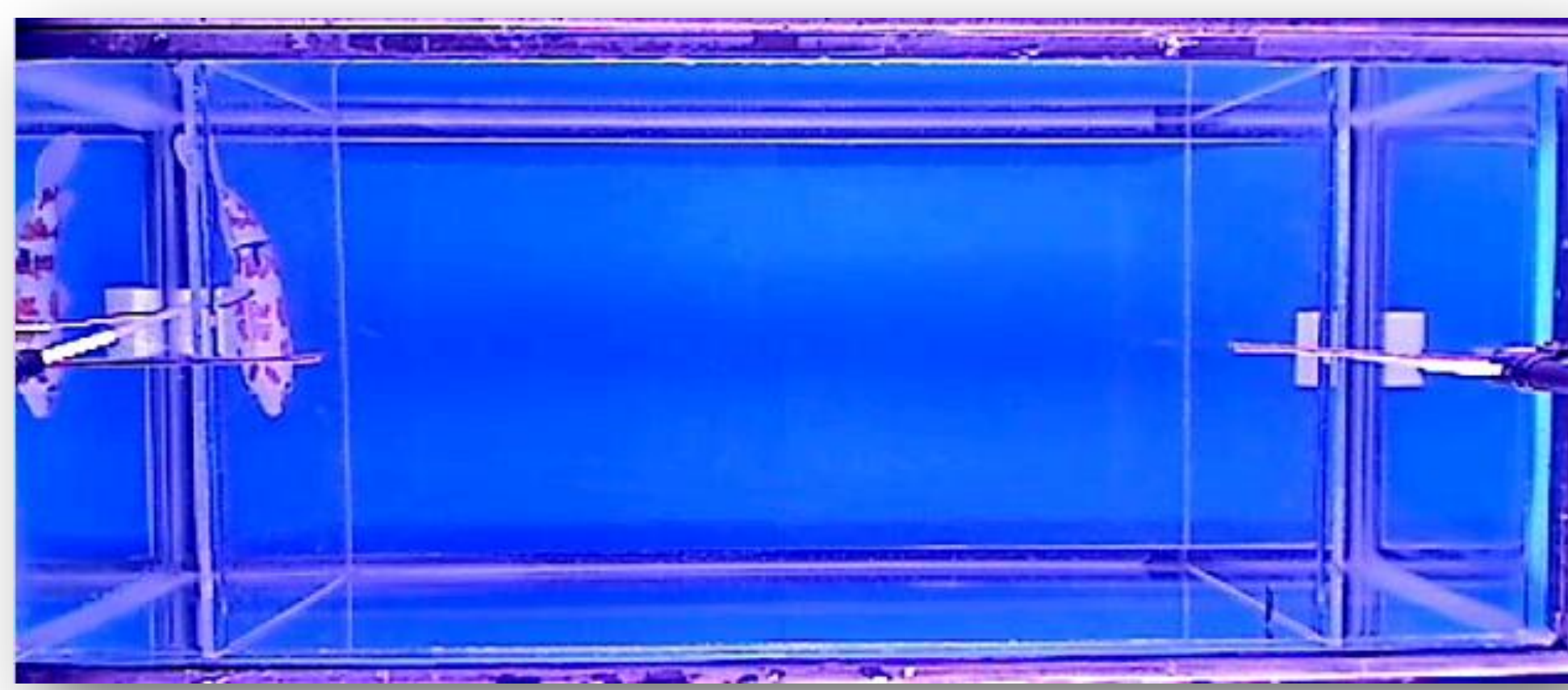
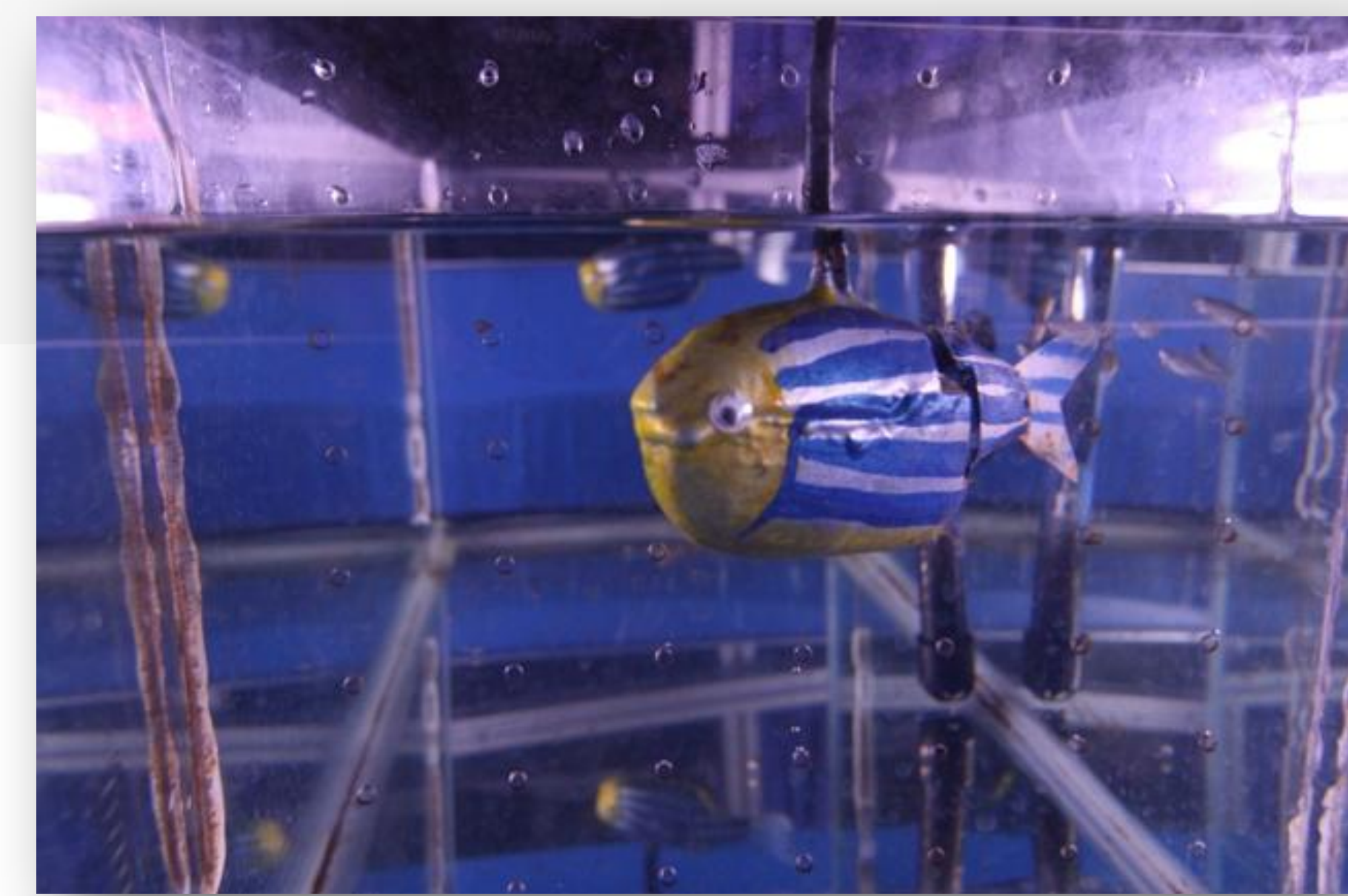
## Robotics to aid animal behavior research

- Remotely-controlled biologically-inspired robotic fish of various sizes and capabilities
- More consistent animal response
- Increased throughput of experiments by decreasing the number of animals required
- Larger degree of control through 3D stimuli



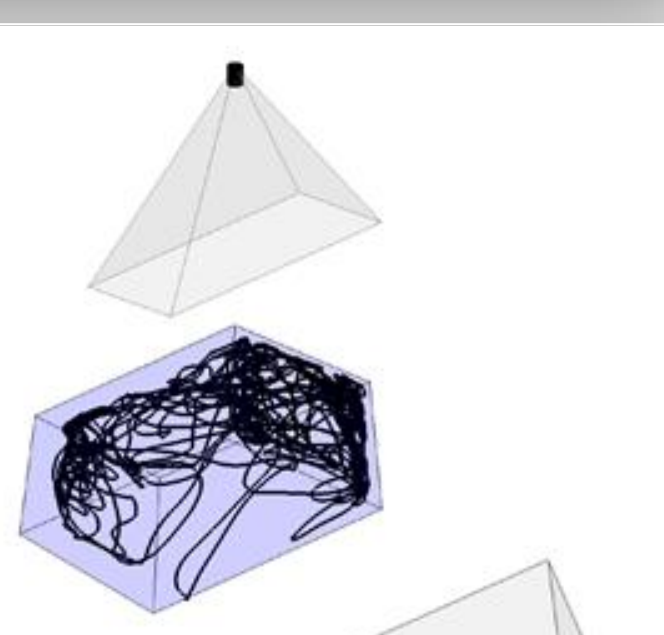
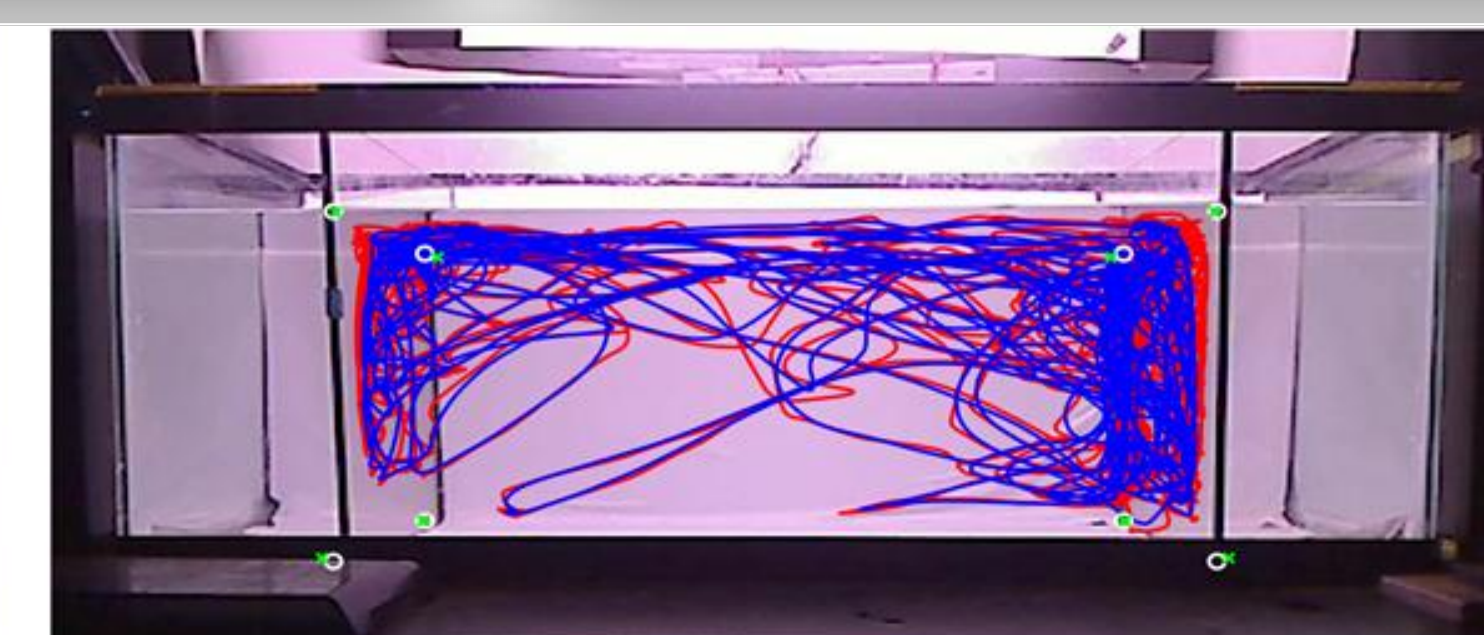
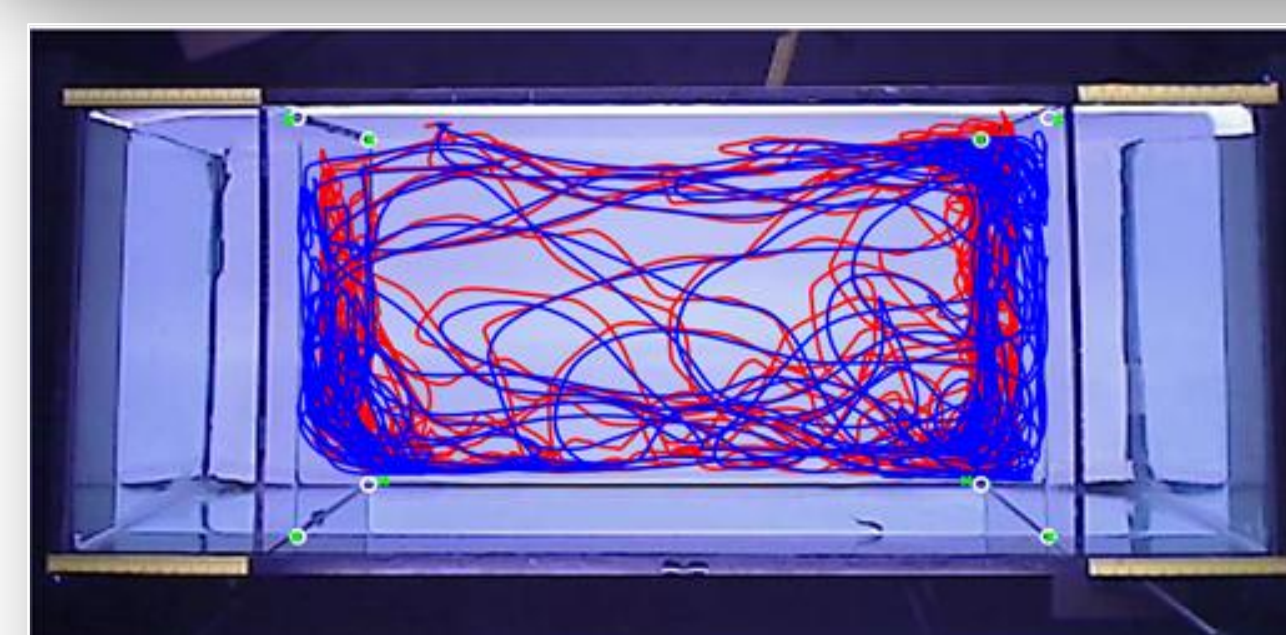
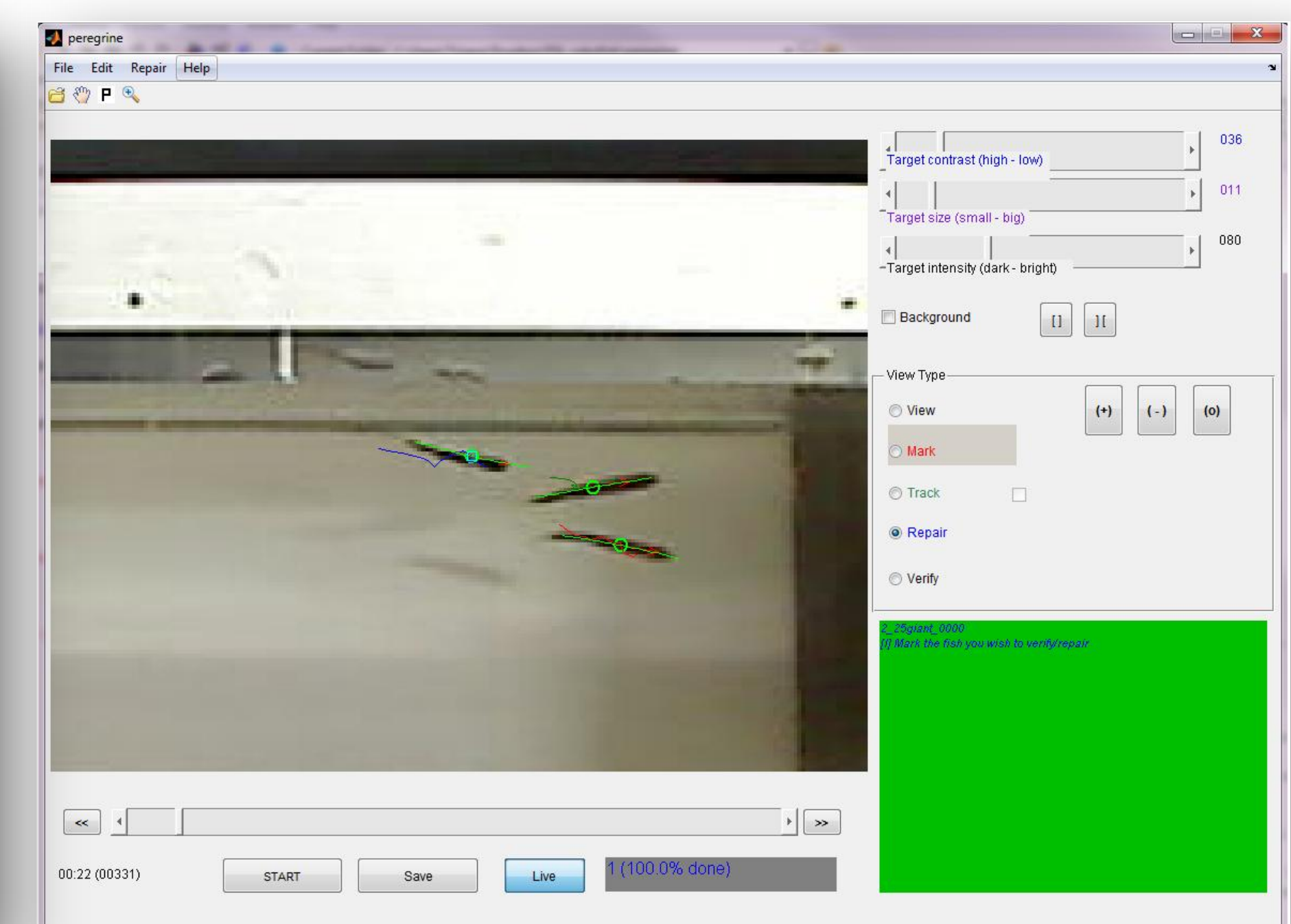
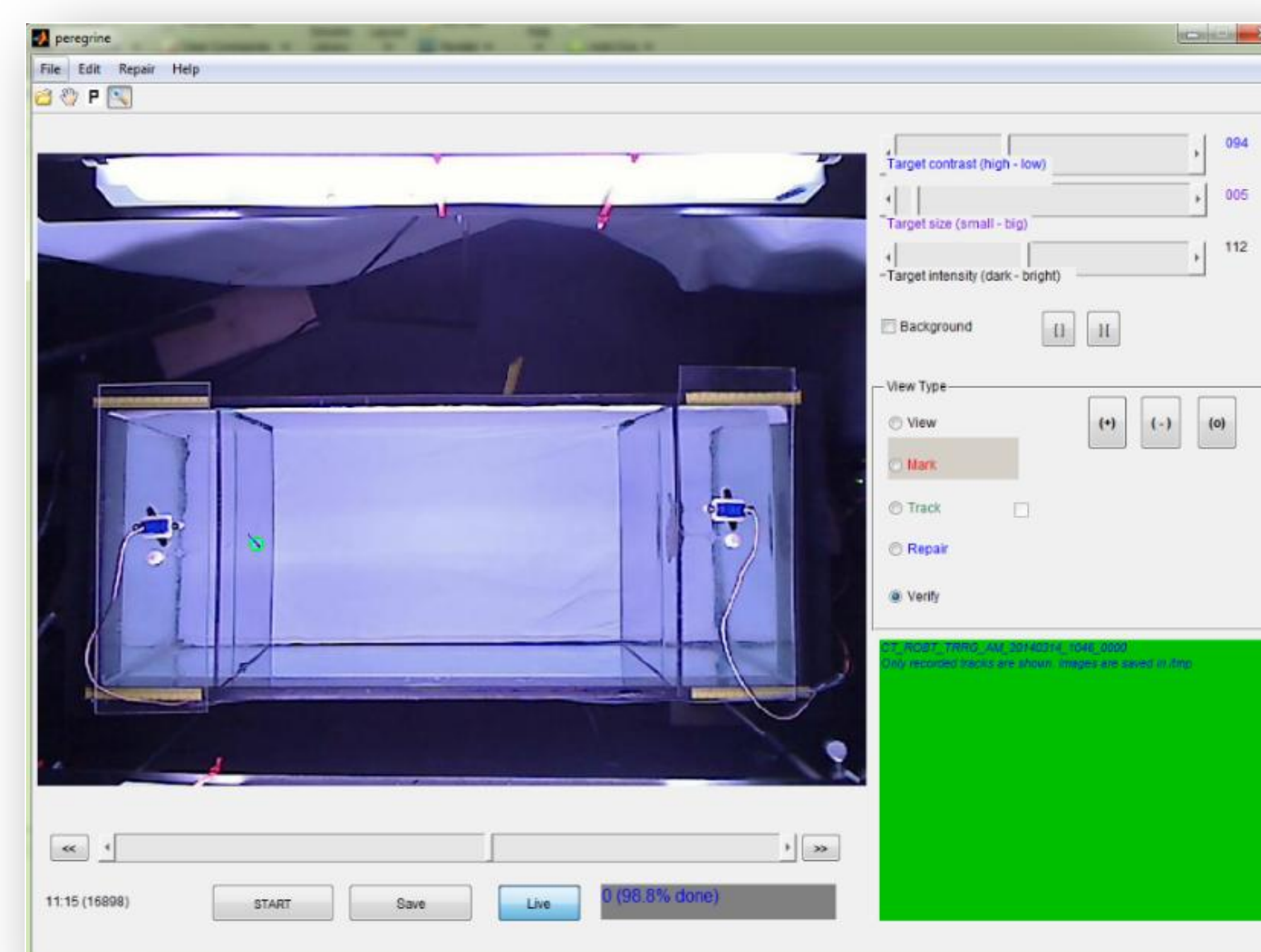
## Biologically-inspired robots for hypothesis-driven research on animal behavior

- Studying visual and flow cues in social interactions
- Closing the loop on live fish behavior
- Robotics-based experimental paradigm for measuring animal response to predators



## Automatic tracking system

- Kalman filtering to estimate 2D position
- Shape tracking
- 3D tracking by merging synchronized videos from different fields of view
- Resolution of occlusions with minimal manual repairs
- Post-processing of fish trajectories to score locomotory patterns



## Contact

Maurizio Porfiri  
Professor  
Department of Mechanical Aerospace Engineering  
New York University Polytechnic School of Engineering

✉ 507 Rogers Hall  
6 MetroTech Center  
Brooklyn, NY 11201 USA  
☎ +01-718-260-3681  
@ mporfiri@nyu.edu  
🖱 <http://faculty.poly.edu/~mporfiri/>

