

# Landau damping of inhomogeneous states in the Kuramoto model

Helge Dietert

Joint work with Bastien Fernandez and David Gérard-Varet

Duke, 29 November 2016

# Kuramoto model

**Aim:** Model synchronisation behaviour of oscillators

- Describe each oscillator by a phase angle  $\theta_i$  and intrinsic frequency  $\omega_i$

# Kuramoto model

**Aim:** Model synchronisation behaviour of oscillators

- Describe each oscillator by a phase angle  $\theta_i$  and intrinsic frequency  $\omega_i$
- Note that we can take out a global rotation (drift) by setting  $\omega_i - \bar{\omega}$

# Kuramoto model

**Aim:** Model synchronisation behaviour of oscillators

- Describe each oscillator by a phase angle  $\theta_i$  and intrinsic frequency  $\omega_i$
- Note that we can take out a global rotation (drift) by setting  $\omega_i - \bar{\omega}$
- Add a simple global coupling (strength  $K$ )

$$\partial_t \theta_i = \omega_i + \frac{K}{N} \sum_{j=1}^N \sin(\theta_j - \theta_i)$$

# Kuramoto model

**Aim:** Model synchronisation behaviour of oscillators

- Describe each oscillator by a phase angle  $\theta_i$  and intrinsic frequency  $\omega_i$
- Note that we can take out a global rotation (drift) by setting  $\omega_i - \bar{\omega}$
- Add a simple global coupling (strength  $K$ )

$$\partial_t \theta_i = \omega_i + \frac{K}{N} \sum_{j=1}^N \sin(\theta_j - \theta_i)$$

- When does this coupling synchronise the system?

## Mean-field limit

We study the mean-field (continuum) limit as  $N \rightarrow \infty$ :

- Describe the state by the probability density  $\rho(t, \cdot, \cdot)$ , i.e.

$$\rho(t, \omega, \theta) d\omega d\theta$$

is the proportion of oscillators at time  $t$  with natural frequency within  $[\omega, \omega + d\omega]$  and phase angle within  $[\theta, \theta + d\theta]$ .

- Evolution is given by the PDE

$$\begin{cases} \partial_t \rho(t, \theta, \omega) + \partial_\theta \left[ \left( \omega + \frac{K}{2i} (\eta(t) e^{-i\theta} - \overline{\eta(t)} e^{i\theta}) \right) \rho(t, \theta, \omega) \right] = 0, \\ \eta(t) = \int_{\theta=0}^{2\pi} e^{i\theta} \int_{\mathbb{R}} \rho(t, \theta, \omega) d\omega d\theta, \end{cases}$$

where  $\eta(t)$  is the order parameter.

- As kinetic equation  $\theta$  is the position and  $\omega$  is the velocity.

## Homogeneous state

A spatial homogeneous state  $\rho(\theta, \omega) = (2\pi)^{-1}g(\omega)$  is a stationary solution with order parameter  $\eta = 0$ .

### Questions

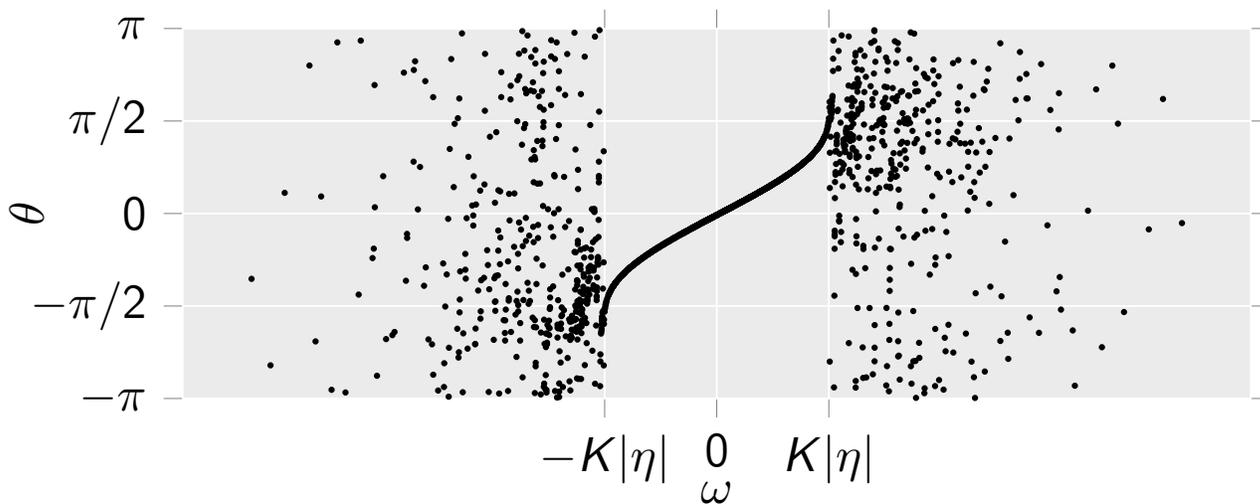
- Is it stable?
- How is the phase transition as the order parameter increases?

## Inhomogeneous state

If we look at a stationary solution with order parameter  $\eta \neq 0$ :

- Oscillators with  $|\omega| \leq K|\eta|$  are trapped
- Oscillators with  $|\omega| > K|\eta|$  are moving around with varying velocity

These states are called *partially locked states* and we ask again whether they are stable.



### Question

When are these states stable?

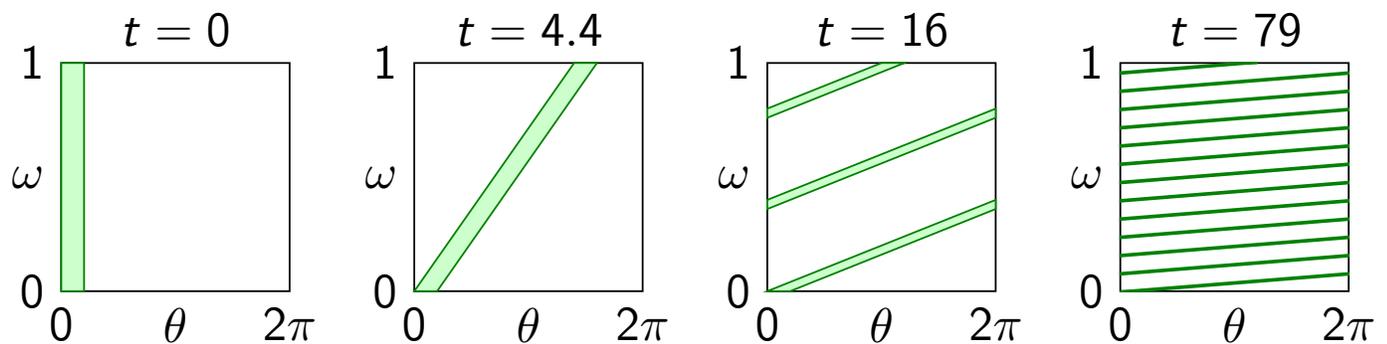
# Intuitive picture

Two competing mechanisms

## Intuitive picture

### Two competing mechanisms

- **Averaging** through the free transport  $\partial_t \rho + \partial_\theta [\omega \rho] = 0$ : The heterogeneity of the natural frequencies  $\omega$  mixes the distribution in phase space



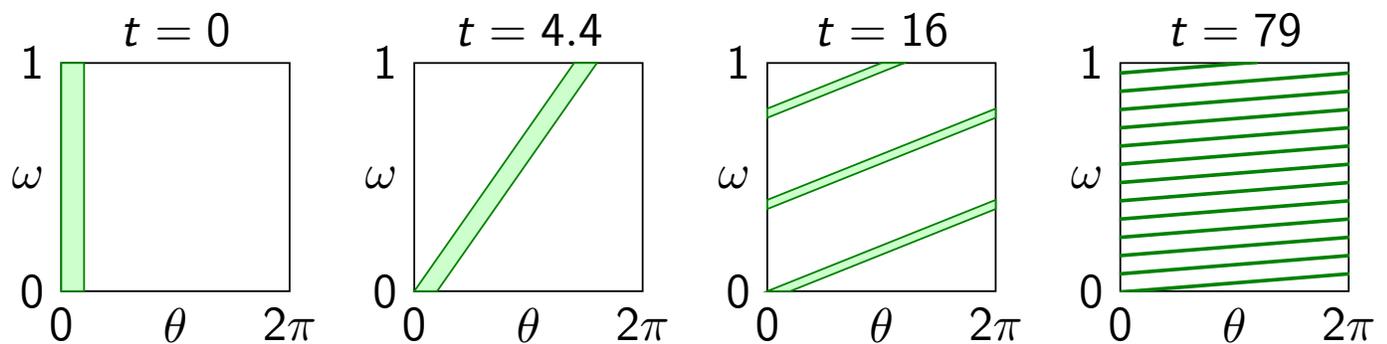
After integrating over  $\omega$  the system spreads out:  $\eta \rightarrow 0$

- **Coupling** term concentrates the phase angles.

## Intuitive picture

### Two competing mechanisms

- **Averaging** through the free transport  $\partial_t \rho + \partial_\theta [\omega \rho] = 0$ : The heterogeneity of the natural frequencies  $\omega$  mixes the distribution in phase space



After integrating over  $\omega$  the system spreads out:  $\eta \rightarrow 0$

- **Coupling** term concentrates the phase angles.

### Challenge

Find norms that capture the spreading of the free transport

# Capturing Landau damping

## Idea

Capture Landau damping by focusing on macroscopic quantities  $\eta$ .

Here  $\eta$  is just the order parameter. For the Vlasov–Poisson equation take the modes of the electric field.

## Linearised behaviour

A perturbation  $u$  of a stationary state has the linear evolution operator  $L = L_1 + L_2$  with

- $L_1$  is the transport operator under the stationary state.
- $L_2$  is a bounded operator depending only on  $\eta[u]$  and models the interaction of the perturbation on the background state.

## Volterra equation

By Duhamel's principle we find

$$u(t) = e^{tL_1} u_{\text{in}} + \int_0^t e^{(t-s)L_1} L_2 u(s) ds.$$

## Volterra equation

By Duhamel's principle we find

$$u(t) = e^{tL_1} u_{\text{in}} + \int_0^t e^{(t-s)L_1} L_2 u(s) ds.$$

Computing  $\eta$  from  $u$  gives that  $\eta(t) = \eta[u(t)]$  satisfies the Volterra equation

$$\eta(t) + \int_0^t k(t-s)\eta(s) ds = F(t),$$

where

- $k$  is the interaction kernel,
- $F$  is the forcing.

## Resolvent

The solution to the Volterra equation

$$\eta(t) + \int_0^t k(t-s)\eta(s)ds = F(t),$$

can be expressed with the **resolvent**  $r$  as

$$\eta(t) = F(t) - (r * F)(t).$$

## Resolvent

The solution to the Volterra equation

$$\eta(t) + \int_0^t k(t-s)\eta(s)ds = F(t),$$

can be expressed with the **resolvent**  $r$  as

$$\eta(t) = F(t) - (r * F)(t).$$

The resolvent is the unique solution to

$$r = k - k * r = k - r * k.$$

### Stability (Paley-Wiener, Gel'fand)

The resolvent  $r$  has the same weighted integrability as  $k$  apart from eigenmodes with eigenvalue  $z$  solving

$$(\mathcal{L}k)(z) = \int_0^\infty k(t)e^{-tz}dt = -\frac{K}{2} \int_0^\infty \hat{g}(t)e^{-tz}dt = -1.$$

## Localise energy in Fourier

### Observations

- The spatial mode  $l = 0$  is the distribution of the natural frequencies and constant
- The positive modes  $l \geq 1$  decouple from the negative modes  $l \leq -1$

Take the Fourier transformation  $\theta \rightarrow l$  and  $\omega \rightarrow \xi$ . The transform  $\rho \rightarrow u$  evolves by

$$\partial_t u(t, 1, \xi) = \partial_\xi u(t, 1, \xi) + \frac{K}{2} \left[ \eta(t) \hat{g}(\xi) - \overline{\eta(t)} u(t, 2, \xi) \right]$$

and for  $l \geq 2$

$$\partial_t u(t, l, \xi) = l \partial_\xi u(t, l, \xi) + \frac{Kl}{2} \left[ \eta(t) u(t, l-1, \xi) - \overline{\eta(t)} u(t, l+1, \xi) \right]$$

and the coupling is modulated by the order parameter  $\eta(t) = u(t, 1, 0)$

## Localise energy in Fourier

### Observations

- The spatial mode  $l = 0$  is the distribution of the natural frequencies and constant
- The positive modes  $l \geq 1$  decouple from the negative modes  $l \leq -1$

Take the Fourier transformation  $\theta \rightarrow l$  and  $\omega \rightarrow \xi$ . The transform  $\rho \rightarrow u$  evolves by

$$\partial_t u(t, 1, \xi) = \partial_\xi u(t, 1, \xi) + \frac{K}{2} \left[ \eta(t) \hat{g}(\xi) - \overline{\eta(t)} u(t, 2, \xi) \right]$$

and for  $l \geq 2$

$$\partial_t u(t, l, \xi) = l \partial_\xi u(t, l, \xi) + \frac{Kl}{2} \left[ \eta(t) u(t, l-1, \xi) - \overline{\eta(t)} u(t, l+1, \xi) \right]$$

and the coupling is modulated by the order parameter  $\eta(t) = u(t, 1, 0)$

## Global stability result of the homogeneous state

### Theorem (Global stability)

Let

$$K_{ec} = \frac{2}{\int_{\xi=0}^{\infty} |\hat{g}(\xi)| d\xi}.$$

Then if  $K < K_{ec}$ , the evolution is stable in the sense that  $\int_0^{\infty} |\eta(s)|^2 ds < \infty$ .

## Global stability result of the homogeneous state

### Theorem (Global stability)

Let

$$K_{ec} = \frac{2}{\int_{\xi=0}^{\infty} |\hat{g}(\xi)| d\xi}.$$

Then if  $K < K_{ec}$ , the evolution is stable in the sense that  $\int_0^{\infty} |\eta(s)|^2 ds < \infty$ .

**Remark:** For a Gaussian distribution  $K_{ec} = K_c$

**Proof:** Use energy functional

$$I(t) = \int_{\xi=0}^{\infty} \sum_{l \geq 1} \frac{1}{l} |u(t, l, \xi)|^2 \phi(\xi) d\xi,$$

where  $\phi$  is increasing. Under this most coupling terms vanish due to the skew-symmetry.

## Linearised system of the homogeneous state

In the linear setting only the first mode is interesting:

$$\partial_t u(t, 1, \xi) = \partial_\xi u(t, 1, \xi) + \frac{K}{2} \eta(t) \hat{g}(\xi)$$

Here  $\hat{g}(\xi)$  is the constant  $u(0, \xi)$  function.

For  $\eta(t) = u(t, 1, 0)$ , find the Volterra equation (Duhamel's principle)

$$\eta(t) + (k * \eta)(t) = u_{in}(1, t)$$

with the convolution kernel

$$k(t) = -\frac{K}{2} \hat{g}(t)$$

### Stability (Paley-Wiener)

If  $k$  is sufficiently decaying, the Volterra equation is stable iff

$$(\mathcal{L}k)(z) = \int_0^\infty k(t) e^{-tz} dt = -\frac{K}{2} \int_0^\infty \hat{g}(t) e^{-tz} dt \neq -1 \quad \forall \Re z \geq 0.$$

## Stability of incoherent state

### Linear stability

If the linear stability condition is satisfied, then we have decay as expected from the linear transport:

- If  $|u(1, \xi)| \leq e^{-a\xi}$ , then  $\eta$  decays as  $e^{-at}$
- If  $|u(1, \xi)| \leq (1 + \xi)^{-k}$ , then  $\eta$  decays as  $(1 + t)^{-k}$

### Nonlinear stability

Can propagate control in

$$\sup_{l \geq 1} \sup_{\xi \in \mathbb{R}} |u(t, l, \xi)| e^{a(\xi + tl/2)}$$

and

$$\sup_{l \geq 1} \sup_{\xi \in \mathbb{R}^+} |u(t, l, \xi)| \frac{(1 + \xi + t)^b}{(1 + t)^{\alpha(l-1)}}.$$

# Center-manifold reduction

## Eigenmodes

In the case the linear stability condition is violated, we have discrete eigenmodes, while the remainder decays as the free transport.

**Aim:** Reduce the dynamics to these eigenmodes for

- understanding the bifurcation behaviour
- (later) handle the rotation invariance of the partially locked states

## Center manifold reduction

Can reduce the dynamics to the amplitude along the eigenvector with nonlinear correction around the bifurcation.

## Stability of the partially inhomogeneous states

We now study the stability of partially locked states.

- Partially locked states have a rotation symmetry and thus we cannot expect decay to the same state.

### Theorem (Stability)

*If a partially locked states is linearly stable, then perturbed initial data will converge to the initial data up to a possible small rotation.*

## Duhamel reduction

Recall the evolution equation

$$\begin{cases} \partial_t \rho(t, \theta, \omega) + \partial_\theta \left[ \left( \omega + \frac{K}{2i} (\eta(t) e^{-i\theta} - \overline{\eta(t)} e^{i\theta}) \right) \rho(t, \theta, \omega) \right] = 0, \\ \eta(t) = \int_{\theta=0}^{2\pi} e^{i\theta} \int_{\mathbb{R}} \rho(t, \theta, \omega) d\omega d\theta \end{cases}$$

or in Fourier

$$\partial_t u(t, l, \xi) = l \partial_\xi u(t, l, \xi) + \frac{Kl}{2} \left[ \eta(t) u(t, l-1, \xi) - \overline{\eta(t)} u(t, l+1, \xi) \right].$$

## Duhamel reduction

Recall the evolution equation

$$\begin{cases} \partial_t \rho(t, \theta, \omega) + \partial_\theta \left[ \left( \omega + \frac{K}{2i} (\eta(t) e^{-i\theta} - \overline{\eta(t)} e^{i\theta}) \right) \rho(t, \theta, \omega) \right] = 0, \\ \eta(t) = \int_{\theta=0}^{2\pi} e^{i\theta} \int_{\mathbb{R}} \rho(t, \theta, \omega) d\omega d\theta \end{cases}$$

or in Fourier

$$\partial_t u(t, l, \xi) = l \partial_\xi u(t, l, \xi) + \frac{Kl}{2} \left[ \eta(t) u(t, l-1, \xi) - \overline{\eta(t)} u(t, l+1, \xi) \right].$$

The modes are not decoupled anymore, however, the reduction to a Volterra equation still works!

## Duhamel reduction

Recall the evolution equation

$$\begin{cases} \partial_t \rho(t, \theta, \omega) + \partial_\theta \left[ \left( \omega + \frac{K}{2i} (\eta(t) e^{-i\theta} - \overline{\eta(t)} e^{i\theta}) \right) \rho(t, \theta, \omega) \right] = 0, \\ \eta(t) = \int_{\theta=0}^{2\pi} e^{i\theta} \int_{\mathbb{R}} \rho(t, \theta, \omega) d\omega d\theta \end{cases}$$

or in Fourier

$$\partial_t u(t, l, \xi) = l \partial_\xi u(t, l, \xi) + \frac{Kl}{2} \left[ \eta(t) u(t, l-1, \xi) - \overline{\eta(t)} u(t, l+1, \xi) \right].$$

The modes are not decoupled anymore, however, the reduction to a Volterra equation still works!

In order to find a *complex* linear equation, consider  $\eta$  and  $\bar{\eta}$  as independent. We then find a *matrix* Volterra equation

$$\begin{pmatrix} \eta \\ \bar{\eta} \end{pmatrix} + k * \begin{pmatrix} \eta \\ \bar{\eta} \end{pmatrix} = F.$$

## Linear stability

The kernel  $k(t)$  consists of entries like

$$\int_0^{2\pi} \int_{\mathbb{R}} \left[ e^{tL_1} \partial_{\theta} (f_{\text{st}} e^{\pm i\theta}) \right] (\theta, \omega) e^{\pm i\theta} d\theta d\omega.$$

Can be explicitly expressed using integrals!

## Linear stability

The kernel  $k(t)$  consists of entries like

$$\int_0^{2\pi} \int_{\mathbb{R}} \left[ e^{tL_1} \partial_{\theta} (f_{\text{st}} e^{\pm i\theta}) \right] (\theta, \omega) e^{\pm i\theta} d\theta d\omega.$$

Can be explicitly expressed using integrals!

Eigenmodes  $z$  at

$$\det [1 + (\mathcal{L}k)(z)] = 0.$$

## Linear analysis (analytic regularity)

For the perturbation  $u$  in Fourier space show decay in norms like

$$\|u\|_{a,k} = \left( \sum_{l \in \mathbb{N}} \int_{\mathbb{R}} e^{2a\xi} l^{2k} (|u_l(\xi)|^2 + |\partial_\xi u_l(\xi)|^2) d\xi \right)^{1/2}.$$

### Strategy

- Split the linear evolution operator  $L = L_1 + L_2$  where
  - $L_1$  is the transport term under a fixed external forcing (matching the free transport operator)
  - $L_2$  is the finite-rank operator corresponding to the coupling

## Linear analysis (analytic regularity)

For the perturbation  $u$  in Fourier space show decay in norms like

$$\|u\|_{a,k} = \left( \sum_{l \in \mathbb{N}} \int_{\mathbb{R}} e^{2a\xi} l^{2k} (|u_l(\xi)|^2 + |\partial_\xi u_l(\xi)|^2) d\xi \right)^{1/2}.$$

### Strategy

- Split the linear evolution operator  $L = L_1 + L_2$  where
  - $L_1$  is the transport term under a fixed external forcing (matching the free transport operator)
  - $L_2$  is the finite-rank operator corresponding to the coupling
- For  $L_1$  replace the explicit solution formula with resolvent estimates in suitable Hilbert spaces
- For  $L_2$  add a complexification by treating  $\bar{\eta}$  as independent variable.

## Nonlinear stability

### Remove eigenmode from rotation symmetry

Express the solution as

$$f = R_{\Theta}(f_{\text{st}} + u)$$

where  $R$  is the rotation and the angle  $\Theta$  is continuously chosen such that  $u$  is in the stable subspace. Then

$$\partial_t u = Lu + P_s Q' u \text{ where } Q' u = Qu - \frac{2\Re\langle Qu, u^* \rangle_{a,0}}{1 + 2\Re\langle D\hat{R}u, u^* \rangle_{a,0}} D\hat{R}u.$$

### Close the estimate

Using the regularisation effect of the linear evolution between  $\|\cdot\|_{a,-1}$  and  $\|\cdot\|_{a,0}$ , we can close the estimates.

## Sobolev regularity

Want to extend the stability result to Sobolev regularity.

### Problem

The Fourier weight is  $(1 + \xi)^k$  and a derivative loses one power in  $k$ . Hence the regularisation in  $k$  loses regularity in  $l$ .

## Sobolev regularity

Want to extend the stability result to Sobolev regularity.

### Problem

The Fourier weight is  $(1 + \xi)^k$  and a derivative loses one power in  $k$ .  
Hence the regularisation in  $k$  loses regularity in  $l$ .

**Cannot** control the nonlinearity as before.

## Sobolev regularity

Want to extend the stability result to Sobolev regularity.

### Problem

The Fourier weight is  $(1 + \xi)^k$  and a derivative loses one power in  $k$ .  
Hence the regularisation in  $k$  loses regularity in  $l$ .

**Cannot** control the nonlinearity as before.

### Solution

Adapt the splitting and perturb the Volterra equation.

Finally

Thank you for listening!