

Growth and Singularity in 2D Fluids

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Euler equations in 2D

The (incompressible) Euler equations are

$$\begin{aligned}u_t + (u \cdot \nabla)u + \nabla p &= 0 \\ \nabla \cdot u &= 0\end{aligned}$$

on $D \times (0, T)$ for some domain $D \subseteq \mathbb{R}^d$ and time $T \leq \infty$, with

$$u \cdot n = 0$$

on $\partial D \times (0, T)$ (no-flow boundary condition) and given $u(\cdot, 0)$.

In 2D, their vorticity form is the active scalar equation

$$\omega_t + u \cdot \nabla \omega = 0$$

with vorticity $\omega := \nabla \times u = -(u_1)_{x_2} + (u_2)_{x_1} \in \mathbb{R}$ and

$$u = \nabla^\perp \Delta^{-1} \omega$$

Here Δ is the Dirichlet Laplacian (no-flow boundary condition).

Growth of solutions to the 2D Euler equations

Solutions of any transport equation

$$\omega_t + \mathbf{u} \cdot \nabla \omega = 0$$

are uniformly bounded, so blow-up might only be possible in the derivatives of ω (loss of regularity).

- Wolibner (1933) and Hölder (1933) showed that solutions remain regular, with the double-exponential bound

$$\|\nabla \omega(\cdot, t)\|_{L^\infty} \leq C e^{e^{Ct}}$$

- Examples with unbounded (up to super-linear) growth by Yudovich (1974), Nadirashvili (1991), Denissov (2009).
- Kiselev-Šverák (2014) proved existence of solutions on a disc with double-exponential growth (on the boundary).
- Z. (2015) proved existence of at least exponential growth for $\omega(\cdot, 0) \in C^{1,1-}(\mathbb{T}^2) \cap C^\infty(\mathbb{T}^2 \setminus \{0\})$ (hence $\partial D = \emptyset$). Double-exponential growth on \mathbb{R}^2 and \mathbb{T}^2 is still open.
- Kiselev-Z. (2015) showed finite time blow-up on a domain with (two) singular points.

SQG and modified SQG equations

Double-exponential (i.e., fast) growth for the 2D Euler equations suggests that they could be **critical** in the sense that finite time blow-up could happen for more singular models. Particularly interesting is the **surface quasi-geostrophic (SQG) equation**

$$\begin{aligned}\omega_t + \mathbf{u} \cdot \nabla \omega &= 0 \\ \mathbf{u} &= -\nabla^\perp (-\Delta)^{-1/2} \omega\end{aligned}$$

It is **used in atmospheric science models** and was first rigorously studied by Constantin-Majda-Tabak (1994).

2D Euler and SQG are extremal members of the natural family

$$\begin{aligned}\omega_t + \mathbf{u} \cdot \nabla \omega &= 0 \\ \mathbf{u} &= -\nabla^\perp (-\Delta)^{-1+\alpha} \omega\end{aligned}$$

of **modified SQG (m-SQG) equations**, with parameter $\alpha \in [0, \frac{1}{2}]$.

The regularity/blow-up question remains open for all $\alpha > 0$.

Patch solutions

I will talk about the corresponding **patch problem** (Bertozzi, Chemin, Constantin, Córdoba, Denissov, Depauw, Gancedo, Rodrigo, Yudovich,...) **on the half-plane** $D = \mathbb{R} \times \mathbb{R}^+$. Here

$$\omega(\cdot, t) = \sum_{n=1}^N \theta_n \chi_{\Omega_n(t)}$$

with $\theta_n \in \mathbb{R} \setminus \{0\}$, and each patch $\Omega_n(t) \subseteq D$ is a bounded open set **advected** by $u = -\nabla^\perp(-\Delta)^{-1+\alpha}\omega$ (see later). For the half-plane D , this is (with $\bar{y} = (y_1, -y_2)$) and some $c_\alpha > 0$)

$$u(x, t) = -c_\alpha \int_D \left(\frac{(x - y)^\perp}{|x - y|^{2+2\alpha}} - \frac{(x - \bar{y})^\perp}{|x - \bar{y}|^{2+2\alpha}} \right) \omega(y, t) dy$$

We require patch-like initial data with some regularity:

- **Patches do not touch each other or themselves:**
 - $\overline{\Omega_n(0)} \cap \overline{\Omega_m(0)} = \emptyset$ for $n \neq m$
 - each $\partial\Omega_n(0)$ is a simple closed curve
- **All $\partial\Omega_n(0)$ have certain prescribed regularity.**

Blow-up happens if one of these fails at some time $t > 0$.

Global regularity of $C^{1,\gamma}$ Euler patches on $\mathbb{R} \times \mathbb{R}^+$

Theorem (Kiselev-Ryzhik-Yao-Z., 2015)

Let $\alpha = 0$ and $\gamma \in (0, 1]$. Then for each $C^{1,\gamma}$ patch-like initial data $\omega(\cdot, 0)$, there *exists a unique global* $C^{1,\gamma}$ patch solution ω .

- The same whole-plane result for a single patch was proved by Chemin (1993). Our proof is motivated by an alternative approach by Bertozzi-Constantin (1993).
- Specifically, each patch boundary is the zero-level set of a function which is advected by u . The rates of change of their $C^{1,\gamma}$ norms, of their gradients on their zero-level sets, and of the distances of their zero-level sets are controlled.
- Previously Depauw (1999) proved local regularity on the half-plane (and global if patches do not touch ∂D initially).
- A result of Dutrifoy (2003) implies global existence in $C^{1,s}$ for some $s < \gamma$.

Blow-up of H^3 patches on $\mathbb{R} \times \mathbb{R}^+$ for small $\alpha > 0$

Theorem (Kiselev-Yao-Z., 2015)

Let $\alpha \in (0, \frac{1}{24})$. Then for each H^3 patch-like initial data $\omega(\cdot, 0)$, there *exists a unique local H^3 patch solution* ω .

Moreover, if the maximal time T_ω of existence of ω is finite, then at T_ω either two patches touch, or a patch boundary touches itself, or a patch boundary loses H^3 regularity (i.e., *blow-up*).

Local existence on the *whole plane* was proved for $\alpha \in (0, \frac{1}{2})$ by Gancedo (2008). We can prove uniqueness and the last claim.

Theorem (Kiselev-Ryzhik-Yao-Z., 2015)

Let $\alpha \in (0, \frac{1}{24})$. Then there are H^3 patch-like initial data $\omega(\cdot, 0)$ for which the solution ω *blows up in finite time* (i.e., $T_\omega < \infty$).

To the best of our knowledge, this is the *first rigorous result proving finite time blow-up* in this type of fluid dynamics models.

Definition of patch solutions

In the Euler case one usually requires that $\Phi_t : \bar{D} \rightarrow \bar{D}$ given by

$$\frac{d}{dt}\Phi_t(x) = u(\Phi_t(x), t) \quad \text{and} \quad \Phi_0(x) = x$$

preserves each patch: $\Phi_t(\Omega_n(0)) = \Omega_n(t)$ for each $t \in (0, T)$.
However, the map Φ_t need not be uniquely defined for $\alpha > 0$.

Definition

A **patch-like** (i.e., no touches of patches at any $t \in [0, T)$ plus continuity of each $\partial\Omega_n(t)$ in time w.r.t Hausdorff distance)

$$\omega(\cdot, t) = \sum_{n=1}^N \theta_n \chi_{\Omega_n(t)}$$

is a **patch solution to m-SQG** on $[0, T)$ if for each t, n we have

$$\lim_{h \rightarrow 0} \frac{d_H\left(\partial\Omega_n(t+h), X_{u(\cdot, t)}^h[\partial\Omega_n(t)]\right)}{h} = 0,$$

with d_H Hausdorff distance and $X_U^h[A] = \{x + hu(x) \mid x \in A\}$.

Properties of patch solutions

Denote $\Omega(t) = \bigcup_n \Omega_n(t)$. The definition shows that:

- $\partial\Omega(t)$ is **moving with velocity $u(x, t)$** at $x \in \partial\Omega(t)$.
- Patch solutions to m-SQG are also **weak solutions** (and weak solutions with C^1 boundaries which move with some continuous velocity are patch solutions).
- In the Euler case it is equivalent to the definition via Φ .
- It is also essentially equivalent to the definition via Φ in the case of H^3 patch solutions to m-SQG with $\alpha < \frac{1}{4}$ [KYZ].
- In fact, $\Phi_t(x)$ is uniquely defined for $x \in \overline{D} \setminus \partial\Omega(0)$, and

$$\Phi_t : \Omega_n(0) \rightarrow \Omega_n(t) \quad \text{and} \quad \Phi_t : [\overline{D} \setminus \overline{\Omega(0)}] \rightarrow [\overline{D} \setminus \overline{\Omega(t)}].$$

Also, these maps are **measure preserving bijections** and we have $\Phi_t(\partial\Omega_n(0)) = \partial\Omega_n(t)$ in an appropriate sense.

- This uses that the **normal component of u** (w.r.t. $\partial\Omega(t)$) is **Lipschitz in the normal direction** if $\alpha < \frac{1}{4}$.

Local H^3 regularity: The contour equation

For simplicity assume a single patch. Parametrize $\partial\Omega(t)$ by $z(\cdot, t) \in H^3(\mathbb{T})$. Then for any $x = z(\xi, t) \in \partial\Omega(t)$ we obtain

$$u(x, t) = \frac{c_\alpha \theta}{2\alpha} \sum_{i=1}^2 \int_{\mathbb{T}} \frac{-\partial_\xi z^i(\xi - \eta, t)}{|z(\xi, t) - z^i(\xi - \eta, t)|^{2\alpha}} d\eta$$

with

$$z^1(\xi, t) := z(\xi, t) \quad \text{and} \quad z^2(\xi, t) := \bar{z}(\xi, t)$$

Next add a multiple of the tangent vector $\partial_\xi z(\xi, t)$ so that the integrand becomes more regular, and get the contour equation

$$\partial_t z(\xi, t) = \frac{c_\alpha \theta}{2\alpha} \sum_{i=1}^2 \int_{\mathbb{T}} \frac{\partial_\xi z(\xi, t) - \partial_\xi z^i(\xi - \eta, t)}{|z(\xi, t) - z^i(\xi - \eta, t)|^{2\alpha}} d\eta$$

Gancedo proves local regularity for the contour equation in \mathbb{R}^2 (which has only $i = 1$, and also a single patch) for any $\alpha < \frac{1}{2}$.

Local H^3 regularity: Existence of a patch solution

We prove local regularity on $D = \mathbb{R} \times \mathbb{R}^+$ for $\alpha < \frac{1}{24}$, via

$$\frac{d}{dt} \lll z(\cdot, t) \rrr \leq C(\alpha)\theta \lll z(\cdot, t) \rrr^8$$

where $\lll \cdot \rrr = \|z(\cdot, t)\|_{H^3} + \text{inverse Lipschitz norm of } z(\cdot, t)$
(+ distance of patches when $N \geq 2$). Quite a bit more involved...

- The method does not seem to work for Hölder norms.

Limitation on α is essentially due to insufficient bounds on the tangential velocity. Where a patch departs x_1 -axis, tangential velocity generated by its reflection might deform it excessively.

- Most of the proof works for $\alpha < \frac{1}{4}$.

This local **contour solution** z then **yields a patch solution** ω .

Local H^3 regularity: Independence of parametrization

Proving uniqueness via some version of Gronwall difficult:

$$|u(x) - \tilde{u}(x)| \lesssim d_H(\partial\Omega, \partial\tilde{\Omega})^{1-2\alpha}.$$

- Gronwall does apply to $\|z - \tilde{z}\|_{L^2}$ but z, \tilde{z} might not exist.

First step towards uniqueness is showing independence of the “contour” patch from parametrization of $\partial\Omega(0)$.

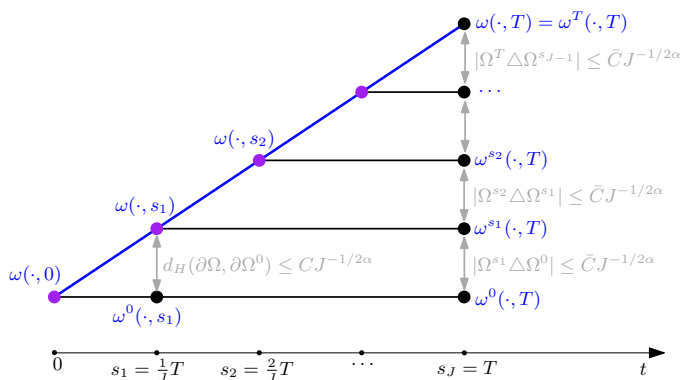
- Regularize:

$$u^\varepsilon(x, t) = -c_\alpha \int_D \left(\frac{(x - y)^\perp}{(|x - y|^2 + \varepsilon^2)^{1+\alpha}} - \frac{(x - \bar{y})^\perp}{(|x - \bar{y}|^2 + \varepsilon^2)^{1+\alpha}} \right) \omega(y, t) dy$$

- Show uniqueness of patch solution ω_ε (e.g., via Gronwall). Then any contour solutions $z_\varepsilon, \tilde{z}_\varepsilon$ which parametrize the same initial patch must yield the same ω_ε .
- Show $z_\varepsilon \rightarrow z$ if they have the same initial parametrization. Similarly $\tilde{z}_\varepsilon \rightarrow \tilde{z}$, hence z, \tilde{z} must yield the same ω .

Local H^3 regularity: Uniqueness of the patch solution

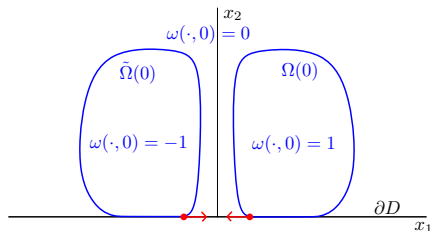
Let ω be any patch solution and ω^s the “contour” patch solution with $\omega^s(\cdot, s) = \omega(\cdot, s)$ (ω^s is unique). For small $T > 0$ and $J \in \mathbb{N}$:



Successive estimation of the rates of change of $d_H(\partial\Omega, \partial\tilde{\Omega})$ and $\|z - \tilde{z}\|_{L^2}$ and telescoping give $|\Omega(T) \Delta \Omega^0(T)| \lesssim J^{1-1/2\alpha}$. Then take $J \rightarrow \infty$ and get $\Omega = \Omega^0$ on $[0, T]$.

Finite time blow-up in H^3 : Initial data and symmetry

Our initial data will be made of two patches and **odd in x_1** .



$$\omega(\cdot, 0) = \chi_{\Omega(0)} - \chi_{\tilde{\Omega}(0)}$$

Then local uniqueness shows that **before blow-up** we have

$$\omega(\cdot, t) = \chi_{\Omega(t)} - \chi_{\tilde{\Omega}(t)}$$

with $\Omega(t) \subseteq D^+ = (\mathbb{R}^+)^2$ and $\tilde{y} = (-y_1, y_2)$. Then (let $c_\alpha = 1$)

$$u(x, t) = - \int_{\Omega(t)} H(x, y) dy$$

$$H(x, y) = \frac{(x - y)^\perp}{|x - y|^{2+2\alpha}} - \frac{(x - \bar{y})^\perp}{|x - \bar{y}|^{2+2\alpha}} - \frac{(x - \tilde{y})^\perp}{|x - \tilde{y}|^{2+2\alpha}} + \frac{(x + y)^\perp}{|x + y|^{2+2\alpha}}$$

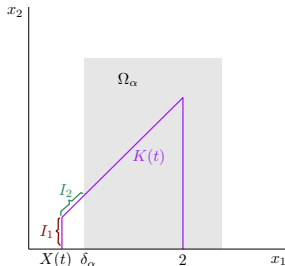
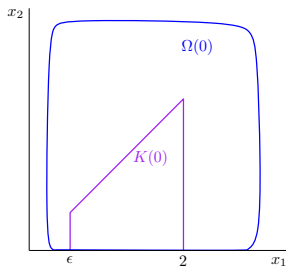
Finite time blow-up in H^3 : A barrier argument

Goal: show that if $\Omega(0) \supseteq [\varepsilon, 3] \times [0, 3]$ and $\varepsilon > 0$ is small, then

$$\Omega(t) \supseteq K(t) = \{X(t) < x_1 < 2\} \cap \{0 < x_2 < x_1\}$$

until blow-up, where $X(0) = \varepsilon$ and $X'(t) = -\frac{1}{100\alpha} X(t)^{1-2\alpha}$.

This gives **blow-up** because $X(50\varepsilon^{2\alpha}) = 0$.



If $t < 50\varepsilon^{2\alpha}$ is the first time with $\overline{D^+ \setminus \Omega(t)} \cap \overline{K(t)} \neq \emptyset$, then by

$$\|u\|_{L^\infty} \leq C_1 \|\omega(\cdot, 0)\|_{L^\infty} + C_2 \|\omega(\cdot, 0)\|_{L^1} \leq C$$

the touch can only be on $I_1 \cup I_2$ (since $\Omega(t) \supseteq \Omega_\alpha$ by ε small).
Also uses that the patch cannot separate from the x_1 -axis...

Finite time blow-up in H^3 : Estimates on the flow

We have $u_1(x, t) = - \int_{\Omega(t)} H_1(x, y) dy$, where

$$H_1(x, y) = \frac{y_2 - x_2}{|x - y|^{2+2\alpha}} - \frac{y_2 - x_2}{|x - \tilde{y}|^{2+2\alpha}} + \frac{y_2 + x_2}{|x - \bar{y}|^{2+2\alpha}} - \frac{y_2 + x_2}{|x + y|^{2+2\alpha}}$$

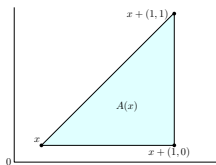
Then $|x - \bar{y}| \leq |x + y|$ on $\Omega(t) \subseteq D^+$ gives

$$u_1(x, t) \leq - \int_{\Omega(t)} \underbrace{\left(\frac{y_2 - x_2}{|x - y|^{2+2\alpha}} - \frac{y_2 - x_2}{|x - \tilde{y}|^{2+2\alpha}} \right)}_{G(x, y)} dy$$

From $K(t) \subseteq \Omega(t)$ we have for $x \in K(t) \cap \{x_1 \leq 1\}$

$$u_1(x, t) \leq \int_{\mathbb{R} \times (0, x_2)} |G(x, y)| dy - \int_{A(x)} G(x, y) dy$$

because $\text{sgn}(G(x, y)) = \text{sgn}(y_2 - x_2)$.



Small α is crucial for $A(x)$ to compensate limited control near x .
Blow-up may be easier to prove in slightly super-critical models.

Finite time blow-up in H^3 : Conclusion of the proof

A computation and cancellations yield for $x_2 \leq x_1 \leq \delta_\alpha (> 0)$

$$\int_{\mathbb{R} \times (0, x_2)} |G(x, y)| dy \leq \frac{1}{\alpha} \left(\frac{1}{1-2\alpha} - 2^{-\alpha} \right) x_1^{1-2\alpha}$$
$$- \int_{A(x)} G(x, y) dy \leq -\frac{1}{\alpha} \left(\frac{1}{6 \cdot 20^\alpha} \right) x_1^{1-2\alpha}$$

and we get for **small** α and $x \in I_1 \cup I_2$ (using $x_1 \geq X(t)$)

$$u_1(x, t) \leq -\frac{1}{50\alpha} x_1^{1-2\alpha} < -\frac{1}{100\alpha} X(t)^{1-2\alpha} = X'(t)$$

So **touch** cannot happen on I_1 .

Similarly, for **small** α and $x \in I_2$

$$u_2(x, t) \geq \frac{1}{50\alpha} x_2^{1-2\alpha} > 0$$

so **touch** cannot happen on I_2 .

