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# Quantum, kinetic and hydrodynamic descriptions on spin transfer torque

#### Xu Yang

#### Department of Mathematics University of California, Santa Barbara

#### Joint work with Jingrun Chen and Carlos J. García-Cervera (UCSB)

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Motivation

Moment system

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- 2 STT model by moment system
- Numerical comparison with Diffusion model
- 4 Formal connections between models at different level
- 5 Conclusion and future works

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#### Application<sup>1</sup>



- Magnetic recording devices: audio, video.
- Computer storage: floppy disks, hard disks.
- Magnetic Memory: Magnetoresistance Random Access Memory (MRAM).

Methodology for detecting the orientation <sup>2</sup>



Julliere's model: Constant tunneling

matrix

$$\mathsf{TMR} \equiv \frac{\mathsf{G}_{\mathsf{AP}} - \mathsf{G}_{\mathsf{P}}}{\mathsf{G}_{\mathsf{AP}}} = \frac{2\mathsf{P}_{\mathsf{L}}\mathsf{P}_{\mathsf{R}}}{1 - \mathsf{P}_{\mathsf{L}}\mathsf{P}_{\mathsf{R}}}$$

$$P_L = \frac{n_L^{\scriptscriptstyle \perp} - n_L^{\scriptscriptstyle \perp}}{n_L^{\scriptscriptstyle \perp} + n_L^{\scriptscriptstyle \perp}} \qquad P_R = \frac{n_R^{\scriptscriptstyle \perp} - n_R^{\scriptscriptstyle \perp}}{n_R^{\scriptscriptstyle \perp} + n_R^{\scriptscriptstyle \perp}}$$

<sup>1</sup>Science@Berkeley Lab: The Current Spin on Spintronics <sup>2</sup>http://ducthe.wordpress.com/category/spintronics/=>

# The key is to control the relative orientation

• Spin transfer torque (STT) <sup>3</sup>



- Two layers of different thickness: different switching fields.
- The thin film is switched, and the resistance measured.
- Literature and references
  - Proposed independently by Berger (1996) and Slonczewski (1996).
  - Theoretical and experimental studies: Bazaliy et al., 1998; Tsoi et al., 1998; Myers et al., 1999; Sun, 2000; Waintal et al. 2000; Stiles and Zangwill, 2002; Zhang et al. 2002; Zutic et al. 2004 (Review); ...

<sup>&</sup>lt;sup>3</sup>http://www.wpi-aimr.tohoku.ac.jp/miyazaki\_labo/spintorque.htm 🚛 🛌 🗐 🔍 🖓

## Model equations – Magnetization

• Landau-Lifshitz-Gilbert (LLG) equation

$$\frac{\partial \boldsymbol{M}}{\partial t} = -\gamma \, \boldsymbol{M} \times (\mathbf{h}_{\boldsymbol{e}} + \boldsymbol{c}\mathbf{s}) + \alpha \boldsymbol{M} \times \frac{\partial \boldsymbol{M}}{\partial t},$$

where the first term is precession, and the second is Gilbert damping term.

• The effective field **h**<sub>e</sub> is defined as

$$\mathbf{h}_{e}=-\frac{2K_{u}}{M_{s}}\left(m_{2}\mathbf{e}_{2}+m_{3}\mathbf{e}_{3}\right)+\frac{2C_{ex}}{M_{s}}\Delta\boldsymbol{M}+\boldsymbol{M}\boldsymbol{u}_{0}\left(\mathbf{h}_{s}+\mathbf{h}_{0}\right),$$

 The stray field, h<sub>s</sub> = −∇u is obtained by solving the magnetostatic equation:

$$\Delta u = \operatorname{div} \boldsymbol{M}, \quad \boldsymbol{x} \in \Omega, \quad \Delta u = 0, \quad \boldsymbol{x} \in \overline{\Omega}^{c},$$

with jump boundary conditions

$$[\boldsymbol{u}]_{\partial\Omega} = \mathbf{0}, \quad \left[\frac{\partial \boldsymbol{u}}{\partial\nu}\right]_{\partial\Omega} = -\boldsymbol{M}\cdot\boldsymbol{\nu}.$$

## Model equations – Spin<sup>4</sup>

• Quantum (Schrödinger equation)

$$i\hbar\frac{\partial\psi}{\partial t} = \left(\left(-\frac{\hbar^2}{2m}\nabla_{\boldsymbol{x}}^2 + V(\boldsymbol{x})\right)\widehat{\boldsymbol{I}} + \frac{\mu_B}{2}\widehat{\boldsymbol{\sigma}}\cdot\boldsymbol{M}(\boldsymbol{x},t)\right)\psi.$$

• Kinetic (Boltzmann equation)

$$\partial_t \boldsymbol{W}(\boldsymbol{x}, \boldsymbol{v}, t) + \boldsymbol{v} \cdot \nabla_{\boldsymbol{x}} \boldsymbol{W}(\boldsymbol{x}, \boldsymbol{v}, t) - \frac{\boldsymbol{e}}{m} \boldsymbol{E} \cdot \nabla_{\boldsymbol{v}} \boldsymbol{W}(\boldsymbol{x}, \boldsymbol{v}, t) \\ + \frac{\mathrm{i}}{2\hbar} [\mu_B \widehat{\boldsymbol{\sigma}} \cdot \boldsymbol{M}(\boldsymbol{x}, t), \boldsymbol{W}(\boldsymbol{x}, \boldsymbol{v}, t)] = -\frac{\boldsymbol{W} - \bar{\boldsymbol{W}}}{\tau} - \frac{2}{\tau_{\mathrm{sf}}} (\bar{\boldsymbol{W}} - \frac{\widehat{\boldsymbol{I}}}{2} \mathrm{Tr} \bar{\boldsymbol{W}})$$

• Hydrodynamic (Diffusion equation)

$$\begin{aligned} \frac{\partial \mathbf{s}}{\partial t} &= -\operatorname{div} \, \mathbf{J}_{s} - 2D_{0}(\mathbf{x}) \frac{\mathbf{s}}{\lambda_{sf}^{2}} - 2D_{0}(\mathbf{x}) \frac{\mathbf{s} \times \mathbf{M}}{\lambda_{J}^{2}}, \\ \mathbf{J}_{s} &= \frac{\beta \mu_{B}}{e} \mathbf{M} \otimes \mathbf{J}_{e} - 2D_{0}(\mathbf{x}) \left[ \nabla \mathbf{s} - \beta \beta' \mathbf{M} \otimes (\nabla \mathbf{s} \cdot \mathbf{M}) \right]. \end{aligned}$$

<sup>4</sup>Piechon and Thiaville, PRB 2007, Gaspari, PR 1966, Zhang, Levy and Fert, PRL 2002 Motivation

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## Ambitious goals

- Set up the connections of the models at different levels of physics.
- Develop new models based on moment system.
- Design efficient numerical algorithms that can capture physical details at different scales.

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# Spin-orbital decomposition

Define 
$$\boldsymbol{\sigma} = \boldsymbol{\sigma}_{x}\hat{\boldsymbol{i}} + \boldsymbol{\sigma}_{y}\hat{\boldsymbol{j}} + \boldsymbol{\sigma}_{z}\hat{\boldsymbol{k}}$$
, where  
 $\boldsymbol{\sigma}_{x} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \boldsymbol{\sigma}_{y} = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \boldsymbol{\sigma}_{z} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$ 

 $\boldsymbol{W} = \boldsymbol{w}\boldsymbol{I} + \widehat{\boldsymbol{\sigma}} \cdot \boldsymbol{w},$ 

where w is the orbital part and w is the spin part.

Macroscopic quantities

charge density  $n(\mathbf{x}, t) = \int_{\mathbb{R}^3} \operatorname{Tr} \mathbf{W} d\mathbf{v}$ , charge current density  $\mathbf{j}_n(\mathbf{x}, t) = \int_{\mathbb{R}^3} \mathbf{v} \operatorname{Tr}(\mathbf{W}) d\mathbf{v}$ , spin density  $\mathbf{m}(\mathbf{x}, t) = \int_{\mathbb{R}^3} \operatorname{Tr}(\widehat{\sigma} \mathbf{W}) d\mathbf{v}$ , spin current density  $\mathbf{j}_m(\mathbf{x}, t) = \int_{\mathbb{R}^3} \mathbf{v} \otimes \operatorname{Tr}(\widehat{\sigma} \mathbf{W}) d\mathbf{v}$ .

#### Equations for *w* and *w*

$$\begin{aligned} \partial_t \boldsymbol{w} + \boldsymbol{v} \cdot \nabla_{\boldsymbol{x}} \boldsymbol{w} &- \frac{\boldsymbol{e}}{m} \boldsymbol{E} \cdot \nabla_{\boldsymbol{v}} \boldsymbol{w} = -\frac{\boldsymbol{w} - \bar{\boldsymbol{w}}}{\tau}, \\ \partial_t (\widehat{\boldsymbol{\sigma}} \cdot \boldsymbol{w}) + \boldsymbol{v} \cdot \nabla_{\boldsymbol{x}} (\widehat{\boldsymbol{\sigma}} \cdot \boldsymbol{w}) - \frac{\boldsymbol{e}}{m} \boldsymbol{E} \cdot \nabla_{\boldsymbol{v}} (\widehat{\boldsymbol{\sigma}} \cdot \boldsymbol{w}) - \frac{\mu_B}{\hbar} \widehat{\boldsymbol{\sigma}} \cdot (\boldsymbol{M} \times \boldsymbol{w}) \\ &= -\frac{(\widehat{\boldsymbol{\sigma}} \cdot \boldsymbol{w}) - \overline{(\widehat{\boldsymbol{\sigma}} \cdot \boldsymbol{w})}}{\tau} - \frac{2}{\tau_{sf}} (\widehat{\boldsymbol{\sigma}} \cdot \boldsymbol{w}), \end{aligned}$$

where we have used the fact

$$\frac{\mathrm{i}}{2\hbar}[\mu_B\widehat{\boldsymbol{\sigma}}\cdot\boldsymbol{M}(\boldsymbol{x},t),\boldsymbol{W}(\boldsymbol{x},\boldsymbol{v},t)]=-\frac{\mu_B}{\hbar}\widehat{\boldsymbol{\sigma}}\cdot(\boldsymbol{M}\times\boldsymbol{w}).$$

Equations live in 6-dimension, which creates numerical difficulties.

Alternative: to develop and solve the moment system.

Numerics

#### Hierarchical moment system

$$\begin{split} \partial_t n(\mathbf{x},t) + \nabla \cdot \mathbf{j}_n(\mathbf{x},t) &= 0, \\ \partial_t \mathbf{j}_n(\mathbf{x},t) + \int_{\mathbb{R}^3} (\mathbf{v} \otimes \mathbf{v}) \cdot \nabla \mathbf{w}(\mathbf{x},\mathbf{v},t) \, \mathrm{d}\mathbf{v} + \frac{\mathbf{e}}{m} \mathbf{E} n(\mathbf{x},t) = -\frac{\mathbf{j}_n(\mathbf{x},t)}{\tau}, \\ \partial_t \mathbf{m}(\mathbf{x},t) + \nabla \cdot \mathbf{j}_m(\mathbf{x},t) - \frac{\mu_B}{\hbar} \mathbf{M} \times \mathbf{m} &= -\frac{\mathbf{m}(\mathbf{x},t)}{\tau_{\mathrm{sf}}}, \\ \partial_t \mathbf{j}_m(\mathbf{x},t) + \int_{\mathbb{R}^3} (\mathbf{v} \otimes \mathbf{v}) \cdot \nabla \mathbf{w}(\mathbf{x},\mathbf{v},t) \, \mathrm{d}\mathbf{v} + \frac{\mathbf{e}}{m} \mathbf{E} \otimes \mathbf{m}(\mathbf{x},t) \\ &- \frac{\mu_B}{\hbar} \varepsilon_{jkl} \mathbf{M}_k(\mathbf{j}_m)_{il}(\mathbf{x},t) = -\frac{\mathbf{j}_m(\mathbf{x},t)}{\tau}. \end{split}$$

Unclosed! Need equations of state for the second order moments.

## Closure assumption

#### • Assumption I.

 $w(\boldsymbol{x}, \boldsymbol{v}, t) \approx \beta_0 n(\boldsymbol{x}, t) + \beta'_0 \boldsymbol{M} \cdot \boldsymbol{m}(\boldsymbol{x}, t) + \beta_1 \cdot \boldsymbol{v} n_1(\boldsymbol{x}, t) + \beta'_1 \boldsymbol{v} \cdot \boldsymbol{m}_1(\boldsymbol{x}, t),$ 

then the charge current equation becomes

$$\partial_t \boldsymbol{j}_n(\boldsymbol{x},t) + \beta_0 \overline{\boldsymbol{v}^2} \nabla_{\boldsymbol{x}} \boldsymbol{n}(\boldsymbol{x},t) + \beta'_0 \overline{\boldsymbol{v}^2} \nabla_{\boldsymbol{x}} \boldsymbol{m}(\boldsymbol{x},t) \boldsymbol{M} \\ + \frac{e}{m} \boldsymbol{E} \boldsymbol{n}(\boldsymbol{x},t) = -\frac{\boldsymbol{j}_n(\boldsymbol{x},t)}{\tau}.$$

Assumption II.

 $\boldsymbol{w}(\boldsymbol{x},\boldsymbol{v},t) \approx \beta \boldsymbol{M} \boldsymbol{n}(\boldsymbol{x},t) + \beta' \boldsymbol{m}(\boldsymbol{x},t) + \beta_2 \boldsymbol{v} \boldsymbol{n}_1(\boldsymbol{x},t) + \beta'_2 \boldsymbol{v}(\boldsymbol{M} \cdot \boldsymbol{m}_1(\boldsymbol{x},t)),$ 

then the spin current equation becomes

$$\partial_t \boldsymbol{j}_{\boldsymbol{m}}(\boldsymbol{x},t) + \beta \overline{\boldsymbol{v}^2} \nabla_{\boldsymbol{x}} \boldsymbol{n}(\boldsymbol{x},t) \otimes \boldsymbol{M} + \beta' \overline{\boldsymbol{v}^2} \nabla_{\boldsymbol{x}} \boldsymbol{m}(\boldsymbol{x},t) \\ + \frac{\boldsymbol{e}}{\boldsymbol{m}} \boldsymbol{E} \otimes \boldsymbol{m}(\boldsymbol{x},t) - \frac{\mu_B}{\hbar} \varepsilon_{jkl} \boldsymbol{M}_k(\boldsymbol{j}_{\boldsymbol{m}})_{il}(\boldsymbol{x},t) = -\frac{\boldsymbol{j}_{\boldsymbol{m}}(\boldsymbol{x},t)}{\tau}.$$

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## Motivation for the assumption

- Introduce the spin-orbital coupling in the moment system.
- Quasistatic approximation for the current equations yields

$$\boldsymbol{j}_{n}(\boldsymbol{x},t) = -\frac{\boldsymbol{e}}{m} \tau \boldsymbol{E} \boldsymbol{n}(\boldsymbol{x},t) - \beta_{0} \overline{\boldsymbol{v}^{2}} \tau \nabla_{\boldsymbol{x}} \boldsymbol{n}(\boldsymbol{x},t) \\ - \beta_{0}' \overline{\boldsymbol{v}^{2}} \tau \nabla_{\boldsymbol{x}} \boldsymbol{m}(\boldsymbol{x},t) \boldsymbol{M},$$

$$\begin{aligned} \boldsymbol{j}_{\boldsymbol{m}}(\boldsymbol{x},t) &= -\frac{\boldsymbol{e}}{\boldsymbol{m}} \tau \boldsymbol{E} \otimes \boldsymbol{m}(\boldsymbol{x},t) - \beta \overline{\boldsymbol{v}^{2}} \tau \nabla_{\boldsymbol{x}} \boldsymbol{n}(\boldsymbol{x},t) \otimes \boldsymbol{M} \\ &+ \frac{\mu_{\boldsymbol{B}}}{\hbar} \varepsilon_{\boldsymbol{j}\boldsymbol{k}\boldsymbol{l}} \boldsymbol{M}_{\boldsymbol{k}}(\boldsymbol{j}_{\boldsymbol{m}})_{\boldsymbol{i}\boldsymbol{l}}(\boldsymbol{x},t) - \beta' \overline{\boldsymbol{v}^{2}} \tau \nabla_{\boldsymbol{x}} \boldsymbol{m}(\boldsymbol{x},t). \end{aligned}$$

This is consistent with the linear response relation used in Zhang, Levy and Fert (PRL 2002) except the term in red.

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#### Experiment setup



Figure: Device. From Bottom to Top: FM1 ( $128 \times 64 \times 200$ nm<sup>3</sup>); Spacer ( $128 \times 64 \times 20$ nm<sup>3</sup>); FM2 ( $128 \times 64 \times 60$ nm<sup>3</sup>). *j<sub>n</sub>* is applied from FM1 to FM2. Numerics

Conclusion

#### Several locally stable states



Figure: State 1

Numerics

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Conclusion

#### Several locally stable states



Figure: State 2

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Conclusion

#### Several locally stable states



Figure: State 3

Numerics

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#### Comparison results

$$\boldsymbol{j_m} = \frac{\beta\mu_B}{e} \boldsymbol{j_n} \otimes \boldsymbol{M} - 2D_0(\boldsymbol{x}) [\nabla \boldsymbol{m} - \beta\beta' (\nabla \boldsymbol{m} \cdot \boldsymbol{M}) \otimes \boldsymbol{M}]$$
$$\boldsymbol{j_m} \boldsymbol{A}(\boldsymbol{M}) = \frac{\beta\mu_B}{e} \boldsymbol{j_n} \otimes \boldsymbol{M} - 2D_0(\boldsymbol{x}) [\nabla \boldsymbol{m} - \beta\beta' (\nabla \boldsymbol{m} \cdot \boldsymbol{M}) \otimes \boldsymbol{M}]$$

where

$$m{A}(m{M}) = \left(egin{array}{cccc} 1 & -M_3 & M_2 \ M_3 & 1 & -M_1 \ -M_2 & M_1 & 1 \end{array}
ight)$$

with eigenvalues 1,  $1 \pm i$ .

Initial states: random in FM1 and uniform in FM2

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Motivation	Moment system	Numerics	Model connections	Conclus
		Cont'd		

Model	S1	$S1 \rightarrow S2$	S1→S3	S1 $\rightarrow$ S2
Diffusion	<b>≤ 7.4</b>	$7.5 \sim 9.9$	10.0	≥ 10.1
Moment	≤ <b>9</b> .0	$9.1 \sim 9.6$	9.7 ~ 10.1	≥ 10.2

Table: Critical applied current  $j_n$  for switching (unit: 10<sup>10</sup>As)

A larger admissible window for effective switching by moment model

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Motivation	Moment system	Numerics	Model connections	Conclusion
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## From moment system to diffusion<sup>5</sup>

 For a clearer illustration, forget the coupling term for the current moment, and rescale the moment system as follows,

$$\varepsilon \partial_t \boldsymbol{m}(\boldsymbol{x}, t) + \partial_{\boldsymbol{x}} \boldsymbol{j}_{\boldsymbol{m}}(\boldsymbol{x}, t) - \varepsilon \boldsymbol{M} \times \boldsymbol{m} = -\varepsilon \boldsymbol{m}(\boldsymbol{x}, t),$$
  
$$\varepsilon \partial_t \boldsymbol{j}_{\boldsymbol{m}}(\boldsymbol{x}, t) + \overline{\boldsymbol{v}^2} \partial_{\boldsymbol{x}} \boldsymbol{m}(\boldsymbol{x}, t) - \boldsymbol{E} \boldsymbol{m}(\boldsymbol{x}, t) - \frac{\boldsymbol{M} \times \boldsymbol{j}_{\boldsymbol{m}}(\boldsymbol{x}, t)}{\varepsilon} = -\frac{\boldsymbol{j}_{\boldsymbol{m}}(\boldsymbol{x}, t)}{\varepsilon}$$

Apply the following asymptotic expansion

$$\boldsymbol{m} = \boldsymbol{m}^0 + \varepsilon \boldsymbol{m}^1 + \varepsilon^2 \boldsymbol{m}^2 + \cdots ,$$
$$\boldsymbol{j}_m = \boldsymbol{j}_m^0 + \varepsilon \boldsymbol{j}_m^1 + \varepsilon^2 \boldsymbol{j}_m + \cdots .$$

<sup>&</sup>lt;sup>5</sup>A field with very rich literature: Bardos, Golse, Levermore, Degond, Ben Abdallah, Gamba, Jin, ...

To the leading order, we have the diffusion equation,

$$2\partial_t \boldsymbol{m} - (\boldsymbol{M} \cdot \partial_t \boldsymbol{m}) \boldsymbol{M} = \overline{\boldsymbol{v}^2} \partial_{x^2} \boldsymbol{m}(x, t) + \overline{\boldsymbol{v}^2} \boldsymbol{M} \times \partial_{x^2} \boldsymbol{m}(x, t) - \boldsymbol{E} \partial_x \boldsymbol{m}(x, t) - \boldsymbol{E} \boldsymbol{M} \times \partial_x \boldsymbol{m}(x, t) + \boldsymbol{M} \times \boldsymbol{m} - \boldsymbol{m},$$

Assuming *M* is uniform and only nonzero in *z*-direction,

$$\partial_t m^z(x,t) + \overline{v^2} \partial_{xx} m^z(x,t) - E \partial_x m^z(x,t) - Mm^z(x,t) = -m^z(x,t), \partial_t m^{\pm}(x,t) - \frac{1}{1 \mp iM} \overline{v^2} \partial_{xx} m^{\pm}(x,t) + \frac{1}{1 \mp iM} E \partial_x m^{\pm}(x,t) - Mm^{\pm}(x,t) = -m^{\pm}(x,t).$$

This recovers the diffusion model in Zhang, Levy and Fert (PRL 2002) without the coupling term, which can be also included by a similar procedure on the coupling moment system.

## From Schrödinger to Liouville

In physical units,

$$\mathrm{i}\hbar\frac{\partial}{\partial t}\psi(\boldsymbol{x},t)=\widehat{\boldsymbol{H}}(\boldsymbol{x},t)\psi(\boldsymbol{x},t),$$

where

$$\widehat{\boldsymbol{H}}(\boldsymbol{x},t) = \left(-\frac{\hbar^2}{2m}\nabla_{\boldsymbol{x}}^2 + \boldsymbol{V}(\boldsymbol{x})\right)\widehat{\boldsymbol{l}} + \frac{\mu_B}{2}\widehat{\boldsymbol{\sigma}}\cdot\boldsymbol{M}(\boldsymbol{x},t).$$

What is the correct nondimensional regime?  $\hbar \rightarrow \varepsilon$ ?

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Define the Wigner transformation of  $\psi$  as

$$\boldsymbol{W}(\boldsymbol{x},\boldsymbol{v},t) = \frac{m^{3/2}}{(2\pi\hbar)^{3/2}} \int_{\mathbb{R}^3} \psi(\boldsymbol{x} + \frac{\hbar}{2m}\boldsymbol{y},t) \otimes \psi^*(\boldsymbol{x} - \frac{\hbar}{2m}\boldsymbol{y},t) \mathrm{e}^{\mathrm{i}\boldsymbol{v}\cdot\boldsymbol{y}} \,\mathrm{d}\boldsymbol{y}.$$

To the leading order,

$$\partial_t \boldsymbol{W}(\boldsymbol{x}, \boldsymbol{v}, t) + \boldsymbol{v} \cdot \nabla_{\boldsymbol{x}} \boldsymbol{W}(\boldsymbol{x}, \boldsymbol{v}, t) - \frac{\boldsymbol{e}}{m} \boldsymbol{E} \cdot \nabla_{\boldsymbol{v}} \boldsymbol{W}(\boldsymbol{x}, \boldsymbol{v}, t) \\ + \frac{i}{2\hbar} [\mu_B \widehat{\boldsymbol{\sigma}} \cdot \boldsymbol{M}(\boldsymbol{x}, t) \cdot \boldsymbol{W}(\boldsymbol{x}, \boldsymbol{v}, t)] = 0.$$

Compare the order of the last two terms in physical units<sup>6</sup>,

$$\frac{e}{m} \frac{|\boldsymbol{E}|}{|\boldsymbol{\bar{v}}|} \approx \frac{10^{-19} \times 10^5}{10^{-30} \times 5 \times 10^5} \approx 10^{-12} s^{-1},$$
$$\frac{\mu_B}{\hbar} |\boldsymbol{M}| \approx \frac{10^{-23}}{10^{-34}} \times 0.1 = 10^{-12} s^{-1}.$$

<sup>6</sup>Qi and Zhang, PRB 2003

#### Semiclassical regime

Weak spinor term:

$$\mathrm{i}\varepsilon\frac{\partial}{\partial t}\psi(\boldsymbol{x},t) = \left(\left(-\frac{\varepsilon^2}{2}\nabla_{\boldsymbol{x}}^2 + V(\boldsymbol{x})\right)\widehat{\boldsymbol{I}} + \frac{\varepsilon}{2}\widehat{\boldsymbol{\sigma}}\cdot\boldsymbol{M}(\boldsymbol{x},t)\right)\psi(\boldsymbol{x},t).$$

The rescaled Wigner transform:

$$\boldsymbol{W}(\boldsymbol{x},\boldsymbol{v},t) = \frac{1}{(2\pi\varepsilon)^{3/2}} \int_{\mathbb{R}^3} \psi(\boldsymbol{x} + \frac{\varepsilon}{2}\boldsymbol{y},t) \otimes \psi^*(\boldsymbol{x} - \frac{\varepsilon}{2}\boldsymbol{y},t) \mathrm{e}^{\mathrm{i}\boldsymbol{v}\cdot\boldsymbol{y}} \,\mathrm{d}\boldsymbol{y},$$

which leads to the Liouville equation in the leading order,

$$\partial_t \boldsymbol{W}(\boldsymbol{x}, \boldsymbol{v}, t) + \boldsymbol{v} \cdot \nabla_{\boldsymbol{x}} \boldsymbol{W}(\boldsymbol{x}, \boldsymbol{v}, t) - \boldsymbol{E} \cdot \nabla_{\boldsymbol{v}} \boldsymbol{W}(\boldsymbol{x}, \boldsymbol{v}, t) \\ + \frac{1}{2} \big[ \widehat{\boldsymbol{\sigma}} \cdot \boldsymbol{M}(\boldsymbol{x}, t), \boldsymbol{W}(\boldsymbol{x}, \boldsymbol{v}, t) \big] = 0.$$

We still have the collision term missing in the picture.

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#### Summary

- Develop STT model based on moment closure that introduces spin-orbital coupling.
- Numerically study the qualitative difference of moment system model from the diffusion model.
- Preliminary results on the connections of models at different scales.
- Future works
  - Further understand the connections of different models, e.g. the origin of collision term, the modeling accuracy of moment system in the long time and large space regime.
  - Develop multiscale numerical methods, e.g. Heterogeneous Multiscale Method (HMM), Asymptotic Preserving scheme (AP), and domain decomposition method (DD).
  - Simulating STT of magnetic devices in experiments.