

Hydrodynamic flocking model with external potential forcing

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The model

$$\begin{cases} \partial_t \rho + \nabla \cdot (\rho \mathbf{u}) = 0 \\ \partial_t \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u} = \int \phi(\|\mathbf{x} - \mathbf{y}\|) (\mathbf{u}(\mathbf{y}, t) - \mathbf{u}(\mathbf{x}, t)) \rho(\mathbf{y}) d\mathbf{y} - \nabla \Psi(\mathbf{x}) \end{cases}$$

pressureless
Euler equations

Cucker-Smale interaction
(non-local alignment)

external
forcing

- ρ, \mathbf{u} : density and velocity field of a continuum of agents
- ϕ : Cucker-Smale interaction potential
- Ψ : external potential

Motivation

- Particle Cucker-Smale model

$$\begin{cases} \dot{\mathbf{x}}_i = \mathbf{v}_i \\ \dot{\mathbf{v}}_i = \frac{1}{N} \sum_{j \neq i} \phi(\|\mathbf{x}_i - \mathbf{x}_j\|) (\mathbf{v}_j - \mathbf{v}_i) \end{cases} \quad i = 1, \dots, N$$

- **Flocking:** under suitable assumptions on ϕ , there holds

$$\|\mathbf{v}_i(t) - \mathbf{v}_j(t)\| \rightarrow 0, \quad \text{as } t \rightarrow \infty$$

- Pairwise interaction \rightarrow global velocity alignment

Motivation

particle model

$$\begin{cases} \dot{\mathbf{x}}_i = \mathbf{v}_i \\ \dot{\mathbf{v}}_i = \frac{1}{N} \sum_{j \neq i} \phi(\|\mathbf{x}_i - \mathbf{x}_j\|) (\mathbf{v}_j - \mathbf{v}_i) \end{cases} \quad i = 1, \dots, N$$

mean field limit



kinetic model

$$\partial_t f + \mathbf{v} \cdot \nabla_{\mathbf{x}} f + \nabla_{\mathbf{v}} \cdot \left(f \int \phi(\|\mathbf{x} - \mathbf{y}\|) (\mathbf{w} - \mathbf{v}) f(\mathbf{y}, \mathbf{w}, t) d\mathbf{w} d\mathbf{y} \right) = 0$$

mono-kinetic ansatz

$$f(\mathbf{x}, \mathbf{v}, t) = \rho(\mathbf{x}, t) \delta(\mathbf{v} - \mathbf{u}(\mathbf{x}, t))$$

(other ansatz (e.g. Maxwellian)
leads to Euler equations
with pressure)

hydrodynamic
model

$$\begin{cases} \partial_t \rho + \nabla \cdot (\rho \mathbf{u}) = 0 \\ \partial_t \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u} = \int \phi(\|\mathbf{x} - \mathbf{y}\|) (\mathbf{u}(\mathbf{y}, t) - \mathbf{u}(\mathbf{x}, t)) \rho(\mathbf{y}) d\mathbf{y} \end{cases}$$

Motivation

- Another aspect for the hydrodynamic model: existence of global smooth solutions — **critical thresholds**.
- Cucker-Smale interaction tends to **suppress** the finite time blow-up of the pressureless Euler equations.
- 1d: Tadmor-Tan (2014), Carrillo-Choi-Tadmor-Tan (2016), Shvydkoy-Tadmor (2017, 2018), Do-Kiselev-Ryzhik-Tan (2018)
- 2d: Tadmor-Tan (2014), He-Tadmor (2017)

Motivation

- In reality, moving agents are subject to pairwise interaction forces as well as external forces.
- These forces may **compete** with the alignment forces, make it harder to achieve the flocking state.
- In this talk we focus on the **external potential forces**. Its particle model counterpart is studied in Ha-Shu (2018), mainly in one spatial dimension.
- Potential forces is possibly the easiest type of external force to study, since there still holds the energy dissipation.

Main results

- ‘Smooth solutions must flock’:
 - (1) Harmonic potential $\Psi(\mathbf{x}) = \frac{a}{2} \|\mathbf{x}\|^2$, general ϕ
 - (2) General convex potential, constant and large ϕ
- Method: hypocoercivity (two different types)

Main results

- Existence of global smooth solutions: critical thresholds
 - (1) 1d: thresholds for global smooth solutions and blow-up
 - (2) 2d, harmonic potential (similar to He-Tadmor)
 - (3) 2d, general potential (including those without a flocking estimate!)
- All thresholds depend on **the size of $\nabla^2\Psi$** : one reason why harmonic potential is special.
- Method: characteristics + spectral dynamics + L^∞ estimates

Flocking: harmonic potential

Theorem 2.2. *Let $\Psi(\mathbf{x}) = \frac{a}{2}\|\mathbf{x}\|^2$ be the harmonic potential. Let (ρ, \mathbf{u}) be a global smooth solution to (1.1). Assume ρ_{in} has compact support. Then there holds the flocking estimate at exponential rate in both velocity and position:*

$$\mathcal{E}(t) := \int \int (\|\mathbf{u}(\mathbf{x}) - \mathbf{u}(\mathbf{y})\|^2 + a\|\mathbf{x} - \mathbf{y}\|^2) \rho(\mathbf{x}) \rho(\mathbf{y}) \, d\mathbf{x} \, d\mathbf{y} \leq C\mathcal{E}(0)e^{-\lambda t}, \quad (2.3)$$

where $\lambda > 0$ depends on a, ϕ_-, ϕ_+, m_0 , and $C > 0$ is an absolute constant.

- Velocity alignment happens together with spatial concentration! (because spatial deviation induces velocity deviation, if Ψ is convex.)
- In the limit $a \rightarrow 0$, one has $\lambda = O(a)$. This means the strength of external potential may have big influence on flocking rate!

- Reduce to the case: mean velocity/position zero

- Energy estimate

$$\partial_t \int \left(\frac{1}{2} \|\mathbf{u}(\mathbf{x}, t)\|^2 + \frac{a}{2} \|\mathbf{x}\|^2 \right) \rho(\mathbf{x}, t) \, d\mathbf{x} \leq -m_0 \phi_- \int \|\mathbf{u}\|^2 \rho \, d\mathbf{x}$$

- Cross term

$$\partial_t \int \mathbf{u}(\mathbf{x}, t) \cdot \mathbf{x} \rho(\mathbf{x}, t) \, d\mathbf{x} \leq -\frac{a}{2} \int \|\mathbf{x}\|^2 \rho \, d\mathbf{x} + \left(1 + \frac{m_0^2 \phi_+^2}{a} \right) \int \|\mathbf{u}\|^2 \rho \, d\mathbf{x}$$

- Use hypocoercivity to get exponential decay

Flocking: general convex potential

Theorem 2.3. *Let $\Psi(\mathbf{x})$ be strictly convex with bounded Hessian:*

$$a\|\mathbf{y}\|^2 \leq \mathbf{y}^T \nabla^2 \Psi(\mathbf{x}) \mathbf{y} \leq A\|\mathbf{y}\|^2, \quad \forall \mathbf{y} \neq 0, \quad 0 < a < A \quad (2.4)$$

and ϕ is constant, and satisfies

$$m_0 \phi > \frac{A}{\sqrt{a}} \quad (2.5)$$

Let (ρ, \mathbf{u}) be a global smooth solution to (1.1). Assume ρ_{in} has compact support. Then there holds the flocking at exponential rate in both velocity and position:

$$\mathcal{E}(t) := \int \int (\|\mathbf{u}(\mathbf{x}) - \mathbf{u}(\mathbf{y})\|^2 + a\|\mathbf{x} - \mathbf{y}\|^2) \rho(\mathbf{x}) \rho(\mathbf{y}) \, d\mathbf{x} \, d\mathbf{y} \leq C \mathcal{E}(0) e^{-\tilde{\lambda} t}, \quad (2.6)$$

where $\tilde{\lambda} > 0$ depends on $a, A, \phi_-, \phi_+, m_0$, and $C > 0$ depends on $a, A, m_0 \phi$.

- Cannot reduce to ‘mean-zero’ case
- Total energy does NOT measure position concentration: cannot apply hypocoercivity directly!

- A new Lyapunov functional

$$F(t) = \frac{K}{2} \|\|\mathbf{x} - \mathbf{y}\|\|^2 + \langle \mathbf{x} - \mathbf{y}, \mathbf{u}(\mathbf{x}) - \mathbf{u}(\mathbf{y}) \rangle + \frac{\beta}{2} \|\|\mathbf{u}(\mathbf{x}) - \mathbf{u}(\mathbf{y})\|\|^2 \quad K = m_0 \phi$$

$$\langle f(\mathbf{x}, \mathbf{y}), g(\mathbf{x}, \mathbf{y}) \rangle := \int \int f(\mathbf{x}, \mathbf{y}) \cdot g(\mathbf{x}, \mathbf{y}) \rho(\mathbf{x}) \rho(\mathbf{y}) \, d\mathbf{x} \, d\mathbf{y}, \quad \|\|f(\mathbf{x}, \mathbf{y})\|\|^2 := \langle f(\mathbf{x}, \mathbf{y}), f(\mathbf{x}, \mathbf{y}) \rangle$$

$$\begin{aligned} \frac{dF}{dt} = \int \int [& -(K\beta - 1) \|\mathbf{u}(\mathbf{x}) - \mathbf{u}(\mathbf{y})\|^2 - (\mathbf{x} - \mathbf{y}) \cdot (\nabla \Psi(\mathbf{x}) - \nabla \Psi(\mathbf{y})) \\ & - \beta (\mathbf{u}(\mathbf{x}) - \mathbf{u}(\mathbf{y})) \cdot (\nabla \Psi(\mathbf{x}) - \nabla \Psi(\mathbf{y}))] \rho(\mathbf{x}) \rho(\mathbf{y}) \, d\mathbf{x} \, d\mathbf{y} \end{aligned}$$

- The second term is a good term if Ψ is convex.
- If K is large enough, then one can choose a proper β to absorb the bad term (the last term)

Regularity: 1d

Theorem 2.7. *Let the space dimension $d = 1$. Assume Ψ'' is bounded below, and bounded above by:*

$$\Psi''(x) \leq A, \quad \forall x \in \Omega \quad (2.12)$$

with A being a constant satisfying

$$A < \frac{(m_0\phi_-)^2}{4} \quad (2.13)$$

Further assume that

$$\max_{x \in \text{supp } \rho_{in}} (\partial_x u_{in}(x) + (\phi * \rho_{in})(x)) > \frac{m_0\phi_-}{2} - \sqrt{\frac{(m_0\phi_-)^2}{4} - A} \quad (2.14)$$

then (1.1) admits global smooth solution.

positive, if $A > 0$;
negative, if $A < 0$.

- Positive Ψ'' induces blow-up; negative Ψ'' suppresses.
- The assumptions do NOT imply flocking.

Theorem 2.8. *Assume*

$$\Psi''(x) \geq B, \quad \forall x \in \Omega$$

- *If B is so large that*

$$B > \frac{(m_0\phi_+)^2}{4}$$

holds, then $\partial_x u$ blows up to $-\infty$ in finite time for any initial data.

- *If (2.18) does not hold but $B > 0$, then $\partial_x u$ blows up to $-\infty$ in finite time if*

$$\partial_x u_{in}(x) + (\phi * \rho_{in})(x) < \frac{m_0\phi_+}{2} - \sqrt{\frac{(m_0\phi_+)^2}{4} - B}$$

for some x . (notice that in this condition $RHS > 0$)

- *If $B \leq 0$, then $\partial_x u$ blows up to $-\infty$ in finite time if*

$$\partial_x u_{in}(x) + (\phi * \rho_{in})(x) < \frac{m_0\phi_-}{2} - \sqrt{\frac{(m_0\phi_-)^2}{4} - B}$$

for some x . (notice that in this condition $RHS \leq 0$)

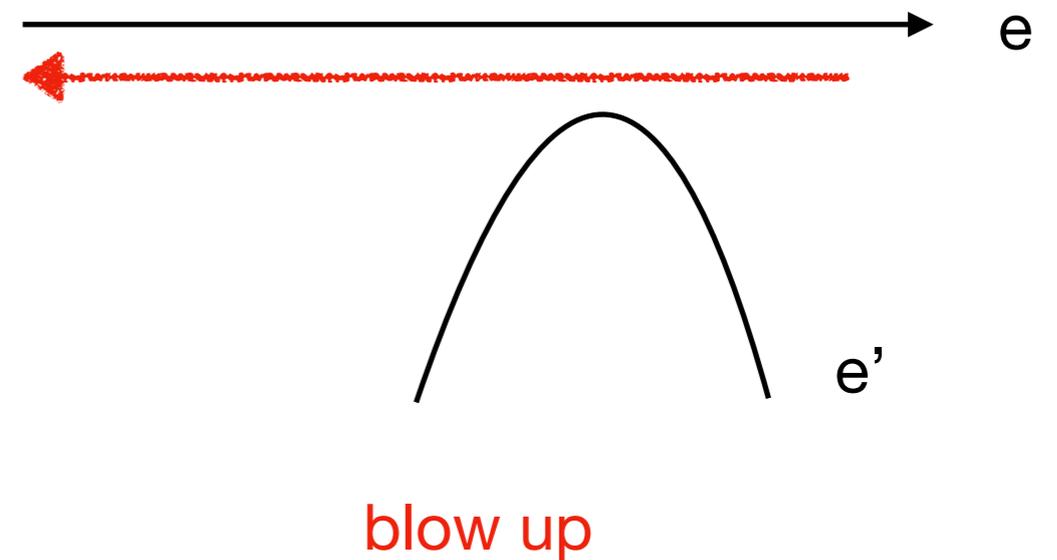
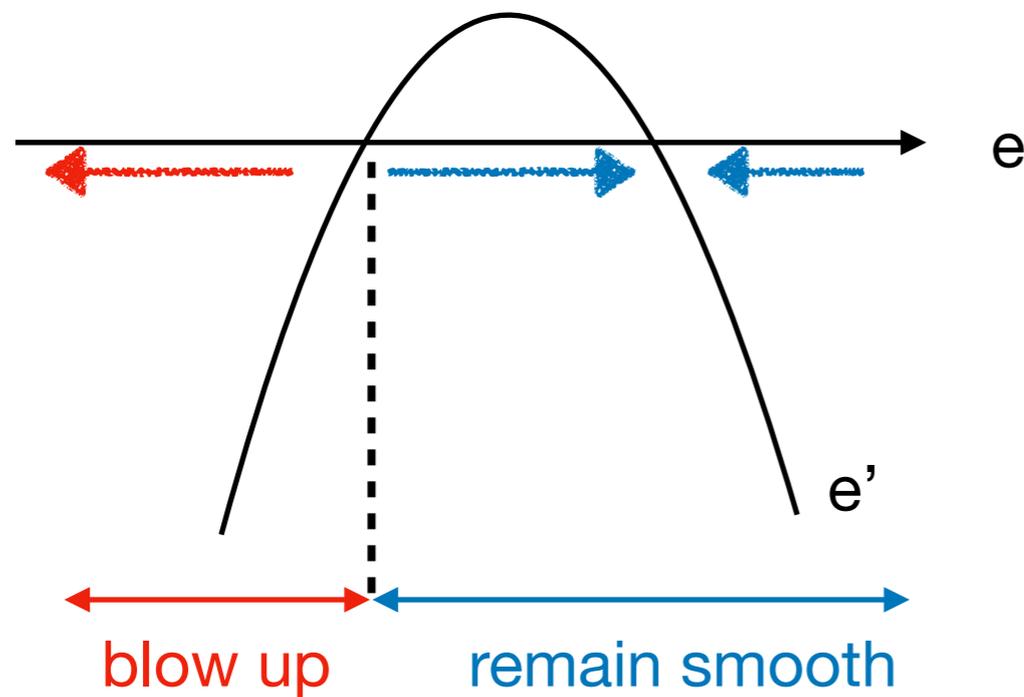
- The 'magic quantity' $e = \partial_x u + \phi * \rho$

$$\rho' = -\rho(e - \phi * \rho)$$

$$e' = -e(e - \phi * \rho) - \Psi''$$

time derivative
along characteristics

quadratic form in e



Regularity: 2d, harmonic potential

Theorem 2.9. *Let the space dimension $d = 2$, and $\Psi(\mathbf{x}) = \frac{a}{2}\|\mathbf{x}\|^2$. There exists a positive constant C_1 , depending on m_0, ϕ_-, ϕ_+, a and $|\phi'|_\infty$ (the L^∞ norm of ϕ'), such that the following holds: Assume*

$$c_1^2 := m_0^2 \phi_-^2 - \left(\max_{\mathbf{x} \in \text{supp } \rho_{in}} |(\eta_S)_{in}(\mathbf{x})| + C_1 \mathcal{E}_\infty(0) \right)^2 - 4a > 0 \quad (2.21)$$

where η_S is the difference between the two eigenvalues of the symmetric matrix $(\nabla \mathbf{u} + (\nabla \mathbf{u})^T)/2$. Assume

$$\max_{\mathbf{x} \in \text{supp } \rho_{in}} (\nabla \cdot \mathbf{u}_{in}(\mathbf{x}) + (\phi * \rho_{in})(\mathbf{x})) \geq 0 \quad (2.22)$$

then (1.1) admits global smooth solution.

- The estimate is good only when the **size of a is moderate**: large a will blow up the $4a$ term (the same reason as 1d), and small a will blow up the C_1 term (because flocking estimate is bad).

$$\partial_t M + \mathbf{u} \cdot \nabla M + M^2 = -(\phi * \rho)M + R - \nabla^2 \Psi \quad M_{ij} = \partial_j u_i$$

$$R_{ij} = \partial_j \phi * (\rho u_i) - u_i (\partial_j \phi * \rho)$$

- Spectral dynamics

$$e' = \frac{1}{2} (4\omega^2 + (\phi * \rho)^2 - \eta_S^2 - e^2 - 2\Delta \Psi) \quad e = \nabla \cdot \mathbf{u} + \phi * \rho$$

$$\omega = (\partial_1 u_2 - \partial_2 u_1)/2$$

$$\eta'_S + e\eta_S = q := \langle \mathbf{s}_2, R_{sym} \mathbf{s}_2 \rangle - \langle \mathbf{s}_1, R_{sym} \mathbf{s}_1 \rangle - \langle \mathbf{s}_2, \nabla^2 \Psi \mathbf{s}_2 \rangle + \langle \mathbf{s}_1, \nabla^2 \Psi \mathbf{s}_1 \rangle$$

- \mathbf{s}_i : (orthonormal) eigenvectors of S, the symmetric part of M

- For harmonic potential,

$$\eta'_S + \underline{e\eta_S} = q := \langle \mathbf{s}_2, \underline{R_{sym}\mathbf{s}_2} \rangle - \langle \mathbf{s}_1, \underline{R_{sym}\mathbf{s}_1} \rangle - \langle \mathbf{s}_2, \nabla^2 \Psi \mathbf{s}_2 \rangle + \langle \mathbf{s}_1, \nabla^2 \Psi \mathbf{s}_1 \rangle$$

- Flocking estimate \rightarrow exponential decay of R
- If $e \geq 0$, then

$$|\eta_S(t)| \leq |(\eta_S)_{in}| + \int_0^\infty |R(s)| ds, \quad \forall t$$

- Use this to propagate $e \geq 0$

require pointwise (L^∞)
flocking estimate:
this can be done by
similar hypocoercivity
on characteristics

Regularity: 2d, general potential

Theorem 2.10. *Let the space dimension $d = 2$. Assume $\nabla^2\Psi$ is bounded:*

$$\|\nabla^2\Psi(\mathbf{x})\| \leq A$$

Assume that there is an a priori estimate

$$\max_{t \geq 0, \mathbf{x} \in \text{supp}} \|\mathbf{u}(\mathbf{x}, t)\| \leq u_{max}$$

for some constant u_{max} . If there hold

$$C_2 := 8|\phi'|_{\infty} m_0 u_{max} + 2A < m_0^2 \phi_-^2 / 2 - 2A$$

and

$$\max_{\mathbf{x} \in \text{supp } \rho_{in}} |(\eta_S)_{in}(\mathbf{x})| \leq \sqrt{(m_0^2 \phi_-^2 / 2 - 2A)} + \sqrt{(m_0^2 \phi_-^2 / 2 - 2A)^2 - C_2^2}$$

and

$$\max_{\mathbf{x} \in \text{supp } \rho_{in}} (\nabla \cdot \mathbf{u}_{in}(\mathbf{x}) + (\phi * \rho_{in})(\mathbf{x})) > \sqrt{(m_0^2 \phi_-^2 / 2 - 2A)} - \sqrt{(m_0^2 \phi_-^2 / 2 - 2A)^2 - C_2^2}$$

then (1.1) admits global smooth solution.

require strictly positive lower bound

- For general potential,

$$\eta'_S + \underline{e\eta_S} = q := \langle \mathbf{s}_2, R_{sym} \mathbf{s}_2 \rangle - \langle \mathbf{s}_1, R_{sym} \mathbf{s}_1 \rangle - \langle \mathbf{s}_2, \nabla^2 \Psi \mathbf{s}_2 \rangle + \langle \mathbf{s}_1, \nabla^2 \Psi \mathbf{s}_1 \rangle$$

- No flocking estimate: R does not decay. The best we can do is a uniform-in-time bound: the u_{\max} assumption
- $\nabla^2 \Psi$ is not identity matrix \rightarrow last two terms are $O(1)$
- **New idea:** make use of the good term $e\eta_S$
- Need to propagate a **positive** lower bound of e

L^∞ estimate

This allows non-convex potentials
(even with multiple local minima)

Proposition 2.11. *Assume that there exists constant $A, a > 0, X_0 > 0$ such that*

$$\frac{a}{2}\|\mathbf{x}\|^2 \leq \Psi(\mathbf{x}) \leq \frac{A}{2}\|\mathbf{x}\|^2, \quad a\|\mathbf{x}\| \leq \|\nabla\Psi(\mathbf{x})\| \leq A\|\mathbf{x}\|, \quad \forall \mathbf{x} \in \Omega, \|\mathbf{x}\| \geq X_0 \quad (2.29)$$

Then there exists a constant u_{max} , depending on $a, A, \phi_-, \phi_+, m_0, E(0)$, where $E(t)$ is the total energy

$$E(t) = \int \left(\frac{1}{2} \|\mathbf{u}(\mathbf{x}, t)\|^2 + \Psi(\mathbf{x}) \right) \rho(\mathbf{x}, t) \, d\mathbf{x} \quad (2.30)$$

such that

$$\max_{t \geq 0, \mathbf{x} \in \text{supp } \rho_{in}} \|\mathbf{u}(\mathbf{x}, t)\| \leq u_{max} \quad (2.31)$$

- Method: hypocoercivity along characteristics

$$F(\mathbf{x}, t) = \frac{1}{2} \|\mathbf{u}(\mathbf{x}, t)\|^2 + \Psi(\mathbf{x}) + c\mathbf{u}(\mathbf{x}, t) \cdot \nabla\Psi(\mathbf{x})$$

Conclusion

- ‘Smooth solutions must flock’:
 - (1) Harmonic potential $\Psi(\mathbf{x}) = \frac{a}{2} \|\mathbf{x}\|^2$; general ϕ
 - (2) General convex potential, constant and large ϕ
- Existence of global smooth solutions: critical thresholds
 - (1) 1d: thresholds for global smooth solutions and blow-up
 - (2) 2d, harmonic potential (similar to He-Tadmor)
 - (3) 2d, general potential (including those without a flocking estimate!)