Nonlocal interaction PDEs with nonlinear diffusion

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A discrete particle system

- N particles, located at $X_1(t),\ldots,X_N(t)\in\mathbb{R}^d$ with masses $m_1,\ldots,m_N.$
- Subject to binary interaction forces depending on their position.
- Friction dominated regime: no inertia.

$$\frac{dX_j(t)}{dt} = -\sum_{k\neq j} m_k \nabla G(X_j(t) - X_k(t)), \qquad j = 1, \dots, N.$$
(1)

Typical assumptions for the interaction potential G

•
$$G\in C(\mathbb{R}^d)$$
, with $G(0)=0$,

• Radial symmetry G(x) = g(|x|),

Notation: g increasing \Rightarrow G attractive, g decreasing \Rightarrow G repulsive.

Stochastic version:

$$dX_j(t) = -\sum_{k \neq i} m_k \nabla G(X_j(t) - X_k(t)) dt + \sigma_N dW^j(t)$$

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Figure: *N* interacting particles

Nonlocal interaction PDEs

Main motivation: population dynamics

Animal swarming:

- Okubo (1980)
- Oelschläger (1989)
- Morale, Capasso, and Oelschläger (1998)
- Mogilner, Edelstein-Keshet (1999)
- Topaz, Bertozzi, and Lewis (2006)

Typical interaction potentials:

- attractive-repulsive Morse potentials $G(x) = -C_a e^{-|x|/l_a} + C_r e^{-|x|/l_r}$
- combination of Gaussian potentials $G(x) = -C_a e^{-|x|^2/l_a} + C_r e^{-|x|^2/l_r}$
- smoothed characteristic functions of a set $G(x) = \alpha \delta_{\epsilon} * \chi_A(x)$.

Hydrodynamic $N \to +\infty$ limit

Empirical measure:

$$\mu_N(t) = \left(\sum_{j=1}^N m_j\right)^{-1} \sum_{k=1}^N m_k \delta_{X_k(t)}$$

Formal limit of μ_N in the stochastic case

Assuming $\lim_{N\to+\infty} \sigma_N = \sigma > 0$, then

$$\frac{\partial \mu}{\partial t} = \frac{\sigma^2}{2} \Delta \mu + \operatorname{div}(\mu \nabla G * \mu)$$

Distributional PDE for μ_N for $\sigma = 0$

$$\frac{\partial \mu}{\partial t} = \operatorname{div}(\mu \nabla G * \mu)$$

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More motivations: Interplay with physics

Mean-field limits of large particle systems in statistical mechanics:

- Onsager (1949) Vortex dynamics
- Morrey (1955) Derivation of hydrodynamics from statistical mechanics
- Dobrushin (1993) Vlasov equation
- Golse (2003) Review paper

In those contexts, the potential G blows-up at the origin, which renders the rigorous analytical framework of the model a challenging issue. Kinetic modeling for granular media:

- Benedetto, Caglioti, Pulvirenti (1997)
- Brilliantov, Pöschel (2004)
- Toscani (2004)

Here, G is a convex attractive potential, typically $G(x) = |x|^{\alpha}$ with $\alpha > 1$.

More motivations: chemotaxis

• In many problems in biology, such as the 2d Keller-Segel model

$$\partial_t \rho = \Delta \rho + \frac{\chi}{2\pi} \operatorname{div}(\rho \nabla \log |\cdot| * \rho),$$

the dichotomy between the *repulsive* linear diffusion term and the *attractive log* 'chemotaxis' term produces *blow-up* (concentration) of solutions in finite time. No one knows (up to now) how to define solutions in a *measure* sense after blow up.

• The large time behavior for models with 'milder' aggregation force and with nonlinear diffusion

$$\begin{split} \partial_t \rho &= \Delta \rho^m + \operatorname{div}(\rho \nabla G * \rho) \\ G(x) &= g(|x|), \qquad g'(r) > 0, \qquad G \in W^{1,\infty}, \end{split}$$

is a (most of the times) highly nontrivial question.

Simplification: no diffusion. Measure solutions theory (particles remain particles).

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More motivations:

- Alignment of actin laments with or without cross-linking proteins, cf. Kang, Perthame, Primi, Stevens, Velazquez (2009). G double well potential.
- Kinetic dithering

$$\partial_t \rho = -\operatorname{div}(\rho \nabla (G * (\rho - \sigma)))$$

with $\sigma \in L^1_+$ being a given profile, and $\int \rho = \int \sigma$. Typically, $G(x) = |x|^{\alpha}$. Stationary solution $\rho = \sigma$. Stable for large times? PhD thesis of J.-C. Hütter. Ref: Fornasier, Haškovec, Steidl - 2012.

- Opinion formation: Sznajd-Weron, Sznajd (2000) Aletti, Naldi, Toscani (2007). Quasi invariant opinion limit of kinetic models.
- Crowd movements: Helbing's social force modelled via nonlocal forces, cf. Hughes (2002), Cristiani et al. (2011), Colombo et al. (2012).

Mathematical motivation

• Models with nonlocal attractive-repulsive kernels

 $\partial_t \rho = \operatorname{div}(\rho \nabla G * \rho)$

with G being a *double-well* potential, e. g. Lennard–Jones. Stationary solutions? How do they look like?

- Fetecau, Huang, Kolkolnikov 2011: L¹ stationary states.
- von Brecht, Bertozzi 2012: aggregation sheets.
- Balagué, Carrillo, Laurent, Raoul 2011: radial ins/stability of 'spherical shells'.
- Similarities with 2d incompressible Euler.
- A repulsive nonlocal approximation for nonlinear diffusion

$$\frac{\partial \rho}{\partial t} = \operatorname{div}(\rho \nabla G_{\epsilon} * \rho)$$

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What is a gradient flow?

Given a smooth function $F : \mathbb{R}^d \to \mathbb{R}$, a differentiable curve $[0, +\infty) \ni t \mapsto X(t) = \mathbb{R}^d$ is a gradient flow of F if X(t) satisfies $\dot{X}(t) = -\nabla F(X(t)).$

• Energy dissipation:

$$\frac{d}{dt}F(X(t)) = -|\nabla F(X(t))|^2$$

• Implicit Euler variational derivation: time step $\tau > 0$, $X_{\tau}(t) = X_{\tau}^{n}$ for $t \in ((n-1)\tau, n\tau]$, with

$$X_{\tau}^{n} = \operatorname{argmin}\left\{\frac{1}{2\tau}|X - X_{\tau}^{n}|^{2} + F(X), \ X \in \mathbb{R}^{d}
ight\}$$

• $D^2 F \ge \lambda \mathbb{I}$ implies stability

$$egin{aligned} &rac{d}{dt}|X_1(t)-X_2(t)|^2=-2< X_1(t)-X_2(t),
abla F(X_1(t))-
abla F(X_1(t))>\ &\leq -2\lambda|X_1(t)-X_2(t)|^2. \end{aligned}$$

Gradient flow structure of the ODE particle system

Consider

$$\frac{dX_j(t)}{dt} = -\sum_{k\neq j} m_k \nabla G(X_j(t) - X_k(t)), \qquad j = 1, \dots, N.$$

with G(-x) = G(x) and $G \in C^2(\mathbb{R}^d)$.

Weighted metric structure

Denote $\mathbf{m} = (m_1, \dots, m_N)$. For $\mathbf{X}, \mathbf{Y} \in \mathbb{R}^{dN}$, let

$$<\mathbf{X},\mathbf{Y}>_{L^2_{\mathbf{m}}}:=\sum_{j=1}^N m_j X_j Y_j, \qquad \|\mathbf{X}\|_{L^2_{\mathbf{m}}}^2=<\mathbf{X},\mathbf{X}>_{L^2_{\mathbf{m}}}.$$

Frechét differential

M. E

Let $\mathbf{F} \in C^1(\mathbb{R}^{dN})$. The linear operator $\operatorname{grad}_{\mathbf{X}} \mathbf{F}[X]$ is defined by

$$\lim_{\epsilon \to 0} \frac{\mathbf{F}[\mathbf{X} + \epsilon \mathbf{Y}] - \mathbf{F}[\mathbf{X}]}{\epsilon} = : < \operatorname{grad}_{\mathbf{X}} \mathbf{F}[\mathbf{X}], \mathbf{Y} >_{L_{\mathbf{m}}^2} = \sum_{i=1}^{N} m_j \nabla_{X_i} \mathbf{F}[\mathbf{X}] \cdot \mathbf{Y}_i.$$

Gradient flow structure of the ODE particle system

Energy functional

Let **X** := $(X_1, ..., X_N)^T$.

$$\mathbf{G}[\mathbf{X}] := \frac{1}{2} \sum_{i,j} m_i m_j G(X_i - X_j)$$

Then

$$\dot{\mathbf{X}}(t) = -\operatorname{grad}_{\mathbf{X}} \mathbf{G}[\mathbf{X}(t)].$$
 (2)

Problem (2) makes sense if $G \in C^1(\mathbb{R}^d)$.

Regularity and collisions

If $G \in C^2(\mathbb{R}^d)$, then particles do not collide.

•

Mildly singular, locally attractive kernels

Assume

- (K1) G(-x) = G(x)
- (K2) $G \in C^1(\mathbb{R}^d \setminus \{0\})$
- (K3) G has a local minimum at x = 0
- (K4) G is λ -convex, i. e. $G(x) \frac{\lambda}{2}|x|^2$ is convex on \mathbb{R}^d .

Examples:

- Morse type potentials $G(x) = -e^{-a|x|}$, with a > 0,
- Pointy potentials, i. e. with a Lipschitz point at the origin,
- Power laws $G(x) = |x|^{\alpha}$ with $\alpha \in (1, 2)$, cf. [Li, Toscani 2004], [Burger, DF 2008]

Kernels with above assumptions (K1)–(K4) possibly produce *finite time collapse* $\mu = \delta_{x_c}$, with x_c center of mass of the particles (constant in time).

Weaker gradient flow structure

Introduce the sub-differential of G

$$\partial G(x) := \left\{ k \in \mathbb{R}^d \ : \ G(y) - G(x) \ge k \cdot (y - x) + o(|x - y|) \text{ for all } y \in \mathbb{R}^d
ight\},$$

and the minimal sub-differential of G

$$\partial^0 G(x) = \operatorname{argmin}_{k \in \partial G(x)} |k| = \begin{cases} \nabla G(x) & \text{if } x \neq 0 \\ 0 & \text{if } x = 0 \end{cases}$$

Sub-differential structure of L_m^2

$$\begin{split} \partial \mathbf{G}[\mathbf{X}] &=:= \left\{ K \in L^2_{\mathbf{m}} \, : \, \mathbf{G}(\mathbf{Y}) - \mathbf{G}(\mathbf{X}) \geq < K, (\mathbf{Y} - \mathbf{X}) >_{L^2_{\mathbf{m}}} \right. \\ &+ o(\|\mathbf{X} - \mathbf{Y}\|_{L^2_{\mathbf{m}}}) \, \text{for all } Y \in L^2_{\mathbf{m}} \right\}. \end{split}$$

Weaker gradient flow structure

We replace our particle system with

$$\frac{dX_{j}(t)}{dt} \in -\sum_{k \in C_{j}(t)} m_{k} \partial^{0} G(X_{j}(t) - X_{k}(t)), \quad C_{j}(t) = \{k : X_{j}(t) \neq X_{k}(t)\}.$$
(3)

Then, it is easily checked that

$$\dot{\mathbf{X}}(t) \in -\partial^0 \mathbf{G}[\mathbf{X}(t)],$$
 (4)

with $\partial^{0}\mathbf{G} = \operatorname{argmin}_{K \in \partial \mathbf{G}} \|K\|_{L^{2}_{\mathbf{m}}}.$

Well posedness in the discrete case

- λ -convexity of the functional **G**
- Existence and uniqueness of gradient flows.

Finite time collapse for attractive potentials

Assume G satisfies (K1)-(K4) and the additional conditions

$$G(x) = g(|x|), \quad g'(r) > 0^1 ext{ for } r > 0, \quad rac{g'(r)}{r} ext{ non-increasing.}$$
 (5)

Proposition (Finite time collapse)

Let X_1, \ldots, X_N evolve according to (4), i. e.

$$\dot{X}_j(t) = -\sum_{X_k(t)
eq X_j(t)} m_k
abla G(X_j(t) - X_k(t)).$$

Then, all the particles collapse in a finite time, i. e. $X_j(t) = \delta_{C_m}$ for all $t \ge t^*$ for some t^* , iff

$$\int_0^\varepsilon \frac{1}{g'(z)} dz < +\infty \tag{6}$$

for some $\varepsilon > 0$.

 ${}^{1}G$ is called *attractive* when g'(r) > 0 and *repulsive* when g'(r) < 0

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Figure: The quantity $R(t) = \max\{|X_j(t) - C_m|, j = 1, \dots, N\}$.

Proof

Assume $\sum_{j=1}^{N} m_j = 1$. Center of mass $C_m = \sum_{j=1}^{N} m_j X_j(t)$ is preserved. Assume for simplicity $C_m = 0$.

$$\begin{aligned} \frac{d}{dt}R(t) &= \frac{d}{dt}|X_1(t)| = -\frac{X_1(t)}{|X_1(t)|} \cdot \sum_{j \neq 1} m_j \nabla G(X_1(t) - X_j(t)) \\ &= -\sum_{j \neq 1} m_j X_1(t) \cdot (X_1(t) - X_j(t)) \frac{g'(|X_1(t) - X_j(t)|)}{|X_1(t)||X_1(t) - X_j(t)|}. \end{aligned}$$

Since $X_1(t) \cdot X_j(t) \le |X_1(t)|^2$, and since g'(r)/r is non increasing, we use $|X_1(t) - X_j(t)| \le 2|X_1(t)|$:

$$egin{aligned} &rac{d}{dt}R(t) \leq -rac{g'(2|X_1(t)|)}{2|X_1(t)|^2}\sum_{j
eq 1}m_j\left(|X_1(t)|^2-X_1(t)\cdot X_j(t)
ight)\ &= -(1-m_1)g'(2|X_1(t)|)+rac{g'(2|X_1(t)|)}{2|X_1(t)|^2}X_1(t)\cdot (-m_1X_1(t))=-g'(2R(t)) \end{aligned}$$

and the assertion is proven. Notice that the collapse time is independent of N.

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Ingredients for the continuum theory²

Aim: produce a unique notion of measure solution for

$$\frac{\partial \mu}{\partial t} = \operatorname{div}(\mu \nabla G * \mu).$$

The measure space

$$\mu\in \mathfrak{P}_2(\mathbb{R}^d):=\left\{\mu\in \mathfrak{P}(\mathbb{R}^d), \ \int |x|^2d\mu(x)<+\infty
ight\}$$

endowed with the 2-Wasserstein distance

$$\begin{aligned} d_2(\mu,\nu)^2 &= \inf\left\{\iint_{\mathbb{R}^d \times \mathbb{R}^d} |x-y|^2 d\gamma(x,y), : \ \gamma \in \Gamma(\mu,\nu)\right\}\\ \Gamma(\mu,\nu) &= \left\{\gamma \in \mathcal{P}(\mathbb{R}^d \times \mathbb{R}^d) : \ \mu \text{ and } \mu \text{ are the marginals of } \gamma\right\}\end{aligned}$$

The functional

$$\mathfrak{G}[\mu] = \frac{1}{2} \iint_{\mathbb{R}^d \times \mathbb{R}^d} G(x - y) d\mu(x) d\mu(y)$$

²Ambrosio, Gigli, Savaré - Birkhäuser 2005

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Why the Wasserstein distance?

Go back to the discrete case:

$$\mu := \sum_{j=1}^N m_j X_j, \quad \nu := \sum_{j=1}^N m_j Y_j.$$

The natural distance is

$$d(\mu,\nu)^2 = \inf\left\{\int_0^1 \|\frac{d}{ds}\mathbf{X}(\cdot)\|_{L^2_{\mathbf{m}}}^2, \ X_j(0) = X_j, \ X_j(1) = Y_j\right\}.$$

The natural continuum version is:

$$d(\mu,\nu)^{2} = \inf\left\{\int_{0}^{1}\int |v_{s}(x)|^{2}d\mu_{s}(x), \ \partial_{s}\mu_{s} + \operatorname{div}(\mu_{s}v_{s})0, \ \mu_{0} = \mu, \ \mu_{1} = \nu\right\},$$

which coincides with the 2-Wasserstein distance according to the Benamou-Brenier formula.

Definition of Wasserstein gradient flow

An absolutely continuous curve $[0, +\infty) \ni t \mapsto \mu(t) \in \mathcal{P}(\mathbb{R}^d)$ is a Wasserstein gradient flow of the functional \mathcal{G} iff

$$\begin{aligned} &\frac{\partial \mu(t)}{\partial t} + \operatorname{div}(\mu(t)v(t)) = 0, & \text{in } \mathcal{D}'(\mathbb{R}^d \times [0, +\infty)) \\ &v(t) = -\partial^0 G * \mu(t) = -\int_{x \neq y} \nabla G(x - y) d\mu(y, t). \end{aligned}$$

Notice that $\partial^0 G * \mu(t)$ coincides with the minimal sub-differential of \mathcal{G} on $\mathcal{P}_2(\mathbb{R}^d)$, namely

$$\begin{split} \partial^{0}G * \mu(t) &= \operatorname{argmin}_{\mathbf{v} \in \partial \mathfrak{G}[\mu]} \|\mathbf{v}\|_{L^{2}(d\mu:\mathbb{R}^{d})} \\ \partial \mathfrak{G}[\mu] &= \left\{ \mathbf{v} \in L^{2}(d\mu) : \\ \mathfrak{G}[\nu] - \mathfrak{G}[\mu] &\geq \inf_{\gamma_{o} \in \Gamma(\mu,\nu)} \iint_{\mathbb{R}^{d} \times \mathbb{R}^{d}} \mathbf{v}(x) \cdot (y-x) d\gamma_{o}(x,y) + o(d_{2}(\mu,\nu)) \right\}, \\ \gamma_{o} \in \Gamma(\mu,\nu) \quad \text{such that} \quad d_{2}(\mu,\nu) &= \iint_{\mathbb{R}^{d} \times \mathbb{R}^{d}} |x-y|^{2} d\gamma_{o}(x,y). \end{split}$$

Existence and uniqueness of solutions

Theorem (Existence and uniqueness^a)

^aCarrillo, DF, Figalli, Laurent, Slepcev - Duke Math. J. - 2011

 Let μ₀ ∈ P₂(ℝ^d). Then, there exists a unique Wasserstein gradient flow solution for 9 with μ₀ as initial datum. Moreover,

$$\mathfrak{G}[\mu(t)] + \int_0^t ds \int_{\mathbb{R}^2} \left| \partial^0 G * \mu(x,s) \right|^2 d\mu(x,s) \le \mathfrak{G}[\mu_0], \tag{7}$$

for all $t \geq 0$.

• Let $\mu_1^0, \mu_2^0 \in \mathcal{P}_2(\mathbb{R}^d)$. Let $\mu_1(t)$ and $\mu_2(t)$ be Wasserstein gradient flows for \mathcal{G} with μ_1^0 and μ_2^0 as initial data respectively. Then,

$$d_2(\mu_1(t),\mu_2(t)) \le e^{|\lambda|t} d_2(\mu_1^0,\mu_2^0), \tag{8}$$

for all $t \geq 0$.

Finite time collapse for general solutions

Theorem (Finite total collapse^a)

^aCarrillo, DF, Figalli, Laurent, Slepcev - Duke Math. J. - 2011

Let $\mu_0 \in \mathfrak{P}_2(\mathbb{R}^d)$ compactly supported. Let $\mu(t)$ the corresponding gradient flow of \mathfrak{G} . Let

$$C_m := \int_{\mathbb{R}^d} x d\mu(x,t).$$

Then, there exists a time t^* depending only on the radius of $\operatorname{spt}(\mu_0)$ such that

$$\mu(t)=\delta_{C_m},$$

for all $t \geq t^*$.

Proof

Similar to an old idea of R. Dobrushin (1979).

• Atomization of μ_0 : for a fixed arbitrary $\varepsilon > 0$, take $\mu_0^N = \sum_{j=1}^N m_j \delta_{X_j}$ such that

$$d_2(\mu_0,\mu_0^N)\leq \varepsilon.$$

Let the particles X₁,..., X_N evolve via the discrete particle system. Let t^{*} be the collapse time,

$$X_1(t)=\ldots=X_N(t)=C_m,\quad\text{for all }t\geq t^*.$$

- 3 This means that $\mu^N(t) := \sum_{j=1} Nm_j \delta_{X_i(t)} = \delta_{C_m}$ for all $t \ge t^*$.
- The stability property (8) implies

$$d_2(\mu(t^*),\mu^N(t^*)) \leq e^{-\lambda t^*} d_2(\mu_0,\mu_0^N) \leq \varepsilon e^{-\lambda t^*},$$

which is an arbitrary small quantity. Hence,

5
$$\mu(t^*) = \mu^N(t^*) = \delta_{C_m}$$
.

Global confinement for attractive-repulsive potentials³

Assume G as in (K1)–(K4), plus
(K5)
$$G(x) = g(|x|), g \in C^1((0, +\infty)),$$

(K6) $g'(r) > 0$ for $r > R_a$ for some $R_a > 0$,
(K7) $g'(r) > -C_G$ for $r < R_a$ for some $C_G > 0$.
Moreover, assume either

$$\begin{array}{l} ({\sf K8}) \\ \text{or} \\ ({\sf K9}) \\ \text{lim}\inf_{r\to 0}g(r)>-\infty, \\ \text{Then, there exists } R^*>0 \\ \text{depending only on } G \\ \text{and on } \mu_0 \\ \text{such that} \\ \\ \operatorname{spt}(\mu(t))\subset B(0,R^*), \\ \text{for all } t\geq 0. \end{array}$$

Remark: conditions (K5)-(K7) alone are not enough for global confinement (Theil, 2006).

³Carrillo, DF, Figalli, Laurent, Slepcev - Nonlinear Anal. - 2012

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N-dependent repulsion range⁴

$$\begin{split} \frac{dX_j(t)}{dt} &= -\sum_{k \neq j} m_k \nabla G(X_j(t) - X_k(t)) - \sum_{k \neq j} m_k \nabla V_N(X_j(t) - X_k(t)), \ j = 1, \dots, N \\ V_N(x) &= N^{d\beta} V(N^{\beta} x), \quad \beta \in (0, 1) \\ V(x) &= v(|x|), \quad v \in C^2((0, +\infty)), \quad v'(r) < 0, \ \text{as } r > 0, \\ V &\ge 0, \quad \int_{\mathbb{R}^d} V(x) dx = \varepsilon. \end{split}$$

• V_N is a repulsive kernel, with a range of interaction $O(N^{-\beta})$ and strength of the interaction force $O(N^{d\beta})$ depending on the number of individuals N.

• Formally
$$V_N(x) \to \varepsilon \delta$$
 in \mathcal{D}' as $N \to +\infty$.

Formal limit of the particle system

$$\frac{\partial \mu}{\partial t} = \operatorname{div}(\mu \nabla G * \mu) + \varepsilon \operatorname{div}(\mu \nabla \mu).$$
(9)

Hence... a quadratic porous medium type diffusion term appears.

⁴Ölschläger - Prob. Th. Rel. Fields - 1989

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Nonlocal interaction PDEs

Basic properties of the limiting equation

Assume

- $G(x) = g(|x|), g \in C^2([0, +\infty)),$
- g'(r) > 0 for all r > 0,
- spt $G = \mathbb{R}^d$, $G \leq 0$, $G \in L^1(\mathbb{R}_d)$.

Regularizing effect

For all initial data $\mu_0 \in \mathcal{P}_2(\mathbb{R}^d)$, the corresponding solutions are *densities*, $\mu(t) = \rho(t) d\mathcal{L}_d$.

Conservation of the center of mass

Let

$$CM[\rho(t)] := \int x \rho(x,t) dx,$$

then $CM[\rho(t)] = CM[\rho_0]$ for all $t \ge 0$.

Wasserstein gradient flow for the limiting equation

$$\frac{\partial \rho}{\partial t} = \operatorname{div}(\rho \nabla (\varepsilon \rho + G * \rho)).$$

Energy functional:

$$E[\rho] := \frac{\varepsilon}{2} \int_{\mathbb{R}^d} \rho^2(x) dx + \frac{1}{2} \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} G(x-y) \rho(y) \rho(x) dy dx.$$
(10)

Energy identity:

$$E[\rho(t)] + \int_0^T \int_{\mathbb{R}^d} \rho \left| \nabla(\varepsilon \rho + G * \rho) \right|^2 dx dt = E[\rho_0].$$
(11)

The identity (11) can be proven rigorously in the context of the *Wasserstein gradient flow* theory developed in [Ambrosio, Gigli, Savaré, Birkhäuser 2003].

A key question: large time behavior

How does $\rho(t)$ behave as $t \to +\infty$? There are (basically) three possibilities:

- (i) **Diffusion dominated case:** $\rho(t)$ decays to zero in some L^p norm with p > 1. In this case, the repulsive effects dominates.
- (ii) Aggregation dominated case: $\rho(t)$ concentrates to a singular measure (delta) in finite or infinite time. Here, the aggregation effect dominates.
- (iii) **Balanced case:** $\rho(t)$ converges to some (stable) non trivial L^1 steady state for large times.

Unlike the Keller-Segel system, here no mass threshold phenomenon occurs, since the equation is quadratically homogeneous.

A minimization problem

$$\operatorname{argmin}_{\rho \in L^1_+(\mathbb{R}^d)} \left\{ \int_{\mathbb{R}^d} \Phi(\rho(x)) dx - \frac{1}{2} \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \rho(x) \rho(y) G(x-y) dx dy \right\}.$$

Existence of nontrivial minimizers⁵ under the assumptions

- Total mass sufficiently large,
- $\Phi(tu) \leq t^{\nu} \Phi(u)$ with $1 < \nu < 2$,
- G slow decaying at infinity, i. e. $G(tx) \ge t^{-\alpha}G(x)$ with $\alpha \in (0, d)$,

•
$$\Phi(u) = o(u^{1+\frac{\alpha}{d}})$$
 as $u \to 0$.

⁵[Lions - Ann. Inst. H. Poincare 1984]

A critical exponent

Nontrivial minimizers exist⁶ if

• $G \in L^1_+$,

•
$$\Phi(u) = cu^2 + o(u^2)$$
 as $u \to 0$ with $c > 0$,

• either c = 0 or $2c < \int G$.

Case $\Phi(u) = u^m$: the exponent m = 2 is *critical*:

- $m > 2 \Rightarrow$ aggregation dominates \Rightarrow nontrivial stationary patterns,
- $m < 2 \Rightarrow$ diffusion dominates (large time decay expected),
- $m = 2 \Rightarrow ??$

⁶[Bedrossian, 2012]

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Stationary states in multiple dimensions.

$$\frac{\partial \rho}{\partial t} = \operatorname{div}(\rho \nabla (\varepsilon \rho + \mathsf{G} * \rho)).$$

Threshold phenomenon^a

^a[Burger, DF, Franek - to appear on CMS], [Bedrossian, AML 2011]

- Let ε < ||G||_{L¹}. Then, there exists at least one non trivial L¹ steady state, which is also a minimizer for the energy E[ρ].
- Let $\varepsilon \ge \|G\|_{L^1}$. Then, there exist no steady states except $\rho \equiv 0$.

Finite time concentration is not possible under the present smoothness assumptions on *G*.

Stationary points of $E[\rho]$ are steady states and vice-versa

Uniqueness of steady states in one space dimension

With d = 1 we can characterize all the steady states as follows.

Theorem (Burger-DF-Franek - to appear on CMS)

Let $\varepsilon < \|G\|_{L^1}$. Then, there exists a unique $\rho \in L^2 \cap \mathcal{P}$ with zero center of mass which solves

$$\rho\partial_{x}(\varepsilon\rho+G*\rho)=0.$$

Moreover,

- ρ is symmetric and monotonically decreasing on x > 0,
- $\rho \in C^2(\operatorname{supp}[\rho])$,
- $supp[\rho]$ is a bounded interval in \mathbb{R} ,
- ρ has a global maximum at x = 0 and $\rho''(0) < 0$,
- ρ is the global minimizer of the energy $E[\rho] = \frac{\varepsilon}{2} \int \rho^2 dx \frac{1}{2} \int \rho G * \rho dx$.

Sketch of the proof

Fix L > 0. Look for ρ ∈ C(ℝ) symmetric on sptρ = [−L, L], strictly decreasing on (0, L]:

$$\varepsilon\rho(x) = -\int_0^L \left(G(x-y) + G(x+y)\right)\rho(y)dy + C \tag{12}$$

• Differentiate (12) w.r.t. x, set $u(x) = -\rho_x(x)$:

$$\varepsilon u(x) = -\int_0^L (G(x-y) - G(x+y)) u(y) dy =: \mathcal{G}_L[u](x)$$
(13)

- Solve the eigenvalue problem (13) with Krein-Rutman theorem. \mathcal{G}_L is a *strictly positive* operator, therefore $\varepsilon = \varepsilon(L)$ is a *simple* eigenvalue \Rightarrow uniqueness of $\rho(x) = \int_x^L u(y) dy$ with $\int_0^L \rho(x) dx = 1$.
- Prove that the function (0, +∞) ∋ L → ε(L) ∈ (0, 1) is continuous and 1 : 1 ⇒ uniqueness is proven provided all steady states are supported on a bounded interval, symmetric and decreasing on x > 0.
- Prove that all steady states are as above. Main tools: symmetric rearrangement and connected support.

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Nonlocal interaction PDEs

Remarks and open problems:

- The uniqueness is surprising because the functional is neither geodesically convex in the Wasserstein space nor convex in the classical sense.
- Uniqueness in many dimensions? We believe it true in the radially symmetric case.
- Porous medium exponent $\gamma \neq 2$ (ongoing discussion with M. Burger, R. Fetecau, Y. Huang).

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Interplay with entropy solutions



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The JKO scheme produces entropy solutions

• Nonlocal interaction equations with nonlinear diffusion

$$\partial_t \rho = \Delta \rho^m + \operatorname{div}(\rho \nabla G * \rho) = 0 \tag{14}$$

with m > 1 and $G \in C^2$ and G even. Here, both notions of *entropy* solutions and gradient flow solutions have been used (almost at the same time!) to prove uniqueness of solutions.

• Nonlinear diffusion equations with in-homogeneous term

$$\partial_t \rho = \partial_x (\rho \partial_x (a(x) \rho^{m-1}))$$

with $a(x) \ge c > 0$. In [DF, Matthes - submitted 2012] we prove that the notions of gradient flow solution and entropy solutions coincide.

The results in [DF, Matthes] can be applied also for (14).

A one dimensional repulsive equation⁷

Consider ρ gradient flow solution to

$$\rho_t = \partial_x (\rho \partial_x (G * \rho)), \qquad G(x) = -|x|.$$
(15)

Let

$$F(x,t)=\int_{-\infty}^{x}\rho(y,t)dy,$$

then F is an entropy solution to the Burgers' type equation

$$F_t + (F^2 - F)_x = 0. (16)$$

Applications:

- Smoothing effect: initial deltas become densities,
- Wave front tracking approximation for (16) provide particle approximation for (15).

⁷Work in preparation with G. Bonaschi and J. A. Carrillo

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A two species model⁸

- X_1, \ldots, X_N particles of the first species with masses n_1, \ldots, n_N ,
- Y_1, \ldots, Y_M are particles of the second species with masses m_1, \ldots, m_M .

Particle system:

$$\begin{cases} \dot{X}_{i}(t) = -\sum_{X_{i} \neq X_{k}} n_{k} \nabla H_{1}(X_{i}(t) - X_{k}(t)) - \sum_{X_{i} \neq Y_{k}} m_{k} \nabla K_{1}(X_{i}(t) - Y_{k}(t)) \\ \dot{Y}_{j}(t) = -\sum_{Y_{j} \neq Y_{k}} m_{k} \nabla H_{2}(Y_{j}(t) - Y_{k}(t)) - \sum_{Y_{j} \neq X_{k}} n_{k} \nabla K_{2}(Y_{j}(t) - X_{k}(t)) \end{cases}$$

Continuum version:

$$\begin{cases} \partial_t \mu_1 = \operatorname{div} \left(\mu_1 \nabla H_1 * \mu_1 + \mu_1 \nabla K_1 * \mu_2 \right) \\ \partial_t \mu_2 = \operatorname{div} \left(\mu_2 \nabla H_2 * \mu_2 + \mu_2 \nabla K_2 * \mu_1 \right). \end{cases}$$

⁸[DF, Fagioli - submitted]

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Motivation

- Pedestrian movements, lane formation, segregation, cf. [Appert-Rolland, Degond, Motsch 2011], [Colombo, Lécureux-Mercier 2012].
- Opinion formation, cf. [Josek 2009], [Düring, Markowich, Pietschmann, Wolfram 2009], [Escudero, Macià, Velázquez 2010].
- Two species chemotaxis, cf. [Horstmann 2011], [Espejo, Stevens, Velázquez 2009], [Conca, Espejo, Vilches 2011].
- Predator-Prey type interaction, cf. [Mogilner, Edelstein-Keshet, Bent, Spiros 2003].

Symmetrizable case

$$\begin{cases} \partial_t \mu_1 = \operatorname{div} \left(\mu_1 \nabla K_{11} * \mu_1 + \mu_1 \nabla K_{12} * \mu_2 \right) \\ \partial_t \mu_2 = \alpha \operatorname{div} \left(\mu_2 \nabla K_{22} * \mu_2 + \mu_2 \nabla K_{12} * \mu_1 \right). \end{cases}$$
(17)

System (17) has a gradient flow structure, with functional

$$\mathbf{F}(\mu_1,\mu_2) = \frac{1}{2} \int_{\mathbb{R}^d} K_{11} * \mu_1 d\mu_1 + \frac{1}{2} \int_{\mathbb{R}^d} K_{22} * \mu_2 d\mu_2 + \int_{\mathbb{R}^d} K_{12} * \mu_2 d\mu_1.$$

The quantity

$$c_{M,\alpha} := \alpha \int x d\mu_1(x) + \int x d\mu_2(x)$$

is preserved.

Metric product structure

$$\mu = (\mu_1, \mu_2) \in \mathscr{P}_2(\mathbb{R}^d) \times \mathscr{P}_2(\mathbb{R}^d), \ W^2_{2,\alpha}(\mu, \nu) = W^2_2(\mu_1, \nu_1) + rac{1}{lpha} W^2_2(\mu_2, \nu_2).$$

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Results in the symmetrizable case

Assumptions: all the kernels K_{ij} are mildly singular and λ_{ij} -convex. We prove:

- λ convexity of the interaction energy on a suitable sub-differential structure.
- Existence, uniqueness, and stability of gradient flow solutions, by generalizing the one-species theory.
- Finite time collapse if all the kernels are of Non–Osgood type.
- Partial intermediate collapse of each species if the cross interaction kernel decays at infinity.

General case: the strategy

No gradient flow structure in general, no variational formulation. Main idea: semi-implicit version of the JKO scheme. For all $\mu \in \mathscr{P}(\mathbb{R}^d)^2$ we set

$$\mathbf{F}[\mu|\nu] = \frac{1}{2} \int_{\mathbb{R}^d} H_1 * \mu_1 d\mu_1 + \int_{\mathbb{R}^d} K_1 * \nu_2 d\mu_1 + \frac{1}{2} \int_{\mathbb{R}^d} H_2 * \mu_2 d\mu_2 + \int_{\mathbb{R}^d} K_2 * \nu_1 d\mu_2.$$

Let $\tau > 0$ be a fixed time step, and let $\mu_0 = (\mu_{0,1}, \mu_{0,2}) \in \mathscr{P}(\mathbb{R}^d)^2$ be a fixed initial pair of probability measures. For a given $\mu_n^{\tau} \in \mathscr{P}(\mathbb{R}^d)^2$, we define the sequence μ_{n+1}^{τ} as

$$\mu_{\tau}^{n+1} \in \operatorname{argmin}_{\mu \in \mathscr{P}_{2}(\mathbb{R}^{d}) \times \mathscr{P}_{2}(\mathbb{R}^{d})} \left\{ \frac{1}{2\tau} \mathcal{W}_{2}^{2}(\mu_{\tau}^{n}, \mu) + \mathbf{F}\left[\mu | \mu_{\tau}^{n}\right] \right\}.$$

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General case: the results

Existence of weak measure solutions

$$\begin{split} \frac{d}{dt} \int \phi(x) d\mu_1(x,t) &= -\frac{1}{2} \iint \nabla H_1(x-y) \cdot (\nabla \phi(x) - \nabla \phi(y)) d\mu_1(x) d\mu_1(y) \\ &- \iint \nabla K_1(x-y) \cdot \nabla \phi(x) d\mu_1(x) d\mu_2(y) \\ \frac{d}{dt} \int \psi(x) d\mu_2(x,t) &= -\frac{1}{2} \iint \nabla H_2(x-y) \cdot (\nabla \psi(x) - \nabla \psi(y)) d\mu_2(x) d\mu_2(y) \\ &- \iint \nabla K_2(x-y) \cdot \psi(x) d\mu_2(x) d\mu_1(y). \end{split}$$

as limit of the semi-implicit JKO scheme.

• Uniqueness in case H_j and K_j are $W^{2,\infty}$, via a variant of the characteristics method.

Open problems and future work

- Open problem: uniqueness in the two species system for less regular potentials.
- Many species with nonlocal aggregation and nonlinear cross-diffusion terms: segregation. Ongoing project with M. Burger and A. Stevens.
- Derivation of multi-species continuum second order models via particle methods.
- Derivation of first order systems as damping dominated limits of second order systems.

End of the talk

Thank you for your attention!