Different types of phase transitions for a simple model of alignment of oriented particles

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Goal: macroscopic description of some animal societies



- Local interactions without leader
- Emergence of macroscopic structures, phase transitions

Images 🐼 🌒 Benson Kua (flickr) and 🚱

Modeling of interacting self-propelled particles

• Vicsek *et al.* (1995). Discrete in time (interval Δt), alignment only, synchronous reorientation.

 $\frac{\mathsf{New}}{\mathsf{direction}} = \frac{\mathsf{Mean \ direction \ of \ neighboring}}{\mathsf{particles \ at \ previous \ step}} + \mathsf{Noise}$

Simulations: phase transition phenomenon, emergence of coherent structures.

• Degond-Motsch (2008).

Time-continuous version: relaxation (with constant rate ν) towards the local mean direction.

Hydrodynamic limit without phase transition phenomenon.

• Model presented here: making ν (and the intensity of the noise) a function of the (norm of the) local mean momentum.

Outline

Time-continuous Vicsek model with phase transition

- Presentation of the model
- Kinetic model Homogeneous setting
- Stability issues

Examples of different types of phase transitions

Second order (or continuous) phase transition

• First order (discontinuous) phase transition – Hysteresis

Presentation of the model Kinetic model – Homogeneous setting Stability issues

Individual dynamics

Particles at positions: X_1, \ldots, X_N in \mathbb{R}^n . Orientations $\omega_1, \ldots, \omega_N$ in \mathbb{S} (unit sphere).

$$\begin{cases} \mathrm{d}X_k = \omega_k \mathrm{d}t \\ \mathrm{d}\omega_k = \nu P_{\omega_k^{\perp}} \bar{\omega}_k \mathrm{d}t + \sqrt{2\tau} \, P_{\omega_k^{\perp}} \circ \mathrm{d}B_t^k \end{cases}$$

Target direction:

$$ar{\omega}_k = rac{J_k}{|J_k|}, \quad J_k = rac{1}{N}\sum_{j=1}^N K(X_j - X_k)\,\omega_j.$$

Setting $\nu = \nu(|J_k|)$ and $\tau = \tau(|J_k|)$, no singularity if $\frac{\nu(|J|)}{|J|}$ is Lipschitz.

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Kinetic description

Assumptions : K with finite second moment, and K, $|J| \mapsto \frac{\nu(|J|)}{|J|}$ and τ bounded Lipschitz.

Theorem (following Bolley, Cañizo, Carrillo, 2012)

Probability density function $f(x, \omega, t)$, as $N \to \infty$:

$$\begin{split} \partial_t f + \omega \cdot \nabla_x f + \nu(|\mathcal{J}_f|) \nabla_\omega \cdot (P_{\omega^{\perp}} \bar{\omega}_f f) &= \tau(|\mathcal{J}_f|) \Delta_\omega f \\ \bar{\omega}_f &= \frac{\mathcal{J}_f}{|\mathcal{J}_f|}, \quad \mathcal{J}_f = \mathcal{K} * \mathcal{J}_f, \quad \mathcal{J}_f = \int_{\omega \in \mathbb{S}} \omega f(x, \omega, t) \, \mathrm{d}\omega \,. \end{split}$$

Tool : coupling process + estimations.

$$\begin{cases} \mathrm{d}\bar{X}_{k} = \bar{\omega}_{k} \mathrm{d}t \\ \mathrm{d}\bar{\omega}_{k} = \nu(|\mathcal{J}_{f_{t}^{N}}|) P_{\omega_{k}^{\perp}} \, \bar{\omega}_{f_{t}^{N}} \, \mathrm{d}t + \sqrt{2\tau(|\mathcal{J}_{f_{t}^{N}}|)} P_{\omega_{k}^{\perp}} \circ \mathrm{d}B_{t}^{k} \\ f_{t}^{N} = \mathsf{law}(\bar{X}_{1}, \bar{\omega}_{1}) = \mathsf{law}(\bar{X}_{k}, \bar{\omega}_{k}) \end{cases}$$

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Space-homogeneous version

Reduced equation, for a function $f(\omega, t)$:

$$\partial_t f = Q(f),$$

 $Q(f) = -\nu(|J_f|)
abla_\omega \cdot (P_{\omega^\perp} \Omega_f f) + \tau(|J_f|) \Delta_\omega f$
 $\Omega_f = rac{J_f}{|J_f|}, \quad J_f(t) = \int_{\mathbb{S}} f(\omega, t) \, \omega \, \mathrm{d}\omega.$

Key parameter: the conserved quantity $\rho = \int_{\mathbb{S}} f$. Writing $h(|J|) = \frac{\nu(|J|)}{\tau(|J|)}$, we get

$$Q(f) = \tau(|J_f|) \nabla_{\omega} \cdot (e^{h(|J_f|)\omega \cdot \Omega_f} \nabla_{\omega} (e^{-h(|J_f|)\omega \cdot \Omega_f} f)).$$

Main assumption: $|J| \mapsto h(|J|)$ is increasing. Its inverse: σ .

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Equilibria

Definitions: Fisher-von Mises distribution

$$M_{\kappa\Omega}(\omega) = \frac{e^{\kappa\,\omega\cdot\Omega}}{\int_{\mathbb{S}} e^{\kappa\,\upsilon\cdot\Omega}\,\mathrm{d}\upsilon}.$$

Orientation $\Omega \in \mathbb{S}$, concentration $\kappa \ge 0$. Order parameter: $c(\kappa) = |J_{M_{\kappa\Omega}}| = \frac{\int_0^{\pi} \cos \theta \, e^{\kappa \cos \theta} \sin^{n-2} \theta \, \mathrm{d}\theta}{\int_0^{\pi} e^{\kappa \cos \theta} \sin^{n-2} \theta \, \mathrm{d}\theta}$.

For $\kappa_f = h(|J_f|)$, we can write Q under the form:

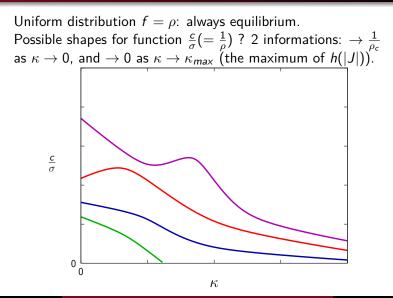
$$Q(f) = au(|J_f|)
abla_\omega \cdot \left[M_{\kappa_f \Omega_f}
abla_\omega \left(rac{f}{M_{\kappa_f \Omega_f}}
ight)
ight].$$

Equilibria: $f_{eq} = \rho M_{\kappa\Omega}$, for some $\Omega \in \mathbb{S}$. Then $|J_{f_{eq}}| = \rho |J_{M_{\kappa\Omega}}| = \rho c(\kappa)$, and $\kappa = \kappa_{f_{eq}} = h(|J_{f_{eq}}|)$.

Compatibility condition: $\kappa = h(\rho c(\kappa))$, i.e. $\sigma(\kappa) = \rho c(\kappa)$.

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Solutions to the compatibility condition



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Existence, uniqueness, regularity, positivity, bounds

Theorem

For an initial probability measure $f_0 \in H^s(\mathbb{S})$, (for an arbitrary s):

- Existence and uniqueness of a weak solution f.
- Global solution, in $C^{\infty}(\mathbb{R}^*_+ \times \mathbb{S})$, and f > 0 for t > 0.
- Instantaneous regularity estimates and uniform bounds:

$$\|f(t)\|_{H^{s+m}}^2 \leqslant C\left(1+\frac{1}{t^m}\right) \|f_0\|_{H^s}^2.$$

Tool: spherical harmonics decomposition. Nonlinearity: finite number of coefficients.

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Main tool: Onsager free energy

Free energy: $\mathcal{F}(f) = \int_{\mathbb{S}} f \ln f - \Phi(|J_f|)$, with $\frac{\mathrm{d}\Phi}{\mathrm{d}|J|} = h(|J|)$. Dissipation: $\mathcal{D}(f) = \tau(|J_f|) \int_{\mathbb{S}} f |\nabla_{\omega}(\ln f - h(|J_f|)\omega \cdot \Omega_f)|^2 \ge 0$.

$$rac{\mathrm{d}}{\mathrm{d}t}\mathcal{F}+\mathcal{D}=0 \quad \Rightarrow \mathcal{F}(f) ext{ decreasing towards } \mathcal{F}_{\infty}.$$

LaSalle's principle

$$\text{Limit set: } \mathcal{E}_{\infty} = \{f \in C^{\infty}(\mathbb{S}) | \mathcal{D}(f) = 0 \text{ and } \mathcal{F}(f) = \mathcal{F}_{\infty} \}.$$

$$\lim_{t\to\infty}\inf_{g\in\mathcal{E}_{\infty}}\|f(t)-g\|_{H^s}=0.$$

Refined: if the roots of $\sigma(\kappa) = \rho c(\kappa)$ are isolated, there exists a solution κ_{∞} such that:

$$\lim_{t\to\infty}|J_f(t)|=\rho c(\kappa_\infty)\quad\text{and}\quad\forall s\in\mathbb{R},\lim_{t\to\infty}\|f(t)-\rho M_{\kappa_\infty\Omega_f(t)}\|_{H^s}=0.$$

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Local analysis near uniform equilibria

Critical value:
$$ho_{m{c}} = \lim_{\kappa o 0} rac{\sigma(\kappa)}{c(\kappa)} \in (0,+\infty].$$

Theorem: Strong unstability – Exponential stability

- $\rho > \rho_c$: if $J_{f_0} \neq 0$, then f cannot converge to the uniform equilibrium.
- $\rho < \rho_c$: There exists a universal constant δ such that if $\|f_0 \rho\|_{H^s} < \delta$, then we have for all $t \ge 0$

$$\|f(t) - \rho\|_{H^s} \leqslant rac{\|f_0 - \rho\|_{H^s} e^{-\lambda t}}{1 - rac{1}{\delta} \|f_0 - \rho\|_{H^s}}, ext{ with } \lambda = (n-1) au_0(1 - rac{
ho}{
ho_c}).$$

Tools: linearization for the evolution of J_f , and then energy estimates for the whole equation.

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Around a nonisotropic equilibria $\rho M_{\kappa\Omega}$

Proposition: weak stability/unstability

We denote by \mathcal{F}_{κ} the value of $\mathcal{F}(\rho M_{\kappa\Omega})$ (independent of $\Omega \in \mathbb{S}$).

- $(\frac{\sigma}{c})'(\kappa) < 0$ (unstable): in any neighborhood of $\rho M_{\kappa\Omega}$, there exists f_0 such that $\mathcal{F}(f_0) < \mathcal{F}_{\kappa}$.
- $(\frac{\sigma}{c})'(\kappa) > 0$ (stable): If $||f_0||_{H^s} \leq K$, with $s > \frac{n-1}{2}$, then there exists $\delta > 0$ and C (depending only on K and s), such that if $||f_0 \rho M_{\kappa\Omega}||_{L^2} \leq \delta$ for some $\Omega \in \mathbb{S}$, then for all $t \ge 0$, we have

$$\mathcal{F}(f) \geqslant \mathcal{F}_{\kappa}, \text{ and } \|f - \rho M_{\kappa \Omega_f}\|_{L^2} \leqslant C \|f_0 - \rho M_{\kappa \Omega_{f_0}}\|_{L^2}.$$

Tools: expansion of $\mathcal{F} - \mathcal{F}_{\kappa}$, and Sobolev interpolation.

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Stronger stability: exponential convergence to equilibrium

Theorem: exponential stability in case $\left(\frac{\sigma}{c}\right)'(\kappa) > 0$

For all $s > \frac{n-1}{2}$, there exist universal constants $\delta > 0$ and C > 0, such that if $\|f_0 - \rho M_{\kappa\Omega}\|_{H^s} < \delta$ for some $\Omega \in \mathbb{S}$, there exists $\Omega_{\infty} \in \mathbb{S}$ such that

$$\|f - \rho M_{\kappa\Omega_{\infty}}\|_{H^s} \leqslant C \|f_0 - \rho M_{\kappa\Omega_{f_0}}\|_{H^s} e^{-\lambda t},$$

with

$$\lambda = \frac{c\tau(\sigma)}{\sigma'}\Lambda_{\kappa}(\frac{\sigma}{c})',$$

where Λ_{κ} is the best constant for the following weighted Poincaré inequality:

$$\langle |
abla g|^2
angle_{M_{\kappa\Omega}} \geqslant \Lambda_\kappa \langle (g - \langle g
angle_{M_{\kappa\Omega}})^2
angle_{M_{\kappa\Omega}}$$

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General statements in the case $\left(\frac{\sigma}{c}\right)' > 0$ for all κ

- If $\rho < \rho_c$, then the solution converges exponentially fast towards the uniform distribution $f_{\infty} = \rho$.
- $\bullet~{\rm If}~\rho=\rho_{\rm c},$ the solution converges to the uniform distribution.
- If $\rho > \rho_c$ and $J_{f_0} \neq 0$, then there exists Ω_{∞} such that f converges exponentially fast to the von Mises distribution $f_{\infty} = \rho M_{\kappa \Omega_{\infty}}$, where $\kappa > 0$ is the unique positive solution to the equation $\rho c(\kappa) = \sigma(\kappa)$.

We can then define c (order parameter) as a function of ρ , and this function is continuous.

Critical exponent β : when $c(\rho) \asymp (\rho - \rho_c)^{\beta}$. Can be any number in (0, 1], as one can artificially choose $\sigma(\kappa) = c(\kappa)(1 + \kappa^{\frac{1}{\beta}})$.

Practical criteria for continuous phase transition

Lemma

If $\frac{h(|J|)}{|J|}$ is a nonincreasing function of |J|, then we are in the previous case of a continuous phase transition. In that case, the critical exponent β , if it exists, can only take values in $[\frac{1}{2}, 1]$.

In that case, we also have a special cancellation (related to the so-called conformal Laplacian), which gives global exponential decay when $\rho < \rho_c$:

Proposition

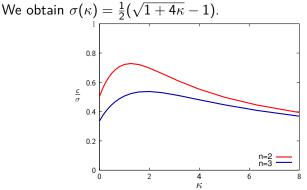
If $\rho < \rho_{\rm c},$ there exists a universal constant C such that we have for all $t \geqslant 0$

$$\|f(t)-
ho\|_{H^s}\leqslant C\|f_0-
ho\|_{H^s}e^{-\lambda t}, ext{ with } \lambda=(n-1) au_{min}(1-rac{
ho}{
ho_c}).$$

A special example

Focus:
$$\nu(|J|) = |J|$$
 and $\tau(|J|) = \frac{1}{1+|J|}$ (related to the so-called "extrinsic noise").

In that case, we get $h(|J|) = |J| + |J|^2$, so we are not indeed in the previous case.

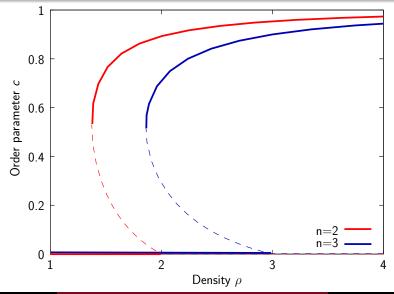


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Alignment interaction with different types of phase transitions

Second order (or continuous) phase transition First order (discontinuous) phase transition – Hysteresis

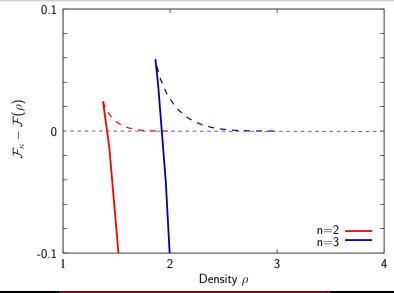
The phase diagram



Alignment interaction with different types of phase transitions

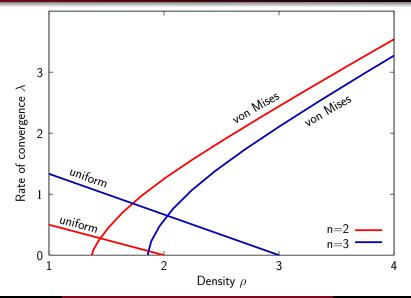
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Comparison of Free energy levels



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Rates of convergence



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Numerical illustration of the hysteresis phenomena

Change of scale $\tilde{f} = \frac{f}{\rho}$. The parameter ρ can now be considered as a free parameter that we let evolve in time.

