

Hyperbolizing Surfaces

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- Influenced by S. Lie, in his 1872 *Erlangen Program*, F. Klein proposed that a *geometry* is the study of properties of an abstract space X which are invariant under a transitive group G of transformations of X .

Geometry through symmetry

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 - *Algebraicization of geometry*: Many diverse geometries — homogeneous spaces G/H — classified by Lie groups and Lie algebras.

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 - Examples: Euclidean, hyperbolic, projective, affine, conformal, constant curvature Lorentzian ..

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 - *Algebraicization of geometry*: Many diverse geometries — homogeneous spaces G/H — classified by Lie groups and Lie algebras.
 - Examples: Euclidean, hyperbolic, projective, affine, conformal, constant curvature Lorentzian ..
- .
- Group theory arises in topology through the *fundamental group* and the *universal covering space*.

Putting geometric structure on a topological space

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- *Topology:* Smooth manifold M , coordinate patches U_α ;

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- *Topology*: Smooth manifold M , coordinate patches U_α ;
- Charts — *diffeomorphisms*

$$U_\alpha \xrightarrow{\psi_\alpha} \psi_\alpha(U_\alpha) \subset X$$

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$$U_\alpha \xrightarrow{\psi_\alpha} \psi_\alpha(U_\alpha) \subset X$$

- For each component $C \subset U_\alpha \cap U_\beta$, $\exists g = g(C) \in G$:

$$g \circ \psi_\alpha|_C = \psi_\beta|_C.$$

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- Well-defined local (G, X) -geometry defined by ψ_α .

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- Well-defined local (G, X) -geometry defined by ψ_α .
- Σ acquires *geometric structure* M modeled on (G, X) .
(Ehresmann 1936)

Development

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- Globalize the G -compatible coordinate charts are to a *development*: a local diffeomorphism

$$\tilde{\Sigma} \longrightarrow X$$

equivariant with respect to a *holonomy representation*

$$\pi_1(\Sigma) \xrightarrow{\rho} G$$

which is well-defined up to conjugation in G .

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- The space of *marked structures* on a fixed topology Σ forms a *deformation space* locally modeled on $\text{Hom}(\pi_1, G)/G$ (Thurston 1978):

$$\mathcal{D}_{(G, X)}(\Sigma) := \left\{ \text{Marked } (G, X)\text{-structures on } \Sigma \right\} / \text{Isotopy}$$

$$\xrightarrow{\text{hol}} \text{Hom}(\pi_1(\Sigma), G)/G$$

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- Many cases: when $M = \Omega/\Gamma$, where $\Omega \subset X$ is a domain and $\Gamma \subset G$ is discrete acting properly on Ω , the restriction of hol is an embedding.

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- Euclidean structures;

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- Many cases: when $M = \Omega/\Gamma$, where $\Omega \subset X$ is a domain and $\Gamma \subset G$ is discrete acting properly on Ω , the restriction of hol is an embedding.
- Euclidean structures;
- Hyperbolic structures;

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- Euclidean structures;
- Hyperbolic structures;
- Complete affine structures (includes Euclidean structures);

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- Euclidean structures;
- Hyperbolic structures;
- Complete affine structures (includes Euclidean structures);
- Complex projective structures (includes hyperbolic structures via Poincaré disk, Euclidean, elliptic);

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- Many cases: when $M = \Omega/\Gamma$, where $\Omega \subset X$ is a domain and $\Gamma \subset G$ is discrete acting properly on Ω , the restriction of hol is an embedding.
- Euclidean structures;
- Hyperbolic structures;
- Complete affine structures (includes Euclidean structures);
- Complex projective structures (includes hyperbolic structures via Poincaré disk, Euclidean, elliptic);
- Real projective structures (hyperbolic structures via Klein model, Euclidean, elliptic).

Representations of surface groups

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Σ closed oriented surface, $\chi(\Sigma) < 0$, fundamental group
 $\pi = \pi_1(\Sigma)$; G algebraic Lie group.

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 - Algebraic structure on $\text{Hom}(\pi, G)$ invariant under the natural action of $\text{Aut}(\pi) \times \text{Aut}(G)$:

$$\pi \longrightarrow \pi \xrightarrow{\rho} G \longrightarrow G.$$

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- *Mapping class group*

$$\text{Mod}(\Sigma) = \pi_0(\text{Diff}(\Sigma)) \cong \text{Out}(\pi) = \text{Aut}(\pi)/\text{Inn}(\pi)$$

acts on $\text{Hom}(\pi, G)/G$.

The fundamental group of a closed surface

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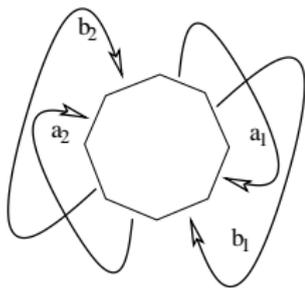
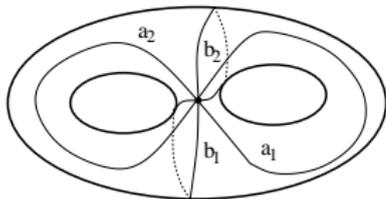
$SL(2, \mathbb{C})$

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Obtain a genus g surface from a $4g$ -gon.



A presentation for the fundamental group

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- The fundamental group $\pi = \pi_1(\Sigma)$ is the fundamental group of a closed orientable surface admits a presentation

$$\pi = \langle A_1, \dots, B_g \mid A_1 B_1 A_1^{-1} B_1^{-1} \dots A_g B_g A_g^{-1} B_g^{-1} = 1 \rangle$$

A presentation for the fundamental group

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- A representation $\pi_1(\Sigma)$ in a group G is just

$$(\alpha_1, \dots, \beta_g) \in G^{2g}$$

satisfying the *defining relation*

$$\alpha_1 \beta_1 \alpha_1^{-1} \beta_1^{-1} \dots \alpha_g \beta_g \alpha_g^{-1} \beta_g^{-1} = 1.$$

Navigating the deformation space

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Associated to simple closed curves $\alpha \subset \Sigma$ are *generalized twist deformations*, paths in $\text{Hom}(\pi, G)$ supported on α .

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Associated to simple closed curves $\alpha \subset \Sigma$ are *generalized twist deformations*, paths in $\text{Hom}(\pi, G)$ supported on α .

- Example: if α is the nonseparating simple loop A_1 ,

$$\rho_t : \begin{cases} A_i & \mapsto \rho(A_i) \text{ if } i \geq 1 \\ B_j & \mapsto \rho(B_j) \text{ if } j > 1 \\ B_1 & \mapsto \rho(B_1)\zeta(t) \end{cases}$$

where $\zeta(t)$ path in the centralizer of $\rho(A_1)$.

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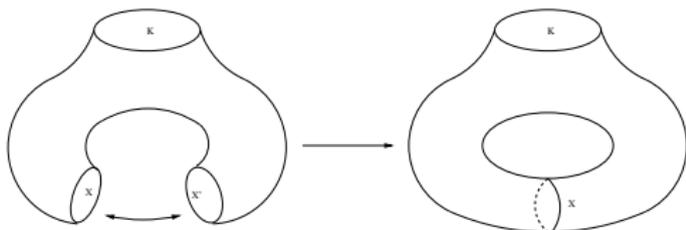
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where $\zeta(t)$ path in the centralizer of $\rho(A_1)$.

- *Fenchel-Nielsen twist flow*: ($G = SL(2, \mathbb{R})$): $\zeta(t)$ group of *transvections* along $\rho(A_1)$ -invariant geodesic in H^2 —



Observing the deformation space

- A natural class of functions on $\text{Hom}(\pi, G)/G$ arise from functions $G \xrightarrow{f} \mathbb{R}$ invariant under conjugation and $\alpha \in \pi$:

$$\begin{aligned} \text{Hom}(\pi, G)/G &\xrightarrow{f_\alpha} \mathbb{R} \\ [\rho] &\longmapsto f(\rho(\gamma)) \end{aligned}$$

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- The *trace* of any linear representation $G \longrightarrow GL(N, \mathbb{R})$

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$$\begin{aligned} \text{Hom}(\pi, G)/G &\xrightarrow{f_\alpha} \mathbb{R} \\ [\rho] &\longmapsto f(\rho(\gamma)) \end{aligned}$$

- The *trace* of any linear representation $G \longrightarrow GL(N, \mathbb{R})$
- The *geodesic displacement function* (only defined for hyperbolic elements)

$$\text{tr}(\gamma) = \pm 2 \cosh(\ell(\gamma)/2)$$

if $\gamma \in SL(2, \mathbb{R})$ is hyperbolic.

Symplectic structure

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- Ad-invariant inner product on $\mathfrak{g} \implies \text{Mod}(\Sigma)$ -invariant *symplectic structure* on $\text{Hom}(\pi, G)/G$.

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- $G = \mathbb{R}$ or $\mathbb{C} \implies \text{Hom}(\pi, G)$ is a real (or complex) *symplectic vector space* $H^1(\Sigma)$.

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- $G = \mathbb{R}$ or $\mathbb{C} \implies \text{Hom}(\pi, G)$ is a real (or complex) *symplectic vector space* $H^1(\Sigma)$.
- α represented by a simple closed curve on Σ ,

$\text{Inn}(G)$ -invariant function $G \xrightarrow{f} \mathbb{R}$

\implies Hamiltonian flow of f_α covered by *generalized twist flow* on $\text{Hom}(\pi, G)$.

Fricke space

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- Deformation space $\mathfrak{F}(\Sigma)$ of marked hyperbolic structures Σ corresponds to *discrete embeddings*:

$$\pi := \pi_1(\Sigma) \xrightarrow{\rho} \mathrm{PSL}(2, \mathbb{R})$$

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$$\pi := \pi_1(\Sigma) \xrightarrow{\rho} \mathrm{PSL}(2, \mathbb{R})$$

- Components of $\mathrm{Hom}(\pi, \mathrm{PSL}(2, \mathbb{R}))$ detected by the *Euler class* of the associated oriented $\mathbb{R}P^1$ -bundle over Σ :

$$\mathrm{Hom}(\pi, \mathrm{PSL}(2, \mathbb{R})) \xrightarrow{e} H^2(\Sigma, \mathbb{Z}) \cong \mathbb{Z}.$$

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- $|e(\rho)| \leq |\chi(\Sigma)|$ (Milnor 1958, Wood 1971)

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- Deformation space $\mathfrak{F}(\Sigma)$ of marked hyperbolic structures Σ corresponds to *discrete embeddings*:

$$\pi := \pi_1(\Sigma) \xrightarrow{\rho} PSL(2, \mathbb{R})$$

- Components of $\text{Hom}(\pi, PSL(2, \mathbb{R}))$ detected by the *Euler class* of the associated oriented $\mathbb{R}P^1$ -bundle over Σ :

$$\text{Hom}(\pi, PSL(2, \mathbb{R})) \xrightarrow{e} H^2(\Sigma, \mathbb{Z}) \cong \mathbb{Z}.$$

- $|e(\rho)| \leq |\chi(\Sigma)|$ (Milnor 1958, Wood 1971)
- Equality $\iff \rho$ is a discrete embedding. (1980)

Branched hyperbolic structures

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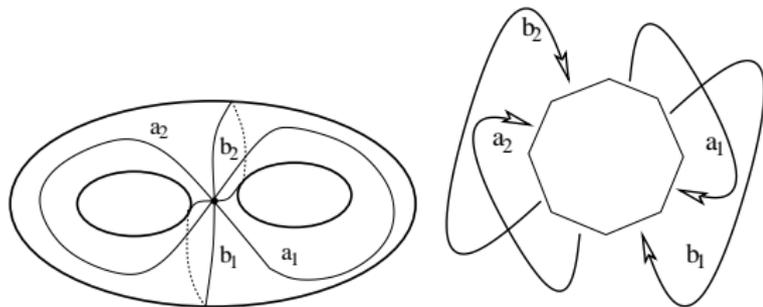
$SL(2, \mathbb{R})$

$SL(2, \mathbb{C})$

$SU(2, 1)$

$SL(3, \mathbb{R})$

$Aff(2, \mathbb{R})$



Branched hyperbolic structures

Hyperbolizing
Surfaces

Geometric
structures

Surface groups

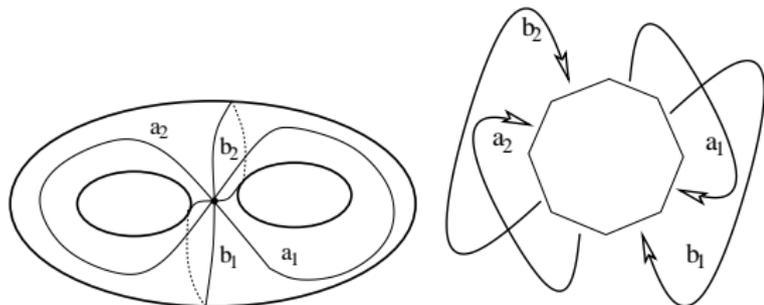
$SL(2, \mathbb{R})$

$SL(2, \mathbb{C})$

$SU(2, 1)$

$SL(3, \mathbb{R})$

$Aff(2, \mathbb{R})$



- Interior angles sum to $2\pi k$, ($k \in \mathbb{Z}$) \implies quotient space is hyperbolic surface with one singularity (the image of the vertex) with cone angle $2\pi k$.

Branched hyperbolic structures

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Surface groups

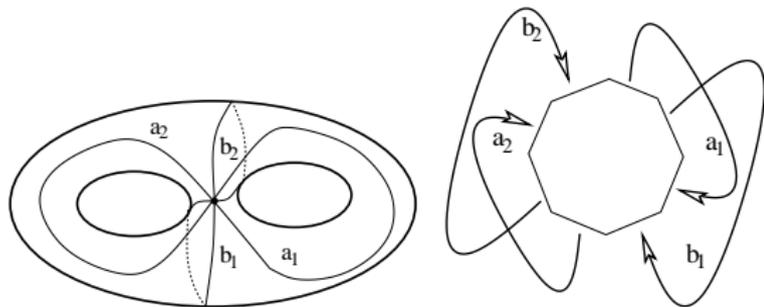
$SL(2, \mathbb{R})$

$SL(2, \mathbb{C})$

$SU(2, 1)$

$SL(3, \mathbb{R})$

$Aff(2, \mathbb{R})$



- Interior angles sum to $2\pi k$, ($k \in \mathbb{Z}$) \implies quotient space is hyperbolic surface with one singularity (the image of the vertex) with cone angle $2\pi k$.
- Holonomy representation of a hyperbolic surface with cone angles $2\pi k_i$ extends to $\pi_1(\Sigma)$ with Euler number

$$e(\rho) = 2 - 2g + \sum k_i.$$

A hyperbolic surface of genus two

Hyperbolizing
Surfaces

Geometric
structures

Surface groups

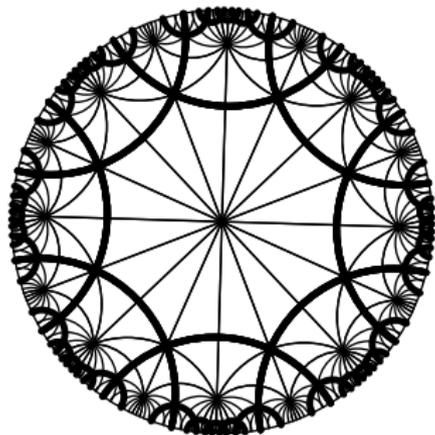
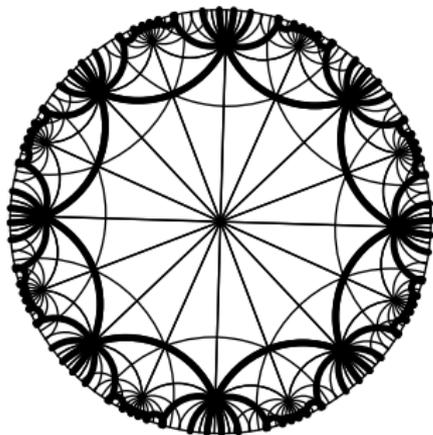
$SL(2, \mathbb{R})$

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A hyperbolic surface of genus two

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Surface groups

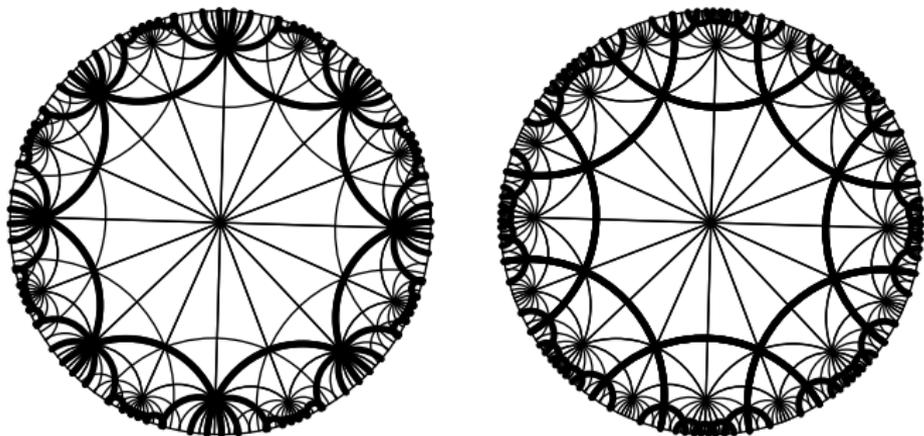
$SL(2, \mathbb{R})$

$SL(2, \mathbb{C})$

$SU(2, 1)$

$SL(3, \mathbb{R})$

$Aff(2, \mathbb{R})$



- Identifying a regular octagon with angles $\pi/4$ yields a nonsingular hyperbolic surface with $e(\rho) = \chi(\Sigma) = -2$.

A hyperbolic surface of genus two

Hyperbolizing
Surfaces

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structures

Surface groups

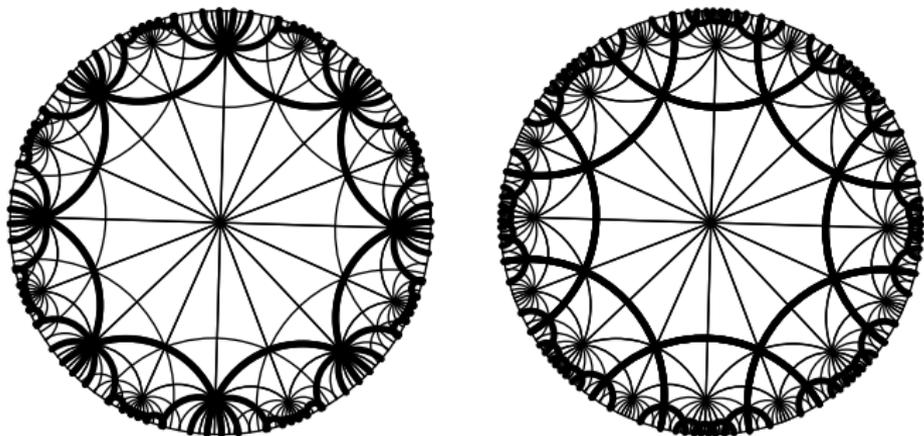
$SL(2, \mathbb{R})$

$SL(2, \mathbb{C})$

$SU(2, 1)$

$SL(3, \mathbb{R})$

$Aff(2, \mathbb{R})$



- Identifying a regular octagon with angles $\pi/4$ yields a nonsingular hyperbolic surface with $e(\rho) = \chi(\Sigma) = -2$.
- But when the angles are $\pi/2$, the surface has one singularity with cone angle 4π and

$$e(\rho) = 1 + \chi(\Sigma) = -1.$$

Branched hyperbolic structures

Hyperbolizing
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Surface groups

$SL(2, \mathbb{R})$

$SL(2, \mathbb{C})$

$SU(2, 1)$

$SL(3, \mathbb{R})$

$Aff(2, \mathbb{R})$

- Each component of $\text{Hom}(\pi, \text{PSL}(2, \mathbb{R}))$ contains holonomy of branched hyperbolic structures.

Branched hyperbolic structures

Hyperbolizing
Surfaces

Geometric
structures

Surface groups

$SL(2, \mathbb{R})$

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$SL(3, \mathbb{R})$

$Aff(2, \mathbb{R})$

- Each component of $\text{Hom}(\pi, \text{PSL}(2, \mathbb{R}))$ contains holonomy of branched hyperbolic structures.
- The Euler class $2 - 2g + k$ component deformation retracts onto k -fold symmetric product. (Hitchin 1987)

Dynamic/homotopic triviality

Hyperbolizing
Surfaces

Geometric
structures

Surface groups

$SL(2, \mathbb{R})$

$SL(2, \mathbb{C})$

$SU(2, 1)$

$SL(3, \mathbb{R})$

$Aff(2, \mathbb{R})$

- Discrete embeddings determine connected component of $\text{Hom}(\pi, \text{PSL}(2, \mathbb{R}))/\text{PGL}(2, \mathbb{R})$.

Dynamic/homotopic triviality

Hyperbolizing
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Geometric
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$Aff(2, \mathbb{R})$

- Discrete embeddings determine connected component of $\text{Hom}(\pi, \text{PSL}(2, \mathbb{R}))/\text{PGL}(2, \mathbb{R})$.
 - $\mathfrak{F}(\Sigma) \approx \mathbb{R}^{6g-6}$.

Dynamic/homotopic triviality

Hyperbolizing Surfaces

Geometric structures

Surface groups

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 - $\text{Mod}(\Sigma)$ acts properly discretely on $\mathfrak{F}(\Sigma)$.

Dynamic/homotopic triviality

Hyperbolizing
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Geometric
structures

Surface groups

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$Aff(2, \mathbb{R})$

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 - $\mathfrak{F}(\Sigma) \approx \mathbb{R}^{6g-6}$.
 - $\text{Mod}(\Sigma)$ acts properly discretely on $\mathfrak{F}(\Sigma)$.
- *Uniformization theorem* identifies $\mathfrak{F}(\Sigma)$ with *Teichmüller space* of marked *conformal structures* on Σ .

Dynamic/homotopic triviality

Hyperbolizing Surfaces

Geometric structures

Surface groups

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 - $\text{Mod}(\Sigma)$ -invariant complex structure on $\mathfrak{F}(\Sigma)$.

Dynamic/homotopic triviality

Hyperbolizing
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structures

Surface groups

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$SL(2, \mathbb{C})$

$SU(2, 1)$

$SL(3, \mathbb{R})$

$Aff(2, \mathbb{R})$

- Discrete embeddings determine connected component of $\text{Hom}(\pi, \text{PSL}(2, \mathbb{R}))/\text{PGL}(2, \mathbb{R})$.
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- *Uniformization theorem* identifies $\mathfrak{F}(\Sigma)$ with *Teichmüller space* of marked *conformal structures* on Σ .
 - $\text{Mod}(\Sigma)$ -invariant complex structure on $\mathfrak{F}(\Sigma)$.
 - For $G = \text{PSL}(2, \mathbb{R})$, the general symplectic structure and the complex structure from Teichmüller space are part of the *Weil-Petersson* Kähler geometry on $\mathfrak{F}(\Sigma)$.

Quasi-Fuchsian groups

Hyperbolizing
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Geometric
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Surface groups

$SL(2, \mathbb{R})$

$SL(2, \mathbb{C})$

$SU(2, 1)$

$SL(3, \mathbb{R})$

$Aff(2, \mathbb{R})$

The group of orientation-preserving isometries of $H_{\mathbb{R}}^3$ equals $PSL(2, \mathbb{C})$. Close to Fuchsian representations in $PSL(2, \mathbb{R})$ are *quasi-Fuchsian representations* $Q\mathcal{F}$:

Quasi-Fuchsian groups

Hyperbolizing
Surfaces

Geometric
structures

Surface groups

$SL(2, \mathbb{R})$

$SL(2, \mathbb{C})$

$SU(2, 1)$

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$Aff(2, \mathbb{R})$

The group of orientation-preserving isometries of $H_{\mathbb{R}}^3$ equals $PSL(2, \mathbb{C})$. Close to Fuchsian representations in $PSL(2, \mathbb{R})$ are *quasi-Fuchsian representations* $Q\mathcal{F}$:

- Discrete embeddings;

Quasi-Fuchsian groups

Hyperbolizing
Surfaces

Geometric
structures

Surface groups

$SL(2, \mathbb{R})$

$SL(2, \mathbb{C})$

$SU(2, 1)$

$SL(3, \mathbb{R})$

$Aff(2, \mathbb{R})$

The group of orientation-preserving isometries of $H_{\mathbb{R}}^3$ equals $PSL(2, \mathbb{C})$. Close to Fuchsian representations in $PSL(2, \mathbb{R})$ are *quasi-Fuchsian representations* $Q\mathcal{F}$:

- Discrete embeddings;
- Topologically conjugate action on S^2 ;

Quasi-Fuchsian groups

Hyperbolizing
Surfaces

Geometric
structures

Surface groups

$SL(2, \mathbb{R})$

$SL(2, \mathbb{C})$

$SU(2, 1)$

$SL(3, \mathbb{R})$

$Aff(2, \mathbb{R})$

The group of orientation-preserving isometries of $H_{\mathbb{R}}^3$ equals $PSL(2, \mathbb{C})$. Close to Fuchsian representations in $PSL(2, \mathbb{R})$ are *quasi-Fuchsian representations* $Q\mathcal{F}$:

- Discrete embeddings;
- Topologically conjugate action on S^2 ;
- $Q\mathcal{F} \approx \mathbb{R}^{12g-12}$,

Quasi-Fuchsian groups

Hyperbolizing
Surfaces

Geometric
structures

Surface groups

$SL(2, \mathbb{R})$

$SL(2, \mathbb{C})$

$SU(2, 1)$

$SL(3, \mathbb{R})$

$Aff(2, \mathbb{R})$

The group of orientation-preserving isometries of $H_{\mathbb{R}}^3$ equals $PSL(2, \mathbb{C})$. Close to Fuchsian representations in $PSL(2, \mathbb{R})$ are *quasi-Fuchsian representations* $Q\mathcal{F}$:

- Discrete embeddings;
- Topologically conjugate action on S^2 ;
- $Q\mathcal{F} \approx \mathbb{R}^{12g-12}$,
- $Mod(\Sigma)$ acts properly on $Q\mathcal{F}$.

Discrete embeddings in $\mathrm{PSL}(2, \mathbb{C})$

Hyperbolizing
Surfaces

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structures

Surface groups

$\mathrm{SL}(2, \mathbb{R})$

$\mathrm{SL}(2, \mathbb{C})$

$\mathrm{SU}(2, 1)$

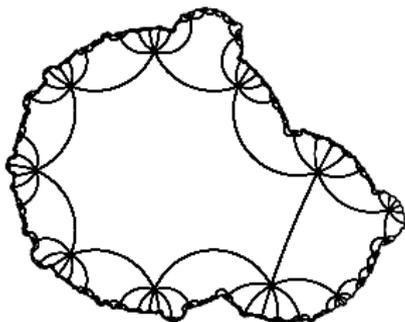
$\mathrm{SL}(3, \mathbb{R})$

$\mathrm{Aff}(2, \mathbb{R})$

- $\mathrm{Hom}(\pi, \mathrm{SL}(2, \mathbb{C}))$ is connected, closure of $Q\mathcal{F}$ consists of all discrete embeddings.

Discrete embeddings in $\mathrm{PSL}(2, \mathbb{C})$

- $\mathrm{Hom}(\pi, \mathrm{SL}(2, \mathbb{C}))$ is connected, closure of \mathcal{QF} consists of all discrete embeddings.
- Discrete embeddings *not open*; *not* comprise a component of $\mathrm{Hom}(\pi, G)$.



Complex hyperbolic geometry

Hyperbolizing
Surfaces

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structures

Surface groups

$SL(2, \mathbb{R})$

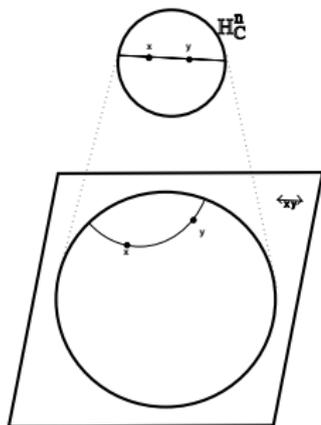
$SL(2, \mathbb{C})$

$SU(2, 1)$

$SL(3, \mathbb{R})$

$Aff(2, \mathbb{R})$

- Complex hyperbolic space $H_{\mathbb{C}}^n$ is the unit ball in \mathbb{C}^n with the *Bergman metric* invariant under the projective transformations in $\mathbb{C}P^n$.



Complex hyperbolic geometry

Hyperbolizing
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structures

Surface groups

$SL(2, \mathbb{R})$

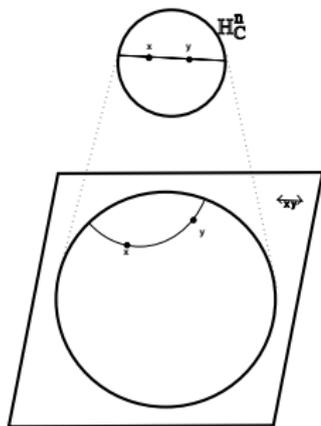
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$Aff(2, \mathbb{R})$

- Complex hyperbolic space $H_{\mathbb{C}}^n$ is the unit ball in \mathbb{C}^n with the *Bergman metric* invariant under the projective transformations in $\mathbb{C}P^n$.



- \mathbb{C} - linear subspaces meet $H_{\mathbb{C}}^n$ in totally geodesic subspaces.

Deforming discrete groups

Hyperbolizing
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Surface groups

$SL(2, \mathbb{R})$

$SL(2, \mathbb{C})$

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$Aff(2, \mathbb{R})$

- Start with a Fuchsian representation $\pi \xrightarrow{\rho_0} U(1, 1)$ acting on a *complex geodesic* $H_{\mathbb{C}}^1 \subset H_{\mathbb{C}}^n$.

Deforming discrete groups

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structures

Surface groups

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$Aff(2, \mathbb{R})$

- Start with a Fuchsian representation $\pi \xrightarrow{\rho_0} U(1, 1)$ acting on a *complex geodesic* $H_{\mathbb{C}}^1 \subset H_{\mathbb{C}}^n$.
- Every *nearby* deformation $\pi \xrightarrow{\rho} U(n, 1)$ stabilizes a complex geodesic, conjugate to a *Fuchsian* representation

$$\pi \xrightarrow{\rho} U(1, 1) \times U(n-1) \subset U(n, 1).$$

Deforming discrete groups

Hyperbolizing
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structures

Surface groups

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$$\pi \xrightarrow{\rho} U(1, 1) \times U(n-1) \subset U(n, 1).$$

- Components detected by a \mathbb{Z} -valued *characteristic* class generalizing the Euler class. (Toledo 1986, Xia 1997, Gothen 1997)

Singularities in the deformation space

Hyperbolizing
Surfaces

Geometric
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Surface groups

$SL(2, \mathbb{R})$

$SL(2, \mathbb{C})$

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$SL(3, \mathbb{R})$

$Aff(2, \mathbb{R})$

- *Singular points* in $\text{Hom}(\pi, G)$!

Singularities in the deformation space

Hyperbolizing
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$SL(2, \mathbb{C})$

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$Aff(2, \mathbb{R})$

- *Singular points* in $\text{Hom}(\pi, G)$!
- In general the analytic germ of a *reductive representation* of the fundamental group of a compact Kähler manifold is defined by a system of homogeneous quadratic equations. (G Millson 1988)

Singularities in the deformation space

Hyperbolizing
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- *Singular points* in $\text{Hom}(\pi, G)$!
- In general the analytic germ of a *reductive representation* of the fundamental group of a compact Kähler manifold is defined by a system of homogeneous quadratic equations. (G Millson 1988)
- For an $SU(1, 1)$ -representation ρ_0 , the neighborhood of

$$\pi \xrightarrow{\rho} SU(1, 1) \subset SU(2, 1)$$

in $\text{Hom}(\pi, SU(2, 1))$ looks like the product of $\text{Hom}(\pi, U(1, 1) \times U(1))$ and a cone defined by a quadratic form of signature $e(\rho_0)$ on \mathbb{R}^{4g-4} .

Real projective geometry

Hyperbolizing
Surfaces

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Surface groups

$SL(2, \mathbb{R})$

$SL(2, \mathbb{C})$

$SU(2, 1)$

$SL(3, \mathbb{R})$

$Aff(2, \mathbb{R})$

- A *convex \mathbb{RP}^2 -surface* is a quotient $M = \Omega/\Gamma$ where $\Omega \subset \mathbb{RP}^2$ is a convex domain and $\Gamma \subset \text{Aut}(\Omega)$ discrete, acting properly and freely on Ω .

Real projective geometry

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Geometric structures

Surface groups

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$SL(2, \mathbb{C})$

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- $\chi(M) < 0$ and $\partial M = \emptyset \implies \partial\Omega$ is C^1 strictly convex curve. (Benzecri 1960)

Real projective geometry

Hyperbolizing Surfaces

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- $\partial\Omega$ is $C^2 \iff \partial\Omega$ is a conic. (Kuiper 1956)

Real projective geometry

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Surface groups

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- $\partial\Omega$ is $C^2 \iff \partial\Omega$ is a conic. (Kuiper 1956)
 $\iff \mathbb{RP}^2$ -structure is *hyperbolic*.

Deformations of triangle groups

Hyperbolizing
Surfaces

Geometric
structures

Surface groups

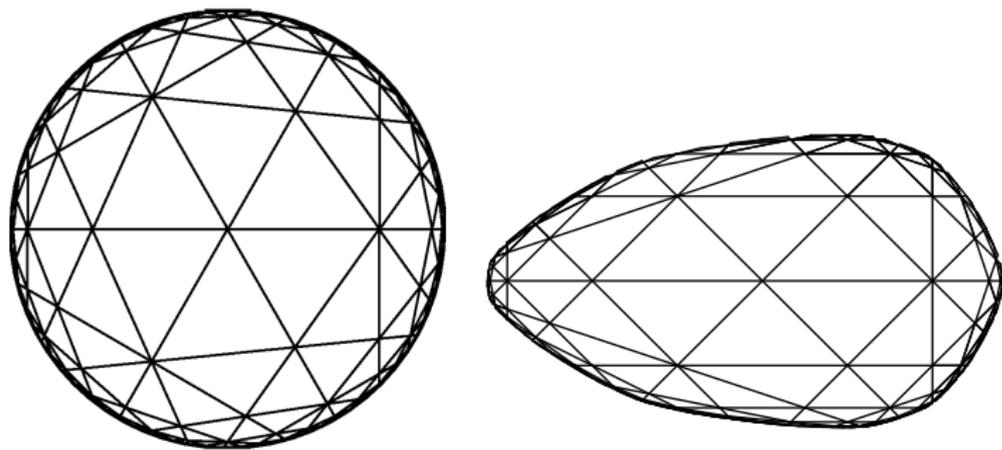
$SL(2, \mathbb{R})$

$SL(2, \mathbb{C})$

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$SL(3, \mathbb{R})$

$Aff(2, \mathbb{R})$



Domains in \mathbb{RP}^2 tiled by $(3,3,4)$ -triangles.

The deformation space of convex \mathbb{RP}^2 -structures

Hyperbolizing
Surfaces

Geometric
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Surface groups

$SL(2, \mathbb{R})$

$SL(2, \mathbb{C})$

$SU(2, 1)$

$SL(3, \mathbb{R})$

$Aff(2, \mathbb{R})$

- The deformation space $\mathcal{C}(\Sigma) \approx \mathbb{R}^{16g-16}$ upon which $\text{Mod}(\Sigma)$ acts properly. (1988)

The deformation space of convex \mathbb{RP}^2 -structures

Hyperbolizing
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- The deformation space $\mathcal{C}(\Sigma) \approx \mathbb{R}^{16g-16}$ upon which $\text{Mod}(\Sigma)$ acts properly. (1988)
- $\mathcal{C}(\Sigma)$ is a connected component of $\text{Hom}(\pi, SL(3, \mathbb{R}))/SL(3, \mathbb{R})$. (Choi G 1993)

The deformation space of convex \mathbb{RP}^2 -structures

Hyperbolizing
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- The deformation space $\mathcal{C}(\Sigma) \approx \mathbb{R}^{16g-16}$ upon which $\text{Mod}(\Sigma)$ acts properly. (1988)
- $\mathcal{C}(\Sigma)$ is a connected component of $\text{Hom}(\pi, SL(3, \mathbb{R}))/SL(3, \mathbb{R})$. (Choi G 1993)
- $\mathcal{C}(\Sigma)$ identifies with the holomorphic vector bundle over $\text{Teich}(\Sigma)$ whose fiber over a marked Riemann surface X equals the vector space $H^0(X, (\kappa_X)^3)$ of *holomorphic cubic differentials* (Labourie 1997, Loftin 2001).

Complete affine structures on the 2-torus

Hyperbolizing
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$SL(2, \mathbb{R})$

$SL(2, \mathbb{C})$

$SU(2, 1)$

$SL(3, \mathbb{R})$

$Aff(2, \mathbb{R})$

A *complete affine manifold* is a quotient \mathbb{R}^n/Γ where $\Gamma \subset \text{Aff}(n, \mathbb{R})$ is a discrete group acting properly on \mathbb{R}^n .

Complete affine structures on the 2-torus

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A *complete affine manifold* is a quotient \mathbb{R}^n/Γ where $\Gamma \subset \text{Aff}(n, \mathbb{R})$ is a discrete group acting properly on \mathbb{R}^n .

- Kuiper (1954): Every complete affine closed orientable 2-manifold is homeomorphic to T^2 and equivalent to:

Complete affine structures on the 2-torus

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 - *Euclidean*: \mathbb{R}^2/Λ , where Λ is a lattice of translations

Complete affine structures on the 2-torus

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- Kuiper (1954): Every complete affine closed orientable 2-manifold is homeomorphic to T^2 and equivalent to:
 - *Euclidean*: \mathbb{R}^2/Λ , where Λ is a lattice of translations (all are affinely equivalent);

Complete affine structures on the 2-torus

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A *complete affine manifold* is a quotient \mathbb{R}^n/Γ where $\Gamma \subset \text{Aff}(n, \mathbb{R})$ is a discrete group acting properly on \mathbb{R}^n .

- Kuiper (1954): Every complete affine closed orientable 2-manifold is homeomorphic to T^2 and equivalent to:
 - *Euclidean*: \mathbb{R}^2/Λ , where Λ is a lattice of translations (all are affinely equivalent);
 - Polynomial deformation $\mathbb{R}^2/(f \circ \Lambda \circ f^{-1})$, where

$$(x, y) \xrightarrow{f} (x + y^2, y).$$

Complete affine structures on the 2-torus

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SL(2, \mathbb{R})

SL(2, \mathbb{C})

SU(2, 1)

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Aff(2, \mathbb{R})

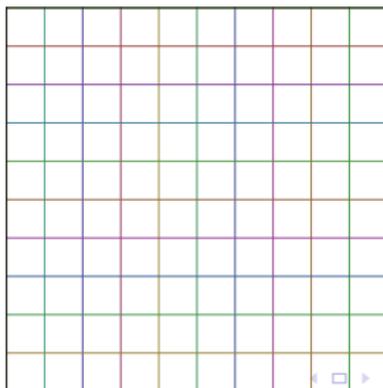
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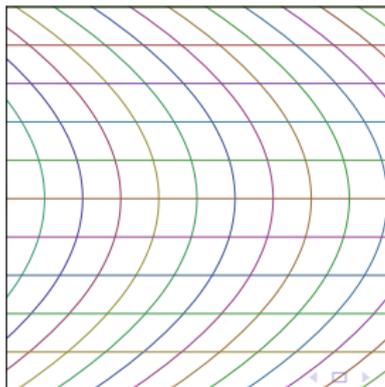
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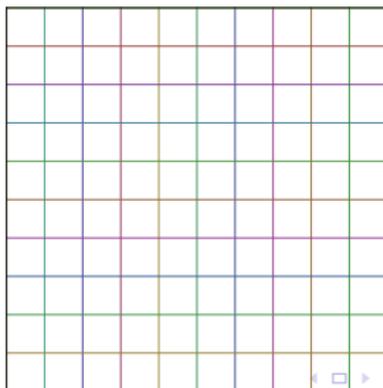
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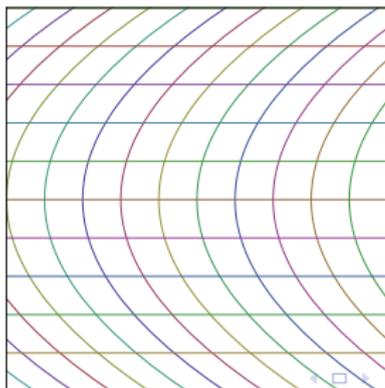
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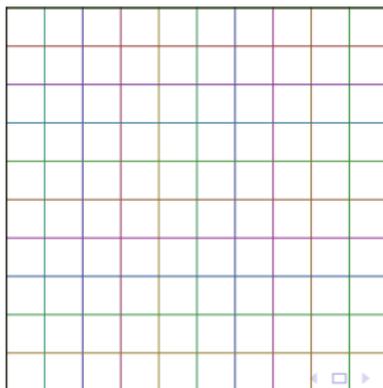
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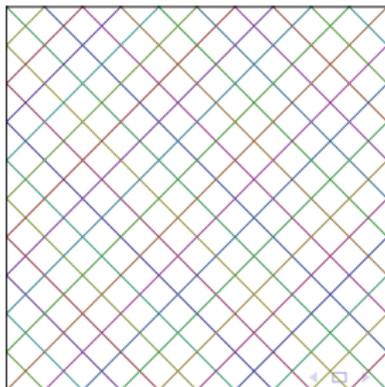
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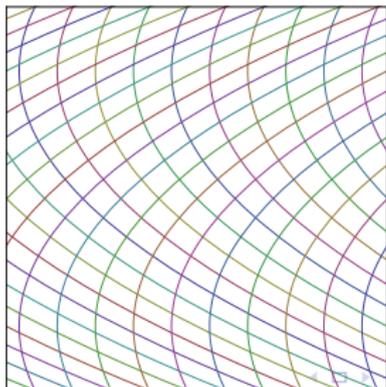
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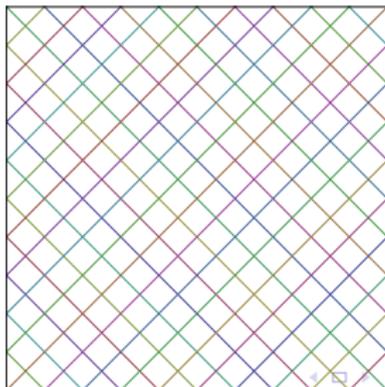
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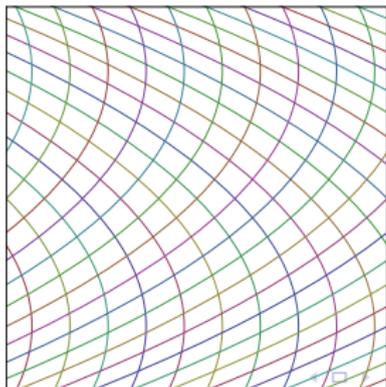
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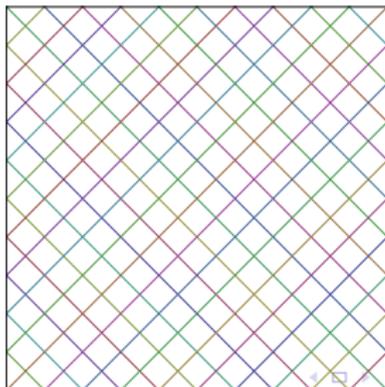
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- (Baues 2000) Deformation space $\approx \mathbb{R}^2$, with $\{(0, 0)\} \longleftrightarrow$ Euclidean structure.

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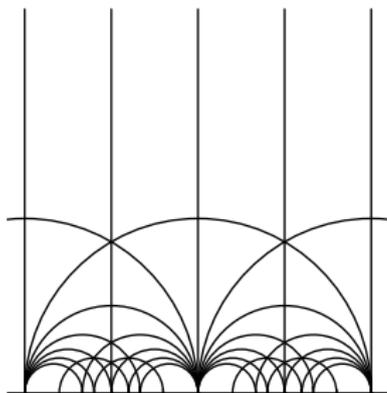
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- Contrast to the *proper* action of $Mod(\Sigma) \cong PGL(2, \mathbb{Z})$ on $\mathfrak{F}(\Sigma)$ by *projective* transformations.



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